

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm/Flat Type
- Mini
- Standard
- Gripper/Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash-Proof
- Controllers
- PMEC/AMEC
- PSEP/ASEP
- ROBO NET
- ERC2
- PCON
- ACON
- SDON
- PSEL
- ASEL
- SSEL
- XSEL
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor

# RCP2-SS7R ROBO Cylinder Slider Type 60mm Width Pulse Motor Side-Mounted Motor Steel Base

■ Configuration: **RCP2** — **SS7R** — **I** — **42P** —   —   —   —   —  

Series — Type — Encoder — Motor — Lead — Stroke — Compatible Controllers — Cable Length — Option

I: Incremental      42P: Pulse motor      12:12mm      50: 50mm      P1:PCON      N: None      See Options below  
 \* The Simple absolute encoder models are labeled as "I".      42 □ size      6: 6mm      600:600mm (50mm pitch increments)      P2:PCON      P: 1m      \* Be sure to specify which side the motor is to be mounted (ML/MR).  
 P3:PMEC      PSEL      M: 5m      X □ □ : Custom Length  
 PSEP      PSEP      R □ □ : Robot cable

\* See page Pre-35 for explanation of each code that makes up the configuration name.

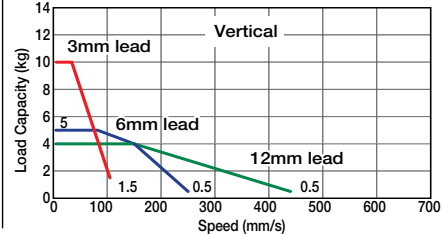
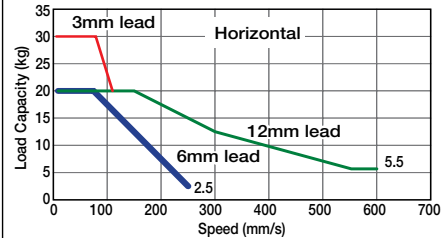


Pictured: Left-mounted motor model (ML).

Technical References A-5

- POINT** Notes on Selection
- When the stroke increases, the maximum speed will drop to prevent the ball screw from reaching the critical rotational speed. Use the actuator specification table below to check the maximum speed at the stroke you desire.
  - Since the RCP2 series use a pulse motor, the load capacity decreases at high speeds. Check in the Speed vs. Load Capacity graph to see if your desired speed and load capacity are supported.
  - The load capacity is based on operation at an acceleration of 0.3G (0.2G for the 3mm-lead model, or when used vertically). These values are the upper limits for the acceleration.

■ Speed vs. Load Capacity  
 Due to the characteristics of the pulse motor, the RCP2 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.



## Actuator Specifications

Lead and Load Capacity				Stroke and Maximum Speed		
Model	Lead (mm)	Max. Load Capacity (Note 1)		Stroke (mm)	Stroke / Lead	
		Horizontal (kg)	Vertical (kg)		50 ~ 500 (50mm increments)	~ 600 (mm)
RCP2-SS7R-I-42P-12-①-②-③-④	12	~ 20	~ 4	50 ~ 600 (50mm increments)	12	600 <440> / 470 <440>
RCP2-SS7R-I-42P-6-①-②-③-④	6	~ 20	~ 5		6	250 / 230
RCP2-SS7R-I-42P-3-①-②-③-④	3	~ 30	~ 10		3	105 / 105

Legend ① Stroke ② Compatible controller ③ Cable length ④ Options

\* The values enclosed in < > apply to vertical setting. (Unit: mm/s)

### ① Stroke List

Stroke (mm)	Standard Price
50/100	-
150/200	-
250/300	-
350/400	-
450/500	-
550/600	-

### ③ Cable List

Type	Cable Symbol	Standard Price
Standard	P (1m)	-
	S (3m)	-
	M (5m)	-
Special Lengths	X06 (6m) ~ X10 (10m)	-
	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	-
	R01 (1m) ~ R03 (3m)	-
Robot Cable	R04 (4m) ~ R05 (5m)	-
	R06 (6m) ~ R10 (10m)	-
	R11 (11m) ~ R15 (15m)	-
	R16 (16m) ~ R20 (20m)	-

\* See page A-39 for cables for maintenance.

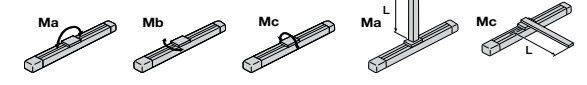
### ④ Option List

Name	Option Code	See Page	Standard Price
Brake	B	→ A-25	-
Reversed-home	NM	→ A-33	-
Left-Mounted Motor (Standard)	ML	→ A-33	-
Right-Mounted Motor	MR	→ A-33	-
Slider Roller	SR	→ A-36	-

### Actuator Specifications

Item	Description
Drive System	Ball screw Ø10mm C10 grade
Positioning Repeatability	±0.02mm
Lost Motion	0.1mm or less
Base	Material: Special alloy steel
Allowable Static Moment	Ma: 79.4 N·m Mb: 79.4 N·m Mc: 172.9 N·m
Allowable Dynamic Moment (*)	Ma: 14.7 N·m Mb: 14.7 N·m Mc: 33.3 N·m
Overhang Load Length	Ma direction: 300mm or less; Mb-Mc direction: 300mm or less
Ambient Operating Temp./Humidity	0~40°C, 85% RH or less (Non-condensing)

(\*) Based on 10,000km travel life. Directions of Allowable Load Moments



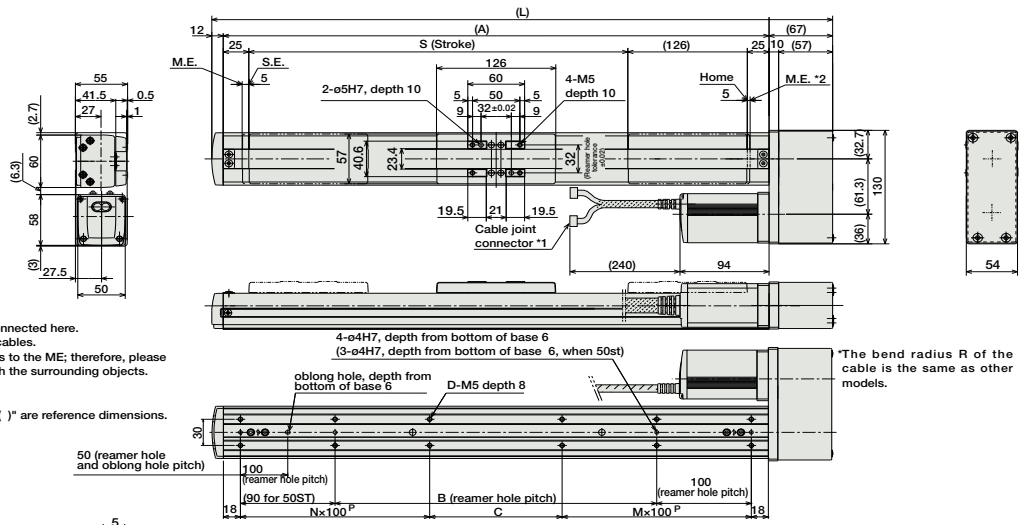
**45** RCP2-SS7R

Dimensions

For Special Orders A-9

\*For the reversed-home model, the dimensions (distance to home) on the motor-side and that on the opposite side are flipped.

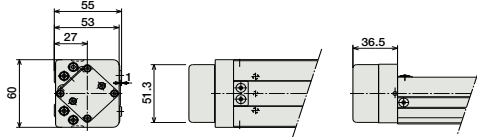
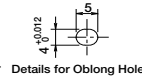
- \* The reference surface is the same as the SS7C type. (See P34)
- \* The offset reference position for the moment Ma is the same as the SS7C type. (See P34)



- \*1: The motor-encoder cable is connected here. See page A-39 for details on cables.
  - \*2: When homing, the slider moves to the ME; therefore, please watch for any interference with the surrounding objects. ME: Mechanical end SE: Stroke end
- The dimensions enclosed in "( )" are reference dimensions.

Dimensions of the brake section

\* Adding a brake increases the actuator's overall length by 24.5mm and its weight by 0.3kg.



■ Dimensions/Weight by Stroke

Stroke	50	100	150	200	250	300	350	400	450	500	550	600
L	305	355	405	455	505	555	605	655	705	755	805	855
A	226	276	326	376	426	476	526	576	626	676	726	776
B	0	40	90	140	190	240	290	340	390	440	490	540
C	90	40	90	140	190	40	90	140	190	40	90	140
D	6	8	8	8	8	12	12	12	12	16	16	16
M	1	1	1	1	1	2	2	2	2	3	3	3
N	0	1	1	1	1	2	2	2	2	3	3	3
Weight (kg)	3.8	4.1	4.4	4.7	5.1	5.4	5.8	6.1	6.4	6.7	7.1	7.4

\* The brake cable is passed through the actuator body and connected to the motor cable.

② Compatible Controllers

The RCP2 series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page
Solenoid Valve Type		PMEC-C-42PI-NP-2-①	Easy-to-use controller, even for beginners	3 points	AC100V AC200V	See P481	-	→ P477
		PSEP-C-42PI-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types. No homing necessary with simple absolute type.					→ P487
Splash-Proof Solenoid Valve Type		PSEP-CW-42PI-NP-2-0						
Positioner Type		PCON-C-42PI-NP-2-0	Positioning is possible for up to 512 points	512 points				
Safety-Compliant Positioner Type		PCON-CG-42PI-NP-2-0						
Pulse Train Input Type (Differential Line Driver)		PCON-PL-42PI-NP-2-0	Pulse train input type with differential line driver support	(-)	DC24V	2A max.		→ P625
Pulse Train Input Type (Open Collector)		PCON-PO-42PI-NP-2-0	Pulse train input type with open collector support					
Serial Communication Type		PCON-SE-42PI-N-0-0	Dedicated to serial communication	64 points				
Field Network Type		RPCON-42P	Dedicated to field network	768 points				→ P503
Program Control Type		PSEL-C-1-42PI-NP-2-0	Programmed operation is possible. Can operate up to 2 axes	1500 points				→ P657

\* This is for the single-axis PSEL.  
 \* ① is a placeholder for the power supply voltage (1: 100V / 2: 100~240V).

Slider Type

Mini

Standard

Controllers Integrated

Controllers Integrated

Rod Type

Mini

Standard

Controllers Integrated

Table/Arm /Flat Type

Mini

Standard

Gripper/ Rotary Type

Linear Servo Type

Cleanroom Type

Splash Proof

Controllers

PMEC /AMEC

PSEP /ASEP

ROBO NET

ERC2

PCON

ACON

SCON

PSEL

ASEL

SSEL

XSEL

Pulse Motor

Servo Motor (24V)

Servo Motor (200V)

Linear Servo Motor