RCA2-TWA4N

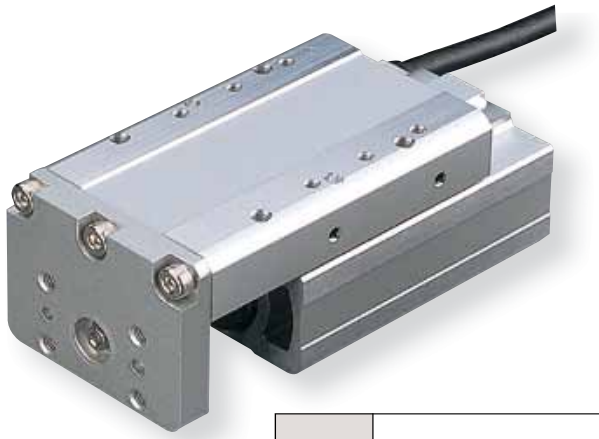
ROBO Cylinder Mini Table Type Short-Length Wide Model 58mm Width
24V Servo Motor Ball Screw/Lead Screw Models

■ Configuration: RCA2 — TWA4N — I — 20 — □ — 30 — □ — □ — □

Series	Type	Encoder	Motor	Lead	Stroke	Compatible Controllers	Cable Length	Option
RCA2	TWA4N	I: Incremental * The simple absolute encoder is also considered type "I".	20: 20W Servo motor	6 : 6mm ball screw 4 : 4mm ball screw 2 : 2mm ball screw 6S : 6mm lead screw 4S : 4mm lead screw 2S : 2mm lead screw	30: 30mm	A1: ACON, RACON, ASEL A3: AMEC, ASEP	N : None P : 1m S : 3m M : 5m X□□ : Custom	K2 : Connector cable exit direction LA : Power-saving

* See page Pre-35 for an explanation of the naming convention.

Power-saving



Technical References P. A-5

POINT Notes on Selection

(1) The load capacity is based on operation at an acceleration of 0.3G (0.2G for the 2mm-lead model, or when used vertically).
This is the upper limit of the acceleration.
(2) When using the Lead screw model, please ensure that your usage is appropriate for its characteristics. (See Pre-42 for more information.)

Actuator Specifications

■ Lead and Load Capacity

Model	Motor Output (W)	Feed Screw	Lead (mm)	Max. Load Capacity Horizontal (kg)	Max. Load Capacity Vertical (kg)	Rated Thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TWA4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-TWA4N-I-20-4-30-①-②-③			4	3	0.75	50.7		
RCA2-TWA4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-TWA4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-TWA4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-TWA4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible controller ② Cable length ③ Options

■ Stroke and Maximum Speed

Lead	Stroke 30 (mm)
Ball screw 6	270 <220>
Ball screw 4	200
Ball screw 2	100
Lead screw 6	220
Lead screw 4	200
Lead screw 2	100

* The values enclosed in "< >" apply to vertical usage. (Unit: mm/s)

Stroke List

Stroke (mm)	Standard Price	
	Feed Screw	
	Ball Screw Model	Lead Screw Model
30	-	-

② Cable List

Type	Cable Symbol	Standard Price
Standard (Robot Cables)	P (1m)	–
	S (3m)	–
	M (5m)	–
Special Lengths	X06 (6m) ～ X10 (10m)	–
	X11 (11m) ～ X15 (15m)	–
	X16 (16m) ～ X20 (20m)	–

* The RCA2 comes standard with a robot cable.
* See page A-39 for cables for maintenance.

③ Option List

Name	Option Code	See Page	Standard Price
Connector cable exit direction	K2	→ A-32	–
Power-saving	LA	→ A-32	–

Actuator Specifications

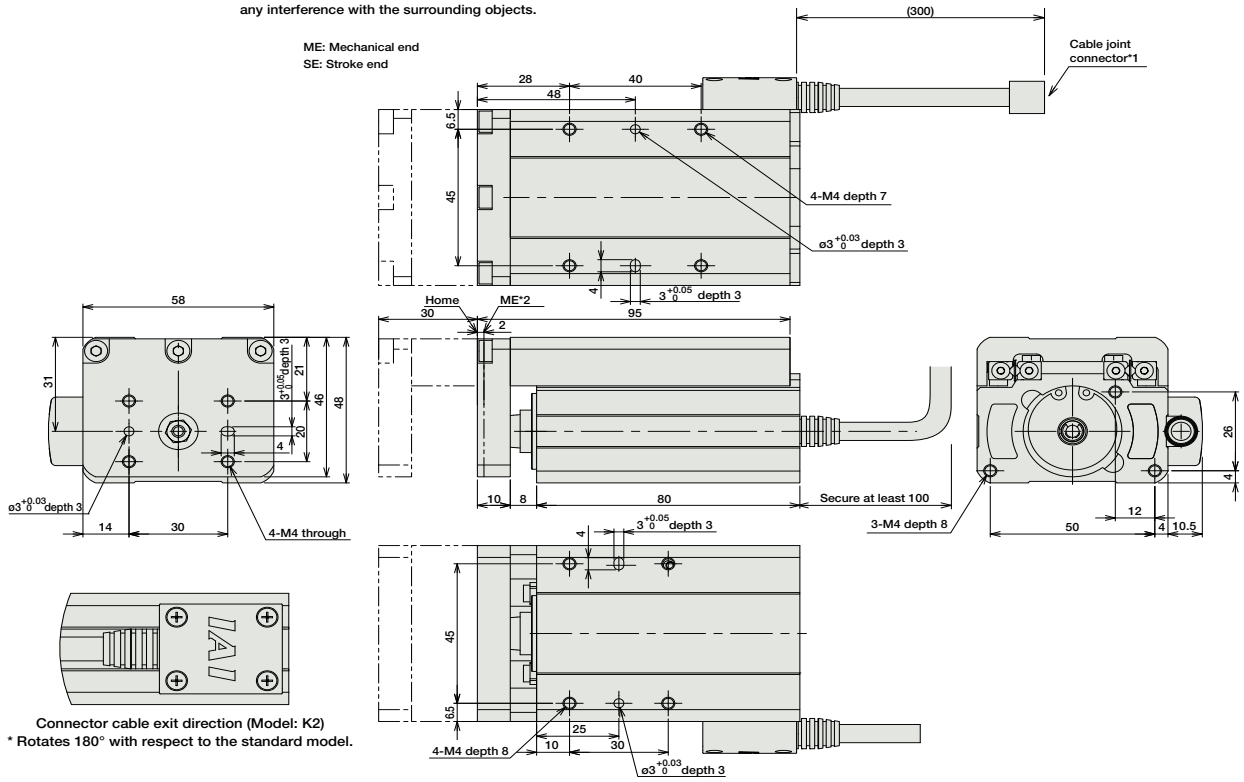
Item	Description
Drive System	Ball screw/Lead screw ø6mm C10 grade
Lost Motion	Ball screw: 0.1mm or less/Lead screw: 0.3mm or less (initial value)
Frame	Material: Aluminum (white alumite treated)
Allowable Dynamic Moment (Note)	Ma: 9.9 N·m Mb: 9.9 N·m Mc: 12.2 N·m
Ambient Operating Temp./Humidity	0～40°C, 85% RH or less (non-condensing)
Service Life Lead Screw Model	Horizontal: 10 million cycles Vertical: 5 million cycles

(Note) Based on a 5,000 km service life set for the guide.

Dimensions

For Special Orders P. A-9

*1 The motor-encoder cable is connected here. See page A-39 for details on cables.
*2 When homing, the table moves to the mechanical end; therefore, please watch for any interference with the surrounding objects.



Connector cable exit direction (Model: K2)
* Rotates 180° with respect to the standard model.

Dimensions/Weight by Stroke

Stroke	30
Weight (kg)	0.65

① Compatible Controllers

The RCA2 series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page
Solenoid Valve Type		AMEC-C-20I①-NP-2-1	Easy-to-use controller, even for beginners	3 points	AC100V	2.4A rated	–	→ P477
		ASEP-C-20I①-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types. No homing necessary with simple absolute type.		DC24V	(Standard) 1.3A rated 4.4A max. (Power-saving) 1.3A rated 2.5A max.	–	→ P487
Splash-Proof Solenoid Valve Type		ASEP-CW-20I①-NP-2-0					–	
Positioner Type		ACON-C-20I①-NP-2-0	Positioning is possible for up to 512 points	512 points			–	→ P535
Safety-Compliant Positioner Type		ACON-CG-20I①-NP-2-0					–	
Pulse Train Input Type (Differential Line Driver)		ACON-PL-20I①-NP-2-0	Pulse train input type with differential line driver support	(–)			–	
Pulse Train Input Type (Open Collector)		ACON-PO-20I①-NP-2-0	Pulse train input type with open collector support				–	
Serial Communication Type		ACON-SE-20I①-N-0-0	Dedicated to serial communication	64 points			–	
Field Network Type		RACON-20①	Dedicated to field network	768 points			–	→ P503
Program Control Type		ASEL-C-1-20I①-NP-2-0	Programmed operation is possible Operation is possible on up to 2 axes	1500 points			–	→ P567

* This is for the single-axis ASEL.
* ① is a placeholder for the code "LA" if the power-saving option is specified.