

Nanopositioning Stage

Like its relatives, the SCR100 integrates a slide guide, encoder, and a Linear Shaft Motor. A wide range of options allows for a better match for stage applications needing sub-nanometer resolution that is free from motion errors. Like the SCR050 and SCR075, the encoder and motor cables are built into the stationary base and are designed so there is no need for them to bend and flex.

Each SCR stage requires a servo driver to operate the stage. Any two SCR stages will bolt directly together to form a very stiff, compact X-Y assembly, without the need for adaptor plates. Two SCR stages can be supplied as an X-Y stage to insure true orthogonal orientation between the two axes.



Stage Specifications

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Specifications ¹	Units	SCR100-050	SCR100-100	SCR100-150	SCR100-200	SCR100-250	SCR100-300
Travel/Stroke	mm	50	100	150	200	250	300
Stage Width (B)	mm	140	190	240	290	340	390
Accuracy	μm	3	5	7	9	11	12
Encoder Resolution	nm	1000, 500, 100, 50, 10					
Bi-Directional Repeatability ²		±1 count					
Maximum Acceleration	m/s²	17	12	10	8	7	6
Maximum Velocity ³	m/s	0.9	1	1.2	1.2	1.3	1.3
Load Capacity ⁴	kg	45.5					
Moving Mass	kg	0.8	1.1	1.3	1.6	2.0	2.2
Total Mass	kg	1.6	2.1	2.6	3.2	3.9	4.5
Straightness & Flatness	μm	2/25mm					
Home Limit Switches		Standard					
Home Switch Location		Center					
Limit Switch Over Travel	mm	1					
Hard Stop Over Travel	mm	2					
Bearing		Cross-roller bearing					
Linear Shaft Motor		S080Q					

Note 1: Standard stage specifications are based on the S080Q Linear Shaft Motor

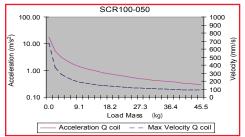
Repeatability +/- 2 counts at sub 0.1µm resolutions Note 2:

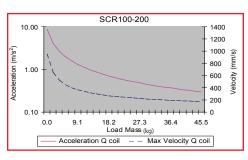
For 10nm (0.01µm) resolution, max velocity of encoder is limited to 135mm/sec; for 50nm (0.05µm), the limit is 675mm/sec; Note 3:

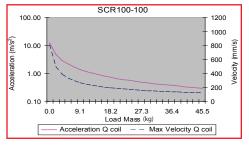
and for 100nm (0.1µm), the limit is 1350mm/sec

Please contact our Applications Engineers for loads exceeding 45.5kg

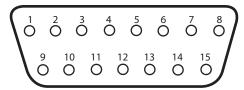
Acceleration/Velocity Curves







10.00 +	SCR100-300	+ 1400				
0.10 0.00 9.1 — Acceleration	Load Mass (kg)	1200 1000 800 600 400 200 0 5.5	Nelocity (mm/s)	ld & S	Service ELI	



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Velocity (mm/s	Pin	Signal	Function
Veloc	2	0V	Ground
	4	Z-	Reference Mark
	5	B-	Incremental Signal
	6	A-	Incremental Signal
1	7	5V	Power
	8	5V	Power
	9	0V	Ground
	10	Q	Limit
	11	Р	Limit
old & Serviced By:	12	Z+	Reference Mark
ELECT	D13N	ATE+	Incremental Signal
	14	A+	Incremental Signal
Toll Free Phone(8 Toll Free Fax(87		17098 ₇₀₉₉ shield	
1011 1 100 1 ax (01			•

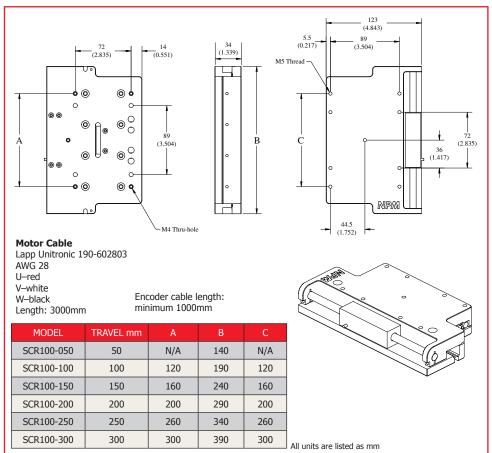
Toll Free Phone

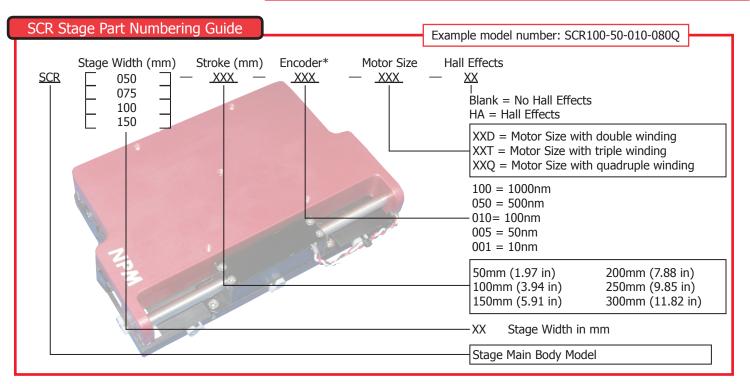
Linear Shaft Motor Specs

Linear Shaft Motor Force Specs	Units	S080Q
Fundamental Motor Constant	N/W	1.39
Motor Force Constant (Kf)	N/A rms	4.2
Back-EMF Constant	V/m/s	1.4
Coil Resistance @ 25°C	Ω	9
Coil Inductance	mH	1.3
Continuous Current @ 135°C	А	0.84
Acceleration Current	А	3.4
Continuous Force @ 135°C	N	3.5
Acceleration Force	N	14
Continuous Power Rating	W	12.7
Thermal Resistance	°C/W	17.3
Magnetic Pole Pitch (N-N)	mm	80

Note: Curves apply only to the stage's standard motor, the S080Q Linear Shaft Motor. If you are interested in using the S080D or S080T in your stage, please contact our application engineers to learn more about these coils.

Dimensions





*SCR Encoder Upgrade Notice

Sold & Serviced By:

As of September 1, 2010, all Nippon Pulse SCR Nanopositioning stages are available with a upgraded encoder. Any stage built respect to the part of the