



The DS-130 is a member of the DS series of Electric Encoders[™] a product line based on Netzer Precision Position Sensor proprietary technology. EE products are characterized by features that enable unparalleled performance:

- Low profile (10 mm)
- Hollow, floating shaft
- No bearings or other contact elements
- High resolution and precision
- High tolerance to temperature extremes , shock, moisture, EMI, RFI and Magnetic fields
- Very low weight
- Holistic signal generation
- Digital interfaces for absolute position

General

Angular resolution	19-21 bit	
Maximum tested static error	±0.010°	
Extended accuracy static error	±0.006°	
Maximum operational speed	750 rpm	
Measurement range	Unlimited rotation	
Rotation direction	Adjustable CW/CCW*	
Power On - Max. operational speed	3.3 RPM, <=20°/sec	
Build In Test BIT	Optional	
* Default same direction from bottom side of the encoder		

* Default same direction from bottom side of the encode

Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable axial mounting tolerance	±0.1 mm
Rotor inertia	25,963 gr · mm ²
Total weight	81 gr
OuterØ /InnerØ/Height	130 / 90 / 10 mm
Material (stator, rotor)	Ultem™ polymer / TRVX-50

The holistic structure of the Electric Encoder^M makes it unique: Its output reading is the averaged outcome of the entire area of the rotor. This feature allows the EE a tolerant mechanical mounting and to deliver outstanding precision.

Due to the absence of components such as ball bearings, flexible couplers, glass discs, light sources and detectors along with very low power consumption enables the EE to deliver virtually failure-free performance in nearly all types of conditions.

The internally shielded, DC - operated EE includes an electric field generator, a field receiver, sinusoidal-shaped dielectric rotor, and processing electronics.

The EE output is a digital serial synchronous with absolute position single turn.

This combination of high precision, low profile and, low weight has made Netzer Precision encoders highly reliable and particularly well suited to a wide variety of industrial automation and harsh environment applications.

Electrical

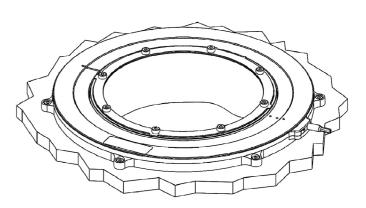
Supply voltage	5V ± 5%
Interconnection	Shielded cable
Cable length	1,500 mm MAX

Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature	-40°C to +85°C
Storage temperature	-50°C to +100°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 40





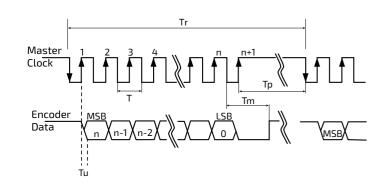




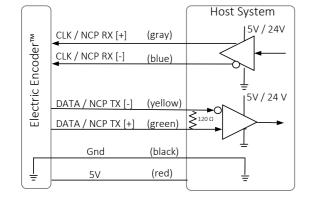


Digital SSi Interface

Synchronous Serial Interface **(SSI)** is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12 - 22
Т	Clock period	
f= 1/T	Clock frequency	0.5 - 2.0 MHz
Tu	Bit update time	200 nsec
Тр	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec
fr=1/Tr	Data request frequency	



SSi / BiSS output signal parameters

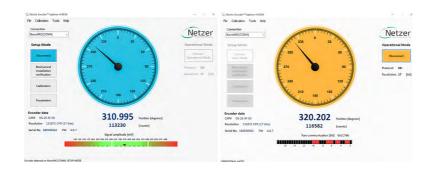
Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock frequency	0.5 ÷ 2.0 MHz
Position update rate	30 kHz
Current consumption	180 mA

SSi / BiSS interface wires color code

Clock +	Grey	Clock	
Clock -	Blue		
Data -	Yellow	Data	
Data +	Green		
GND	Black	Ground	
+5V	Red	Power supply	

Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied <u>Electric Encoder Explorer software</u>, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.





HARSH

ENVIRONMENT

Digital BiSS-C Interface

DATA SHEET

BiSS – **C** Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.

DS-130

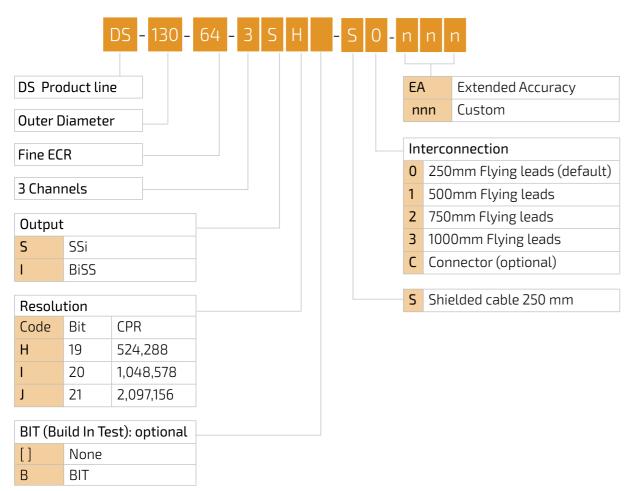


Bit #		Description	Default	Length
29	Ack	Period during which the encoder calculates the absolute position, one clock cycle	0	1/clock
28	Start	Encoder signal for "start" data transmit	1	1 bit
27	"0"	"start" bit follower	0	1 bit
826	AP	Absolute Position encoder data		
7	Error	Error (BIT optional)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$. It is transmitted MSB first and inverted. The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start"request cycle's.		25 µs



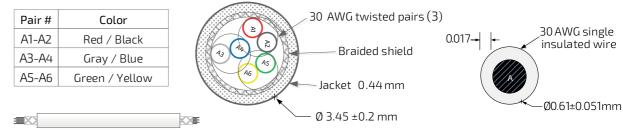


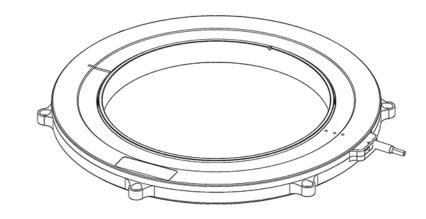
Ordering Code



Cable Information

Netzer Cat No.: CB 00014 Cable: 30 AWG twisted pair (3): 2 (30 AWG 25/44 tinned copper, Insulation: PFE Ø 0.15 to Ø 0.6 ± 0.05 OD) Temperature rating: -60 to +150 Deg C Braided shield: Thinned copper braided 95% min. coverage Jacket: 0.44 silicon rubber (NFA 11-A1) Ø3.45 ±0.2 OD





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Related documents

DS-90 User Manual: mechanical, electrical and calibration setup

Optional Accessories

Demonstration Kit

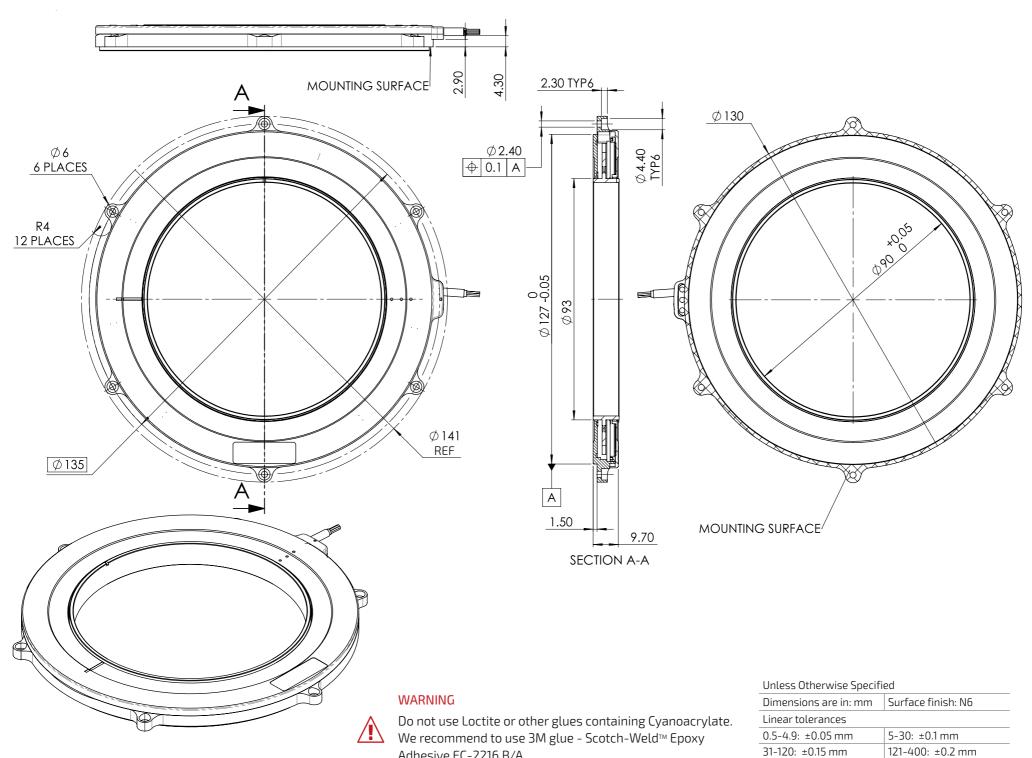
DKIT-DS-130-64-3SH-SO: SSi interface DKIT-DS-130-64-3IH-SO: BiSS interface The demo kit includes ,mounted encoder on rotary jig ,and RS-422 to USB converter.



ABSOLUTE POSITION ROTARY ELECTRIC ENCODER[™]



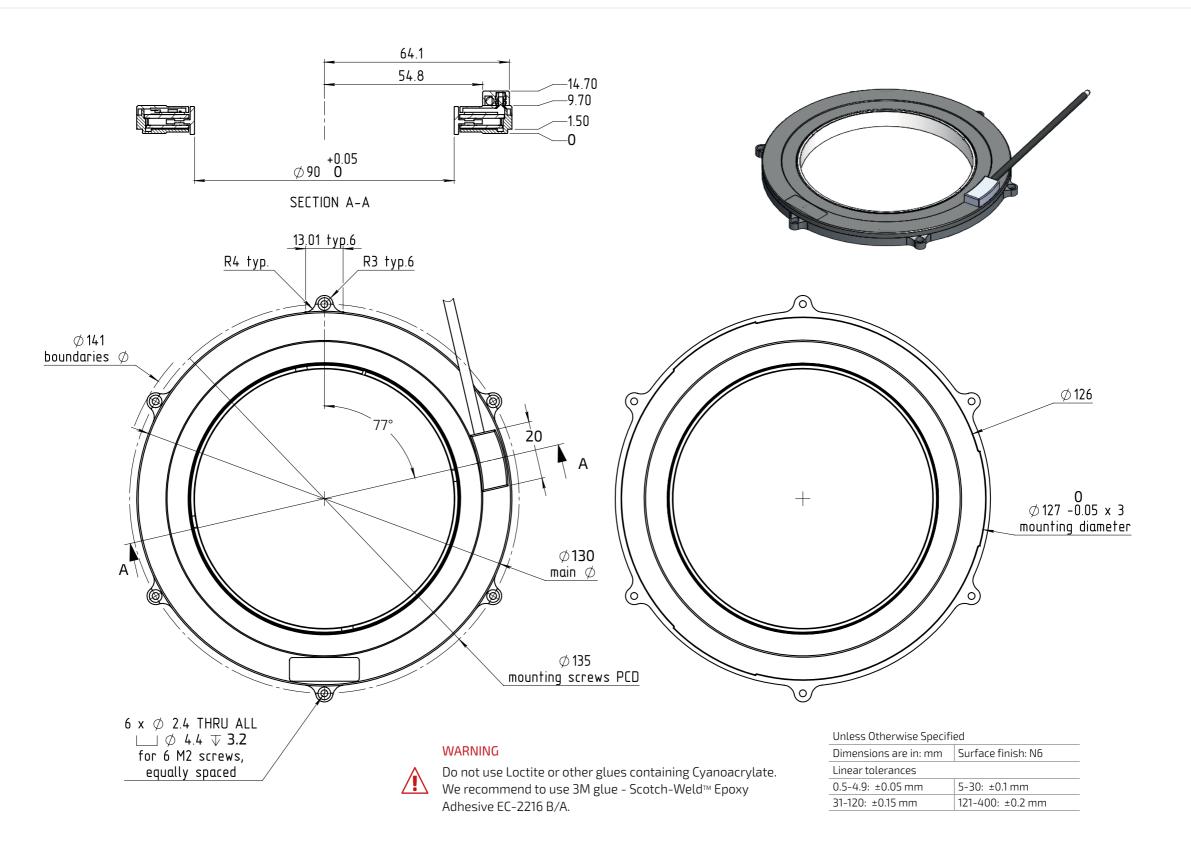
ICD



Adhesive EC-2216 B/A.



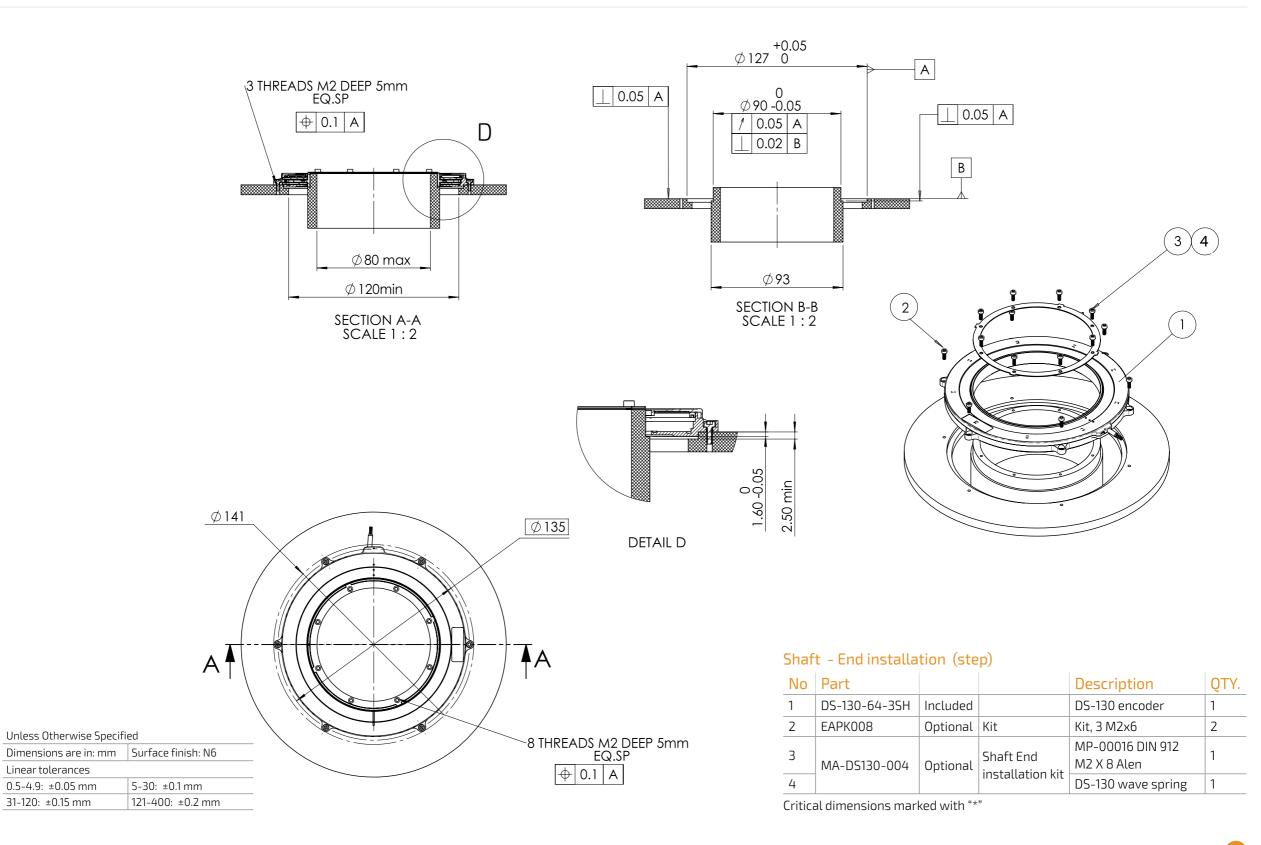












Linear tolerances

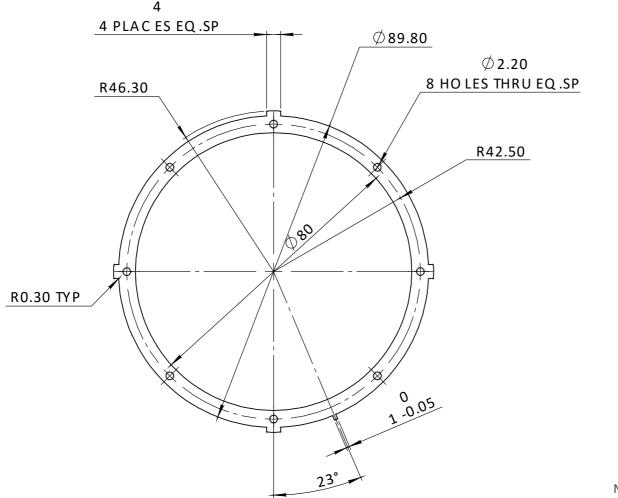
0.5-4.9: ±0.05 mm

31-120: ±0.15 mm





Spring - Shaft - End Installation



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sales@servo2go.com www.servo2go.com

Notes

For any incompatibility with the model or missing dimension, please refer to Netzer for clarification.
Burrs are not allowed
Packing must prevent physical damage during process storage and shipment

0.50

Unless Otherwise Specified

Dimensions are in: mm	Surface finish: N6	
Linear tolerances		
0.5-4.9: ±0.05 mm	5-30: ±0.1 mm	
31-120: ±0.15 mm	121-400: ±0.2 mm	