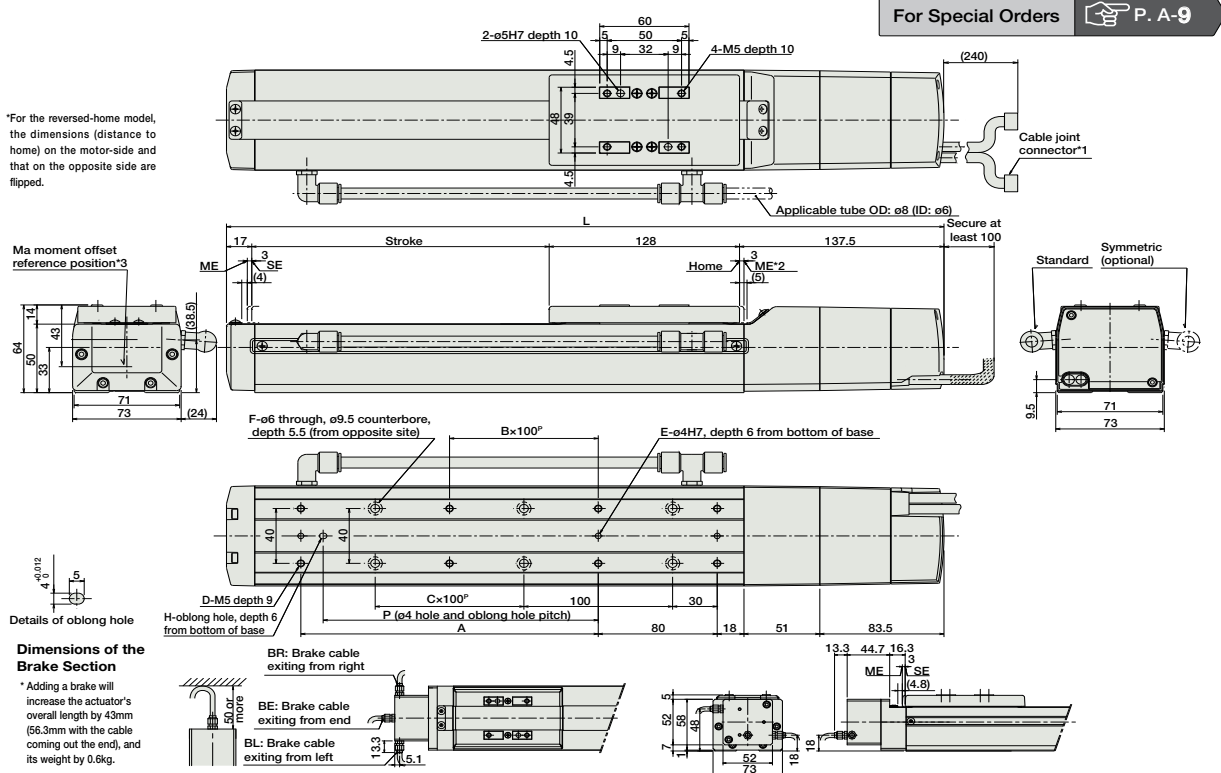


Dimensions



*For the reversed-home model, the dimensions (distance to home) on the motor-side and that on the opposite side are flipped.

Ma moment offset reference position*3

Dimensions of the Brake Section
 * Adding a brake will increase the actuator's overall length by 43mm (56.3mm with the cable coming out the end), and its weight by 0.6kg.

For Special Orders P. A-9

Dimensions and Weight by Stroke

Stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	332.5	382.5	432.5	482.5	532.5	582.5	632.5	682.5	732.5	782.5	832.5	882.5	932.5	982.5	1032.5	1082.5
A	0	100	100	200	200	300	300	400	400	500	500	600	600	700	700	800
B	0	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7
C	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7
D	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20
E	2	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
F	4	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18
H	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
P	0	85	85	185	185	285	285	385	385	485	485	585	585	685	685	785
Weight (kg)	2.6	2.8	3.0	3.2	3.5	3.7	3.9	4.1	4.4	4.6	4.8	5.0	5.3	5.5	5.7	5.9

- The motor-encoder cable is connected here. See page A-39 for details on cables.
- When homing, the slider moves to the ME; therefore, please watch for any interference with the surrounding objects.
 ME: Mechanical end
 SE: Stroke end
 The values enclosed in "()" are reference dimensions.
- Reference position for calculating the moment Ma.

Compatible Controllers

The RCS2CR series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page
Positioner Mode		SCNC-C-60①-NP-2-②	Positioning is possible for up to 512 points	512 points	Single-phase AC100V Single-phase AC200V Three-phase AC200V (XSEL-P/Q only)	360VA max. * When operating a 150W single-axis model	-	→ P547
Solenoid Valve Mode			Operable with the same controls as the solenoid valve	7 points				
Serial Communication Type			Dedicated to serial communication	64 points				
Pulse Train Input Control Type			Dedicated to pulse train input	(-)				
Program Control 1-2 Axes Type		SSEL-C-1-60①-NP-2-②	Programmed operation is possible Operation is possible on up to 2 axes	20000 points			-	→ P577
Program Control 1-6 Axes Type		XSEL-③-1-60①-N1-EEE-2-④	Programmed operation is possible Operation is possible on up to 6 axes	20000 points			-	→ P587

* For SSEL and XSEL, only applicable to the single-axis model.
 * ① is a placeholder for the encoder type (I: incremental / A: absolute).
 * ② is a placeholder for the power supply voltage (1: 100V, or 2: single-phase 200V).
 * ③ is a placeholder for the XSEL type name ("J", "K", "P", or "Q").
 * ④ is a placeholder for the power supply voltage (1: 100V, 2: single-phase 200V, 3: 3-phase 200V).

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm /Flat Type
- Mini
- Standard
- Gripper/ Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash-Proof
- Controllers
- PMEC /AMEC
- PSEP /ASEP
- ROBO NET
- ERC2
- PCON
- ACON
- SCON
- PSEL
- ASEL
- SSEL
- XSEL
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor