





CASE STUDY

# **Dental Implant Surgery Robot**

### **APPLICATION**

Dental implant surgery robot provides an unprecedented level of reliability, precision and control. Using haptic guidance and multisensory feedback. This robot helps you achieve the right location, angulation and depth to place the implant perfectly.

### REQUIREMENTS

- Hollow shaft
- High precision
- Low profile
- Resistance to magnetic fields

#### **POSITION SENSOR**

- Netzer DS-25 Absolute Position Electric Encoders<sup>™</sup> incorporated in the robotic arm with frameless motor.
- Compact, low profile, lightweight & wide bore: Allowing high level integration for a low profile arm joint design.
- Frame-less & contactless with a negligible rotor weight: No mechanical parts operating, resulting in a long-lasting operational time, introducing no extra weight & inertia (load) to the system.
- Immune to magnetic interference: Can be very close to the frameless motor magnets.
- High resolution 18 bit & accuracy < 0.015deg for smooth and high accuracy rotation with high repeatability of 1 count.
- Standard digital serial interfaces, SSi , BiSS.





## **PRODUCT FEATURES**







HIGH PRECISION LOW PROFILE HOLLOW SHAFT

SHAFT RESISTANCE TO MAGNETIC FIELDS

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