Temposonics®

Magnetostrictive, Absolute, Non-contact Linear-Position Sensors



Document Part Number 551081 Revision B

R-Series Model RF

Flexible Housing Option

Data Sheet



Model RF flexible housing option for R-Series sensors with voltage, current, SSI, CANbus, DeviceNet, Profibus, EtherCAT® and EtherNet/IP outputs

FEATURES

- Linear, Absolute Measurement Along an Arc
- LEDs For Sensor Diagnostics
- Non-Contact Sensing Technology
- Linearity Deviation Less Than 0.02%
- Repeatability Within 0.001%
- Flexible Housing is Optional For MTS R-Series Sensors With The Following Full Range of Outputs: Voltage, Current, SSI, CANbus, DeviceNet, Profibus, EtherCAT® and EtherNet/IP
- Measuring Stroke Range:
 255 mm (10 in.) to 10,060 mm (396 in.)
 (Contact factory for longer stroke lengths)

BENEFITS

- Rugged Industrial Sensor
- Multi-Magnet Position Measurement: Up to 20 Positions
- 100% Field Adjustable Null And Span Setpoints
- Cost Effective, Convenient Shipping for Long Measuring Lengths

APPLICATIONS

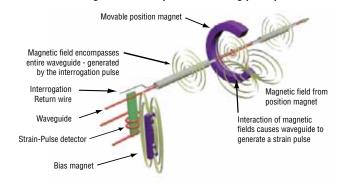
- Hydraulic Cylinder Applications with Limited Sensor Installation Space
- Accurate Position Measurement Along an Arc
- **Very Long Measurement Lengths**

TYPICAL INDUSTRIES

- **■** Fluid Power
- Steel Mills Using Long Cylinders
- Material Handling and Packaging
- Woodworking, Metalworking and Assembly Tools
- Converting Machines

Sold & Serviced By: ELECTROMATE

Time-based Magnetostrictive position sensing principle



Benefits of Magnetostriction

Temposonics linear-position sensors use the time-based magnetostrictive position sensing principle developed by MTS. Within the sensing element, a sonic-strain pulse is induced in a specially designed magnetostrictive waveguide by the momentary interaction of two magnetic fields. One field comes from a moveable permanent magnet that passes along the outside of the sensor. The other field comes from an "interrogation" current pulse applied along the waveguide. The resulting strain pulse travels at sonic speed along the waveguide and is detected at the head of the sensing element.

The position of the magnet is determined with high precision and speed by accurately measuring the elapsed time between the application of the interrogation pulse and the arrival of the resulting strain pulse with a high-speed counter. The elapsed time measurement is directly proportional to the position of the permanent magnet and is an absolute value. Therefore, the sensor's output signal corresponds to absolute position, instead of incremental, and never requires recalibration or rehoming after a power loss. Absolute, non-contact sensing eliminates wear, and guarantees the best durability and output repeatability.

Product Overview and Specifications

Product overview

MTS offers the Model RF Flexible housing as an option with our R-Series family of extremely robust, highly accurate, linear-position sensors.

Constructing a R-Series sensor with the RF flexible housing results in a flexible style sensor that offers trouble-free performance in applications that require very long stroke lengths and linear measurements on an arc.

The Model RF flexible sensors are available in all R-Series sensor outputs including analog, serial, digital, and bus interfaces. Standard stroke lengths for the sensor are up to 10 meters (396 in.) and for special applications, longer lengths are available by consulting the factory.

Flexible sensors incorporate the Temposonics SE (Sensing Element) technology that is the same building block all MTS sensor models use. The SE is housed in a fluoroelastomer coated stainless steel housing that is flexible and can be bent in an arc to an 8 inch minimum bend radius.

Most operating parameters are identical to their rigid cousins. Model RF sensors are recommended for long-length applications because they are simply coiled inside a 40-inch diameter box for shipping, which simplifies logistics and handling.

The model RF sensor can easily bend around corners or obstacles and provides a simple solution for applications where installation space is too confined, or has limited access, making installation or replacement too difficult and costly for a standard rigid type sensor.

Output options

The Model RF Flexible Housing option is available for R-Series Sensors with voltage, current, SSI, CANbus, DeviceNet, Profibus, EtherCAT and EtherNet/IP outputs.

Important specification notes:

- For R-Series model specific specifications, consult the individual R-Series data sheets applicable to the sensor output(s) being used.
- All sensors constructed with the flexible housing have their specifications measured while laying flat.

roduct specific	ations
Parameters	Specifications
ОИТРИТ	
Measured output variables:	Position, velocity, simultaneous multi- position and velocity measurements. (Measured output variables depend on the complete sensor model used.)
Resolution:	Output dependent
Update times:	Output dependent
Linearity deviation:	$<\pm~0.02\%$ full stroke (minimum $\pm~100~\mu m)$ Linearity Correction Option (LCO) available for some R-Series models
Repeatability:	$<\pm$ 0.001% full stroke (minimum \pm 2.5 μ m)
Hysteresis:	< 4 μm, 2 μm typical
Outputs:	Voltage, current, SSI, CANbus, DeviceNet, Profibus, EtherCAT and EtherNet/IP
Measuring range:	255 to 10,060 mm (10 to 396 in.) (Contact factory for longer stroke lengths)
ELECTRONICS	
Operating voltage:	+24 Vdc nominal: -15% or +20% Polarity protection: up to -30 Vdc Over voltage protection: up to 36 Vdc Current drain: Output dependent Dielectric withstand voltage: 500 Vdc (DC ground to machine ground)
ENVIRONMENTAL	
Operating conditions:	Operating temperature: -40 °C (-40 °F) to +75 °C (+167 °F) Relative humidity: 90% no condensation
EMC test:	Emissions: IEC/EN 50081-1 Immunity: IEC/EN 50082-2 IEC/EN 61000-4-2/3/4/6, level 3/4 criterium A, CE qualified

Shock rating: 100 g (single hit)/

IEC standard 68-2-27 (survivability)

5 g/10 to 2000 Hz, IEC standard 68-2-6 Vibration rating:

(operational)

WIRING

Sensor stroke:

Connection type: Connector or integral cable (output

dependent)

ROD STYLE SENSOR (MODEL RF)

Aluminum die cast housing with diagnostic **Electronic head:**

LED display

(LEDs located beside connector/cable exit) Flexible stainless-steel pipe (PTFE plastic

coated), minimum bend radius 200 mm (8 in.)

Sealing: IP 30 (IP 67 or IP 68 rating when installed

inside the optional 1/2 inch O.D. pressure

housing pipe)

Any orientation. Threaded flange M18 x 1.5 Mounting:

or 3/4 - 16 UNF-3A

Ring magnet or open-ring magnet or block Magnet types:

magnet



Model RF flexible housing option dimension references

R-SERIES SENSOR WITH MODEL RF FLEXIBLE HOUSING OPTION

Drawing is for reference only, contact applications engineering for tolerance specific information.

Notes:

- 1. Total sensor length tolerances are:
 - +8 mm (0.3 in.)/-5mm (0.2 in.) up to 7600 mm (300 in.) stroke length.
 - +15 mm ((0.6 in.)/-5 mm (0.2 in.) over 7600 mm (300 in.) stroke length.
- 2. Tolerances of total length do not influence the measuring stroke length.

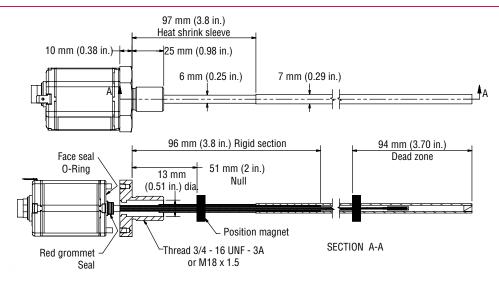


Figure 1. R-Series Model RF flexible housing dimension reference

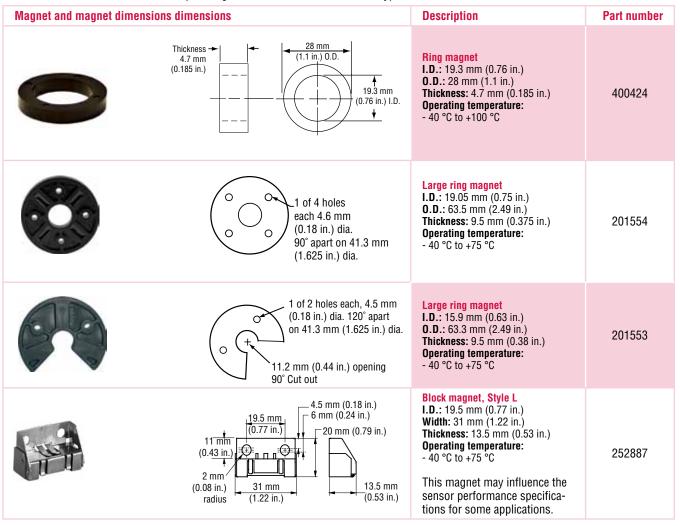
Standard magnet selections (Model RF)

POSITION MAGNET SELECTIONS (Drawing dimensions are for reference only)

Magnet and magnet dimensions		Description	Part number		
0	4 Holes Each 4.3 mm (0.17 in.) dia. 90° apart on 24 mm (0.94 in.) dia.	Standard ring magnet I.D.: 13.5 mm (0.53 in.) O.D.: 33 mm (1.3 in.) Thickness: 8 mm (0.3 in.) Operating temperature: - 40 °C to 100 °C	201542-2		
0		Ring magnet I.D.: 13.5 mm (0.53 in.) O.D.: 25.4 mm (1 in.) Thickness: 8 mm (0.3 in.) Operating temperature: - 40 °C to 100 °C	400533		
	2 Holes Each 4.3 mm (0.17 in.) dia. on 24 mm (0.94 in.) dia. 14 mm (0.55 in.) (0.97 in.)	Open-ring magnet, Style M I.D.: 13.5 mm (0.53 in.) O.D.: 33 mm (1.3 in.) Thickness: 8 mm (0.3 in.) Operating temperature: - 40 °C to 100 °C This magnet may influence the sensor performance specifications for some applications.	251416-2		

Model RF Flexible Housing Option for R-Series Sensors Dimension and Magnet Selection References

POSITION MAGNET SELECTIONS (Drawing dimensions are for reference only)



Sensor mounting and Installation references

R-SERIES MODEL RF SENSOR MOUNTING AND INSTALLATION Flexible installation in any position!

The model RF flexible sensor housing can be mounted to provide straight or curvilinear measurements. The sensor's flexible housing requires supports or anchoring to maintain proper alignment between the sensor rod and the magnet. Without proper alignment, the sensor's output signal can be interrupted or lost.

A hex flange comes mounted on the sensor head having either U.S. customary threads (3/4 - 16 UNF inches) or metric threads (M18 x 1.5). The flange is secured to the sensor head by 2 metric screws (M4 x 59 mm, 2.5 mm hex socket head). The flange can be used, or removed, to best accommodate the installation requirements. If the sensor is mounted without the flange, the red grommet seal can be cut off to provide a flush mounting surface for the sensor's face seal O-Ring (shown in 'Figure 1' on page 3 and 'Figure 2' below).

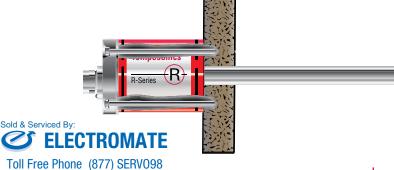


Figure 2. Installation example for flush mounting with red grommet seal removed.

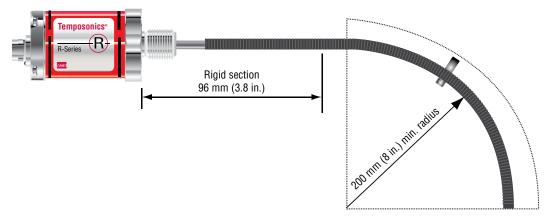


Figure 3. Installation example showing minimum bend radius for curvilinear measurements.

Most applications require that the RF flexible sensor housing be supported, such as, placed inside a guide pipe made of non-ferrous material, straight or bent to the desired shape.

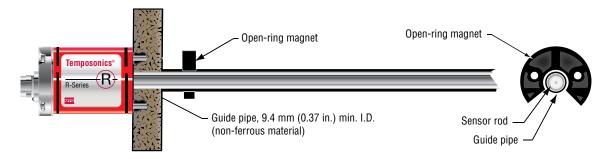


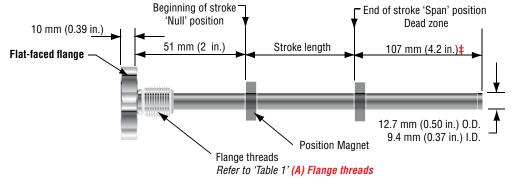
Figure 4. Installation example using non-ferrous guide pipe (customer supplied).

When installed inside the MTS half-inch O.D. pressure housing pipe, the RF flexible sensor housing is suitable for use in hydraulic cylinders, and can simplify installation where installation or mounting space is limited (see 'Figure 7').

Half inch O.D. pressure pipe and flange (Optional)

PIPE AND FLANGE SELECTIONS

The half inch O.D. pressure pipe with flange is designed specifically for R-Series sensors with the model RF flexible housing option. The pressure pipe and flange provide protection from high pressures, as found in hydraulic cylinders, up to 5,000 psi static, 10,000 psi spike. For large cylinders, using the half-inch O.D. pressure pipe requires a larger gun-drilled bore in the piston head/rod assembly. Typically, a 0.75 inch bore is used to match the I.D. of the ring magnet used (e.g. part no.: 201554 or part no.: 400424).



(4.2 in. dead zone = 3.7 in. dead zone of RF sensor +0.5 in. gap)

Figure 5. Style 'HL' pressure pipe (flat-faced flange shown with U.S. customary threads)



R-Series Model RF Flexible Housing Option Pressure Pipe and Flange Selections

HALF INCH O.D. PRESSURE HOUSING PIPE AND FLANGE SELECTIONS (CONTINUED)

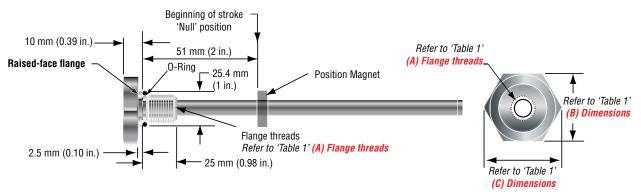


Figure 6. Style 'HP' pressure pipe (raised-face flange shown with U.S. customary threads)

FLANGE TYPE	DESCRIPTION	(A) FLANGE THREADS	(B) DIMENSIONS	(C) DIMENSIONS
HP	US customary threads with raised-face flange	3/4" - 16 UNF-3A	1.75 in.	2 in.
HL	US customary threads with flat-faced flange	3/4" - 16 UNF-3A	1.75 in.	2 in.
HD	Metric threads with flat-faced flange	M18 x 1.5	46 mm	53 mm

Table 1. Flange options and specifications

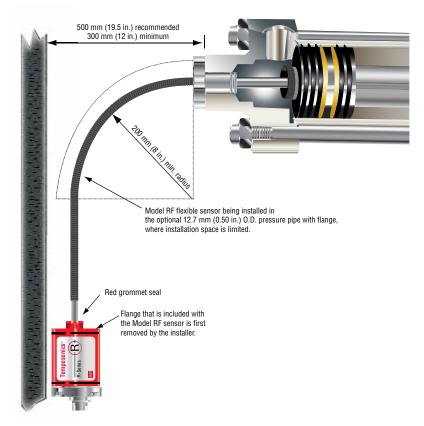


Figure 7. Installation example using optional 12.7 mm (0.50 in.) O.D. pressure pipe inside hydraulic cylinder



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				1	2	3	4	5	6	7
	HALF INCH O.D. PRESSURE PIPE AND FLA	INGE STYLE					=	Н		1-2
HL	= US customary threads, flat-faced flange and 1/2 inch pressure pipe	 US customary threads, raised-faced flange and 1/2 inch pressure pipe, 	= Metric thre and 1/2 inc				•			
	STROKE LENGTH			=						3-7
	M = Millimeters (Encode in 5 mm increments)									
		Stroke Length Notes:								
	U = Inches and tenths (Encode in 0.1 in. increments)	 Half inch O.D. pressure pipe and flang 5840 mm (230 in.) Contact factory for longer lengths. 	je stroke range = 2	255 mm	(10 in.)	to				
	HD1000M = 1/2 inch O.D. pressonering Information	re pipe with flat-faced flange, US customary ire pipe with flat-faced flange, metric threac	y threads, for a 12 ds, for a 1000 mm	2.0 inch s n stroke	stroke le length	ength				
R-Se	eries Model RF Flexible Housing Optic	on								
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	R-SERIES HOUSING MODEL						_ [R	F	1-2
RF	= Flexible style						L		_	
	Magnet must be ordered separately.									
	FLANGE TYPE						_ [\neg		3
S	 US customary threads, flat-faced M flange 	= Metric threads, flat-faced flange		_			_ [
	STROKE LENGTH —			=						4-9
	M = Millimeters (Encode in 5 mm increments)	Studio Langth Notae								
	U = Inches and tenths	Stroke Length Notes: 1. Flexible housing style sensor (model F	PE) etroka ranga —	. 255 mr	n /10 in	\ -	_			
	(Encode in 0.1 in. increments)	10,060 mm (396 in.) 2. Contact factory for longer lengths.	ii) stioke lalige =	200 1111	11 (10 111	., -				
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Ordering Examples:

RFS03937UD701S1B1100 = 393.7 in. stroke length for RF sensor with SSI output

RFM10000MD631P102 = 10,000 mm stroke length for RF sensor with Profibus output



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