

Magnetostrictive, Absolute, Non-contact Linear-Position Sensors

E-Series Model EE Embedded Sensor Analog Output

Data Sheet



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#### **FEATURES**

- Linear, Absolute Measurement
- Non-Contact Sensing Technology
- Linearity Less Than 0.02% F.S.
- Repeatability Less Than 0.002% F.S.
- Direct Analog Output:
  - 4 to 20 mA or 20 to 4 mA
  - Min/max. load 0/500 Ohms
- Stroke Length Range: 50 mm to 2500 mm (or 2 in. to 100 in.)

#### **BENEFITS**

- Compact Design for Embedded Cylinder Applications
- Continuous Absolute Position Measurement
- Over Voltage Protection to 36 Vdc and Polarity Protection up to -30 Vdc
- Increased Operating Temperature

### **APPLICATIONS**

- Space Limited Cylinder Applications
- Embedded Continuous Position Measurement

#### **TYPICAL INDUSTRIES**

- Industrial Applications
- Fluid Power



Time-based Magnetostrictive position sensing principle

#### **Benefits of Magnetostriction**

Temposonics linear-position sensors use the time-based magnetostrictive position sensing principle developed by MTS. Within the sensing element, a sonic-strain pulse is induced in a specially designed magnetostrictive waveguide by the momentary interaction of two magnetic fields. One field comes from a movable permanent magnet that passes along the outside of the sensor. The other field comes from an "interrogation" current pulse applied along the waveguide. The resulting strain pulse travels at sonic speed along the waveguide and is detected at the head of the sensing element.

The position of the magnet is determined with high precision and speed by accurately measuring the elapsed time between the application of the interrogation pulse and the arrival of the resulting strain pulse with a high-speed counter. The elapsed time measurement is directly proportional to the position of the permanent magnet and is an absolute value. Therefore, the sensor's output signal corresponds to absolute position, instead of incremental, and never requires recalibration or re-homing after a power loss. Absolute, non-contact sensing eliminates wear, and guarantees the best durability and output repeatability.



## E-Series Model EE Embedded Sensor, Analog Output Product Overview and Specifications

## **Product overview**

The Temposonics<sup>®</sup> E-Series embedded (EE) position sensor is designed to be embedded into a hydraulic cylinder. The compact sensor design makes the embeddable E-Series the perfect solution for small cylinders with limited space for the integration of a measuring system. The increased temperature range allows an operation of the sensor in high temperature industrial applications. MTS Sensors continues to establish new performance standards for low-cost, fully-industrial, durable position sensors using the widely preferred magnetostrictive technology. This principle for accurate and non-contact measurement of linear-position sensing was developed 30 years ago by MTS and is used with outstanding success in a large variety of industrial applications.

conditions.

Ring magnet

# **Product specifications**

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Parameters Specifications		Parameters	Specifications					
OUTPUT		ENVIRONMENTAL						
Measured output variable:	Position	Operating conditions:	<b>Operating temperature:</b> -40 °C (-40 °F) to +85 °C ( 185 °F)					
Resolution:	<b>Analog:</b> Infinite (restricted by output ripple)		Relative humidity: 90% no condensation					
Linearity deviation:	< ± 0.02% full stroke (minimum ± 60 µm)		IP67 (With professionally mounted housing and connectors.)					
Repeatability:	$< \pm 0.002\%$ full stroke		IP30 (Sensor with flat connector)					
	(minimum ± 20 μm)	EMC test:	Electromagnetic emission:					
Output:	<b>Direct Analog / Current:</b> 4 to 20 mA or 20 to 4 mA (Controller input resisdtance: $RL \le 500$		EN 55011, cl. B:2009 + A1:2010 Electromagnetic immunity: EN 61326-1:2006					
	Òhms)	Shock rating:	100 g (single shock) IEC-Standard 60068-2-27 15 g / 10 to 2000 Hz IEC-Standard					
Stroke length:	<b>Range:</b> 50 mm to 2500 mm (or 2 to 100 in.)	Vibration rating:						
Update Time:	$\leq$ 3 kHz( Stroke length dependent)		60068-2-6 (resonance frequencies excluded)					
ELECTRONICS		WIRING	,					
Operating		Connection types:	6-Pin Moley connector					
voltage:	+24 Vdc nominal: -15% or +20%							
	<b>Over voltage protection:</b> up to 36 Vdc	ROD-STYLE SENSOF	R (MODEL EE)					
	Current drain: 50 to 140 mA	Electronic head:	Stainless Steel 1.4301 / AISI 304					
		Sensor rod:	Stainless Steel 1.4301 / AISI 304 <b>10 mm rod:</b> 350 bar static, 530 bar peak (5000 psi static, 7700 psi peak)					
		Mounting:	Any orientation. According to installation					

Magnet types:



## **Outputs**

### **ANALOG (CURRENT) OUTPUT**

The direct analog output range is 4 to 20 mA or 20 to 4 mA. Since the outputs are direct, no signal conditioning electronics are needed when interfacing with controllers or meters.

### Analog output ranges:

- 4 to 20 mA
- 20 to 4 mA





## **Sensor dimension references**

Drawings are for reference only, contact applications engineering for tolerance specific information.

### **MODEL EE**







## E-Series Model EE Embedded Sensor, Analog Output Magnet Options, Connections and Wiring

# Standard magnet options (Model EE)

Magnets must be ordered separately with Model EE position sensors. The standard ring magnet (part number 201542-2) is suitable for most applications.

**POSITION MAGNET SELECTIONS (Magnet must be ordered separately)** (Drawing dimensions are for reference only)

Magnet and magnet dimensions	Description	Part number		
4 Holes       Each 4.3 mm (0.17 in.) dia.       90° apart on       24 mm (0.94 in.) dia.	Standard ring magnet           I.D.: 13.5 mm (0.53 in.)           O.D.: 33 mm (1.3 in.)           Thickness: 8 mm (0.3 in.)           Operating temperature:           - 40 °C to +100 °C	201542-2		
Image: state of the state o	Magnet spacer           (Non-ferrous, use with ring magnet           Part number: 201542-2)           I.D.: 14 mm (0.56 in.)           O.D.: 32 mm (1.25 in.)           Thickness: 3.2 mm (0.125 in.)	400633		
	Ring magnet           I.D.: 13.5 mm (0.53 in.)           O.D.: 17.4 mm (0.68 in.)           Thickness: 8 mm (0.3 in.)           Operating temperature:           - 40 °C to 100 °C	400533		

# **Connections and wiring (Model EE)**

### MOLEX MATING CONNECTOR CABLE (M12) 5-PIN AND 6-PIN PINOUT/WIRING INFORMATION

The E-Series Model EE Sensor Component connects directly to a controller or interface module with the standard male, 5-pin or 6-pin connector and an extension cable as described in 'Table 1'

### Analog (M12) 5-pin connector (male) as viewed from the face of the sensor plug

5-Pin connector	Molex Pin no.:	(M12) Pin no.:	Signal/function Analog outputs
	6	1	+24 Vdc
	3	2	Output signal
3 4	4	3	DC ground (for power return)
	1	4	n.c.
	5	5	Ground for signal return
	2	-	n.c.

 Table 1.
 M12 connector cable part no.: 254256



## E-Series Model EE Embedded Sensor, Analog Output Cable and Connector Options

**CABLE CONNECTOR OPTIONS FOR 5-PIN (M12) CONNECTOR TYPES** (Photo and drawing dimensions are for reference only)

Connector and dimensions	Description	Part number		
20 mm (0.79 in) dia.	Female cable connector, straight exit (Field installable) 5-Pin (M12) Mates with 5-pin (M12) connector cable part no.: 254256 Sensor component output: Analog Termination: Screw terminals Cable gland: for 4-8 mm dia. cable Ingress protection: IP 67	370677		
64 mm (2.52 in.) 31.1 mm (1.22 in.) (0.75 in.) dia. 20 mm (0.79 in.) dia.	Female cable connector, 90° exit (Field installable) 5-Pin (M12) Mates with 5-pin (M12) connector cable part no.: 254256 Sensor component output: Analog Termination: Screw terminals Cable gland: for 6 mm dia. cable Ingress protection: IP 67	370678		

### **MATING CABLE CONNECTOR SELECTIONS**

(Drawing dimensions are for reference only)

Connector and dimensions	Description	Part number				
Pin 1 12 mm (0.47 in.) dia.	Mating cable connector 5-Pin (M12)	254256				
Pin 1 (2.36 in.)	Pigtail mating connector	254266				

### MATING CABLE CONNECTOR SELECTION

(Drawing dimensions are for reference only)

Connector and dimensions	Description	Part number				
Pin 1	Extension cable, Molex to Molex	254243				



## E-Series Model EE Embedded Sensor, Analog Output Ordering Information

Use con	the orde figure yo	r matrix below to ur Model EE sensor	EE	S					[	M	0	0		1				
oru		1.	1 2	3	4	5 6	1	8		y	10	11		12		13	14	15
EE	<b>SENS</b> = E-Ser	OR MODEL	nsor (Magnet must	be ordered	separate	ly)								_ =	E	E		1 - 2
	ROD	HOUSING AND FLANGE T	(YPE												- =	S		3
3	= Press	URE TIT NOUSING, 10 MM OI	J rod															1 - 8
	3110	M - Millimeters (Enco	de in 5, 10, 25 or 5	0 mm increi	mante) ac	e indicator	d in 'St	roko l	anath	note		0.11						4 0
		Inches (Encode in		inoromonto	) oo indio	s mulcale	troko k	north	notoo	'hole	5 001	0.						
			10.2, 0.3, 1 01 2 111.	Increments	) as muic	aleu III S	li oke le	engun	notes	Delt	JVV.		1					
		Stroke length No	otes:															
		<b>Stroke length ran</b> <b>M</b> = 50 mm to 250 <b>U</b> = 2 in. to 100 ir	<b>ges:</b> DO mm n.															
		The increment s	ize between standa	ard stroke le	engths va	ary as sho	wn bel	low:										
		Stroke length (mm)			Orderi	ng increme	ent											
		≤ 500 mm			5 mm	า												
		$>$ 500 mm and $\leq$	750 mm		10 m	m												
		$>750$ mm and $\leq$	1000 mm		25 m	m												
		> 1000 mm and :	≤ 2500 mm		50 m	m												
		Stroke length (in.)			Orderi	ng increme	ent											
		≤ 20 in.			0.2 in	1.												
		$>$ 20 in. and $\leq$ 30	in.		0.5 in	1.												
		> 30 in. and $\leq$ 40 in. 1 in.																
		$>$ 40 in. and $\leq$ 10	0 in.		2 in.													
	SENS	OR CONNECTION TYPE											=	M	0	0	(	9 - 11
M00	= 6-Pin	Molex, male																
	INPU	T VOLTAGE													=	1		12
1	= + 24	Vdc (+20%, -15%), stand	ard															
	OUTP	TU											=				1:	3 - 15
	CURR	ENT																
A01	= 4 to 2	20 mA																
A11	= 20 to	4 mA																

