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DS-130
DATA SHEET

The DS-130 is a member of the DS series of Electric Encoders ${ }^{\text {TM }}$ a product line based on Netzer Precision Position Sensor proprietary technology. EE products are characterized by features that enable unparalleled performance:

- Low profile ( 10 mm )
- Hollow, floating shaft
- No bearings or other contact elements
- High resolution and precision
- High tolerance to temperature extremes, shock, moisture, EMI, RFI and Magnetic fields
- Very low weight
- Holistic signal generation
- Digital interfaces for absolute position

| General |  |
| :--- | :--- |
| Angular resolution | $19-21 \mathrm{bit}$ |
| Maximum tested static error | $\pm 0.010^{\circ}$ |
| Extended accuracy static error | $\pm 0.006^{\circ}$ |
| Maximum operational speed | 750 rpm |
| Measurement range | Unlimited rotation |
| Rotation direction | Adjustable CW/CCW* |
| Power On - Max. operational speed | 3.3 RPM, $<=20^{\circ} / \mathrm{sec}$ |
| Build In Test BIT | Optional |
| * |  |

* Default same direction from bottom side of the encoder

Mechanical

| Allowable mounting eccentricity | $\pm 0.1 \mathrm{~mm}$ |
| :--- | :--- |
| Allowable axial mounting tolerance | $\pm 0.1 \mathrm{~mm}$ |
| Rotor inertia | $25,963 \mathrm{gr} \cdot \mathrm{mm}^{2}$ |
| Total weight | 81 gr |
| Outer $\emptyset /$ Inner $\emptyset /$ Height | $130 / 90 / 10 \mathrm{~mm}$ |
| Material (stator, rotor) | Ultem ${ }^{\text {TM }}$ polymer / TRVX-50 |

The holistic structure of the Electric Encoder ${ }^{\text {TM }}$ makes it unique: Its output reading is the averaged outcome of the entire area of the rotor. This feature allows the EE a tolerant mechanical mounting and to deliver outstanding precision.
Due to the absence of components such as ball bearings, flexible couplers, glass discs, light sources and detectors along with very low power consumption enables the EE to deliver virtually failure-free performance in nearly all types of conditions.
The internally shielded, DC - operated EE includes an electric field generator, a field receiver, sinusoidal-shaped dielectric rotor, and processing electronics.
The EE output is a digital serial synchronous with absolute position single turn.
This combination of high precision, low profile and, low weight has made Netzer Precision encoders highly reliable and particularly well suited to a wide variety of industrial automation and harsh environment applications.

| Electrical |  |
| :--- | :--- |
| Supply voltage | $5 \mathrm{~V} \pm 5 \%$ |
| Interconnection | Shielded cable |
| Cable length | $1,500 \mathrm{~mm} \mathrm{MAX}$ |
|  |  |
| Environmental | IEC $6100-6-2$, IEC 6100-6-4 |
| EMC | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Operating temperature | $-50^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$ |
| Storage temperature | $98 \%$ Non condensing |
| Relative humidity | 100 g for 11 ms |
| Shock endurance | $20 \mathrm{~g} 10-2000 \mathrm{~Hz}$ |
| Vibration endurance | IP 40 |
| Protection |  |



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Digital SSi Interface

Synchronous Serial Interface (SSI) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.


|  | Description | Recommendations |
| :--- | :--- | :--- |
| n | Total number of data bits | $12-22$ |
| T | Clock period |  |
| $\mathrm{f}=1 / \mathrm{T}$ | Clock frequency | $0.5-2.0 \mathrm{MHz}$ |
| Tu | Bit update time | 200 nsec |
| Tp | Pause time | $26-\infty \mu \mathrm{sec}$ |
| Tm | Monoflop time | $>25 \mu \mathrm{sec}$ |
| Tr | Time between 2 adjacent requests | $\mathrm{Tr}>\mathrm{n}^{\star} \mathrm{T}+26 \mu \mathrm{sec}$ |
| $\mathrm{fr}=1 / \mathrm{Tr}$ | Data request frequency |  |



SSi / BiSS output signal parameters

| Output code | Binary |
| :--- | :--- |
| Serial output | Differential RS-422 |
| Clock | Differential RS-422 |
| Clock frequency | $0.5 \div 2.0 \mathrm{MHz}$ |
| Position update rate | 30 kHz |
| Current consumption | 180 mA |

SSi / BiSS interface wires color code

| Clock + | Grey | Clock |
| :--- | :--- | :--- |
| Clock - | Blue |  |
| Data - | Yellow | Data |
| Data + | Green |  |
| GND | Black | Ground |
| +5 V | Red | Power supply |

Software tools: (SSi / BiSS - C)
Advanced calibration and monitoring options are available by using the factory supplied Electric Encoder Explorer software, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring



Digital BiSS-C Interface

BiSS - C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode). The BiSS-C interface as the SSi is based on RS-422 standards.
${ }^{\frac{\text { Master }}{\text { Clock }} \leftrightarrows \text { N }}$ $\frac{\text { Encoder }}{\text { Data }}$

| Bit \# |  | Description | Default | Length |
| :---: | :---: | :---: | :---: | :---: |
| 29 | Ack | Period during which the encoder calculates the absolute position, one clock cycle | 0 | 1/clock |
| 28 | Start | Encoder signal for "start" data transmit | 1 | 1 bit |
| 27 | "0" | "start" bit follower | 0 | 1 bit |
| 8... 26 | AP | Absolute Position encoder data |  |  |
| 7 | Error | Error (BIT optional) | 1 | 1 bit |
| 6 | Warn. | Warning (non active) | 1 | 1 bit |
| 0... 5 | CRC | The CRC polynomial for position, error and warning data is: $x^{6}+x^{1}+x^{0}$. It is transmitted MSB first and inverted. <br> The start bit and "0" bit are omitted from the CRC calculation. |  | 6 bits |
|  | Timeout | Elapse between the sequential "start"request cycle's. |  | $25 \mu \mathrm{~s}$ |

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Netzer Cat No.: CB 00014
Cable: 30 AWG twisted pair (3):
2 (30 AWG 25/44 tinned copper, Insulation: PFE Ø 0.15 to $\emptyset 0.6 \pm 0.05$ OD)
Temperature rating: - 60 to +150 Deg C
Braided shield: Thinned copper braided 95\% min. coverage
Jacket: 0.44 silicon rubber (NFA 11-A1) Ø3.45 $\pm 0.2$ OD

## Sold \& Serviced By:

## er electromate


sales@electromate.com
www.electromate.com

| Resolution |  |  |
| :--- | :--- | :--- |
| Code | Bit | CPR |
| H | 19 | 524,288 |
| I | 20 | $1,048,578$ |
| J | 21 | $2,097,156$ |

BIT (Build In Test): optional
[] None
B BIT

## Cable Information



Related documents
DS-90 User Manual: mechanical, electrical and calibration setup

Optional Accessories
Demonstration Kit
DKIT-DS-130-64-3SH-SO: SSi interface
DKIT-DS-130-64-3IH-S0: BiSS interface
The demo kit includes ,mounted encoder on rotary jig , and RS-422 to USB converter.

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Spring - Shaft - End Installation


Notes

1) For any incompatibility with the model or missing dimension, please refer to Netzer for clarification.
2) Burrs are not allowed
3) Packing must prevent physical damage during process storage and shipment

Sold \& Serviced By:

## (2) ELECTROMATE $\underset{877.737 .8698}{\text { SERVO2GOM.com }}$ <br> sales@electromate.com <br> www.electromate.com

Unless Otherwise Specified
Dimensions are in: mm Surface finish: N6
Linear tolerances
$0.5-4.9: \pm 0.05 \mathrm{~mm}$

| $0.5-420: \pm 0.05 \mathrm{~mm}$ | $5-30: \pm 0.1 \mathrm{~mm}$ |
| :--- | :--- |
| $31-120: \pm 0.15 \mathrm{~mm}$ | $121-400: 0.2 \mathrm{~m}$ |

