

# RCP2-RTC/RTCL

ROBO Cylinder Rotary Medium Flat Type 88mm Width Pulse Motor

■ Configuration: **RCP2** —  — **I** — **28P** —  —  —  —  —

Series — Type — Encoder — Motor — Deceleration Ratio — Oscillation Angle — Compatible Controllers — Cable Length — Option

RTC: 330-degree rotation  
 RTCL: Multi-rotational

I: Incremental  
 \* The Simple absolute encoder is also considered type "I".

28P: 28 □ size Pulse motor  
 20: 1/20 deceleration ratio  
 30: 1/30 deceleration ratio

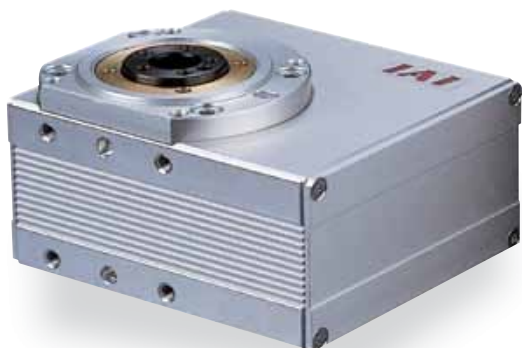
330: 330degrees (RTC only)  
 360: 360degrees (RTCL only)

P1: PCON  
 RPCON  
 PSEL  
 P3: PMEC  
 PSEP

N: None  
 P: 4m  
 S: 3m  
 M: 5m  
 X □ □ : Custom  
 R □ □ : Robot cable

NM: Reversed-rotation  
 SA: Shaft adapter  
 TA: Table adapter

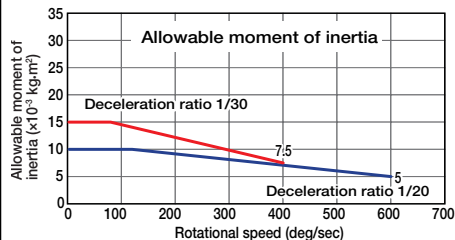
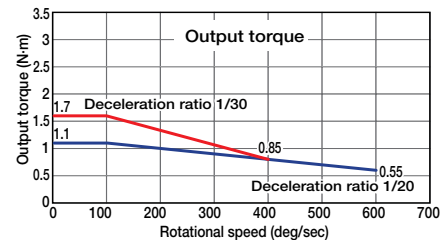
\* See page Pre-35 for an explanation of the naming convention.



Technical References P. A-5

- POINT**  
Notes on Selection
- (1) The output torque decreases as the rotational speed increases. Check the output torque graph on the right to see whether the speed required for your desired motion is supported.
  - (2) The allowable moment of inertia of the rotated work piece varies with the rotational speed. Check the Allowable Moment of Inertia graph on the right to see if the moment of inertia required for your desired motion is within the allowable range.
  - (3) The rated acceleration while moving is 0.3G.

■ Speed vs. Load Capacity  
 Due to the characteristics of the Pulse motor, the RCP2 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.



Actuator Specifications					Deceleration Ratio and Max. Speed	
■ Lead and Load Capacity					Stroke	
Model	Deceleration Ratio	Max. Torque (N·m)	Allowable Moment of Inertia (kg·m <sup>2</sup> )	Oscillation Angle (deg)	Deceleration Ratio	330/360 (deg)
RCP2-RTC-I-28P-20-330-①-②-③	1/20	1.1	0.01	330	1/20	600
RCP2-RTC-I-28P-30-330-①-②-③	1/30	1.7	0.015		1/30	400
RCP2-RTCL-I-28P-20-360-①-②-③	1/20	1.1	0.01	360		
RCP2-RTCL-I-28P-30-360-①-②-③	1/30	1.7	0.015			

Legend: ① Compatible controller ② Cable length ③ Options

(Unit: degrees/s)

Stroke List		
Type	Oscillation Angle (deg)	Standard Price
RTC	330	-
RTCL	360	-

② Cable List		
Type	Cable Symbol	Standard Price
Standard Type	P (1m)	-
	S (3m)	-
	M (5m)	-
Special Lengths	X06 (6m) ~ X10 (10m)	-
	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	-
Robot Cable	R01 (1m) ~ R03 (3m)	-
	R04 (4m) ~ R05 (5m)	-
	R06 (6m) ~ R10 (10m)	-
	R11 (11m) ~ R15 (15m)	-
	R16 (16m) ~ R20 (20m)	-

\* See page A-39 for cables for maintenance.

③ Option List			
Name	Option Code	See Page	Standard Price
Reversed-rotation (*)	NM	→ A-33	-
Shaft adapter	SA	→ A-35	-
Table adapter	TA	→ A-37	-

\* Reversed-rotation option can be selected on the multi-rotational model only.

Actuator Specifications	
Item	Description
Drive System	Hypoid gear
Positioning Repeatability	±0.01 degrees
Homing Accuracy	±0.01 degrees
Lost Motion	±0.1 degrees
Allowable Thrust Load	50N
Allowable Load Moment	3.9 N·m
Weight	0.92kg
Ambient Operating Temp./Humidity	0 ~ 40°C, 85% RH or less (non-condensing)

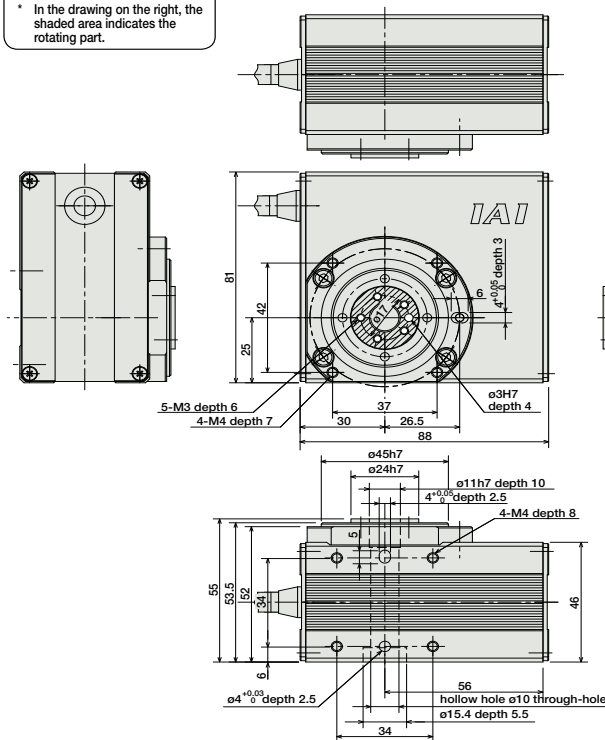
# 359

RCP2-RTC/RTCL

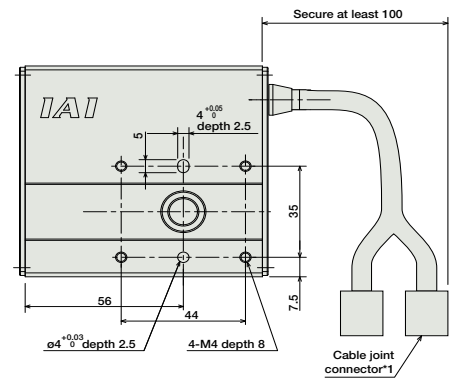
Dimensions

For Special Orders P. A-9

**Note:**  
\* In the drawing on the right, the shaded area indicates the rotating part.



\*1 The motor-encoder cable is connected here. See page A-39 for details on cables.



**Note:**  
The position in the drawing on the left is the home position. When homing, the actuator rotates to the left past the home position by 1 degree. Therefore please watch for any interference with the surrounding objects. The range of motion is 330 degrees clockwise, as viewed from above.

\* The bend radius R of the cable is the same as other models.

Weight (kg) 0.92

① Compatible Controllers

The RCP2 series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page
Solenoid Valve Type		PMEC-C-28PI-NP-2-0①	Easy-to-use controller, even for beginners	3 points	AC100V AC200V	See P481	-	→ P477
		PSEP-C-28PI-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types. No homing necessary with simple absolute type.					
Splash-Proof Solenoid Valve Type		PSEP-CW-28PI-NP-2-0						→ P487
Positioner Type		PCON-C-28PI-NP-2-0	Positioning is possible for up to 512 points	512 points	DC24V	2A max.	-	→ P525
Safety-Compliant Positioner Type		PCON-CG-28PI-NP-2-0						
Pulse Train Input Type (Differential Line Driver)		PCON-PL-28PI-NP-2-0	Pulse train input type with differential line driver support	(-)	DC24V	2A max.	-	→ P525
Pulse Train Input Type (Open Collector)		PCON-PO-28PI-NP-2-0	Pulse train input type with open collector support					
Serial Communication Type		PCON-SE-28PI-N-0-0	Dedicated to serial communication	64 points				
Field Network Type		RPCON-28P	Dedicated to field network	768 points				→ P503
Program Control Type		PSEL-C-1-28PI-NP-2-0	Programmed operation is possible. Operation is possible on up to 2 axes	1500 points				→ P557

\* This is for the single-axis PSEL.  
\* ① is a placeholder for the power supply voltage (1: 100V, 2: 100~240V).

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm /Flat Type
- Mini
- Standard
- Gripper/ Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash-Proof
- Controllers
- PMEC /AMEC
- PSEP /ASEP
- ROBO NET
- ERC2
- PCON
- ACON
- SCON
- PSEL
- ASEL
- SSEL
- XSEL
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor



RCP2-RTC/RTCL **360**