

# RCA2-TA7R

ROBO Cylinder Table Type Side-Mounted Motor 75mm Width 24V Servo Motor Ball Screw

■ Configuration: **RCA2** — **TA7R** — **I** — **30** —  —  —  —  —

Series	Type	Encoder	Motor	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental * The simple absolute encoder is also considered type "I".	30: 30W Servo motor	12 : 12mm 6 : 6mm 3 : 3mm	25: 25mm ) 200: 200mm (25mm pitch increments)	A1: ACON RACON ASEL A3: AMEC ASEP	N : None P : 1m S : 3m M : 5m X <input type="checkbox"/> : Custom	See Options below * Be sure to specify which side the motor is to be mounted (ML/MR).

\* See page Pre-35 for an explanation of the naming convention.

**Power-saving**



**Technical References** P. A-5

**POINT** Notes on Selection

- Please note that the maximum speed is different when used horizontally versus vertically.
- The load capacity is based on operation at an acceleration of 0.3G (0.2G for the 3mm-lead model, or when used vertically). This is the upper limit of the acceleration.

Actuator Specifications						Stroke and Maximum Speed	
■ Lead and Load Capacity						■ Stroke and Maximum Speed	
Model	Motor Output (W)	Lead (mm)	Max. Load Capacity Horizontal (kg)	Max. Load Capacity Vertical (kg)	Rated Thrust (N)	Stroke (mm)	Stroke / Lead (25 ~ 200 (25mm increments))
RCA2-TA7R-I-30-12-①-②-③-④	30	12	4	1	26	25~200 (25mm increments)	25 ~ 200 (25mm increments)
RCA2-TA7R-I-30-6-①-②-③-④		6	6	2.5	53		600 <580>
RCA2-TA7R-I-30-3-①-②-③-④		3	8	4	105		300
							150

Legend: ① Stroke ② Compatible controller ③ Cable length ④ Options

\* The values enclosed in "<" ">" apply to vertical usage. (Unit: mm/s)

① Stroke List

Stroke (mm)	Standard Price
25	-
50	-
75	-
100	-
125	-
150	-
175	-
200	-

③ Cable List

Type	Cable Symbol	Standard Price
Standard Type (Robot Cables)	P (1m)	-
	S (3m)	-
	M (5m)	-
Special Lengths	X06 (6m) ~ X10 (10m)	-
	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	-
		-

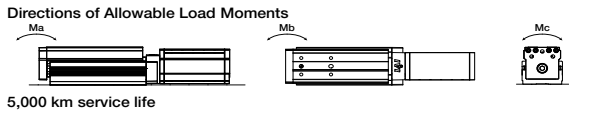
\* The standard cable is the motor-encoder integrated robot cable.  
\* See page A-39 for cables for maintenance.

④ Option List

Name	Option Code	See Page	Standard Price
Brake	B	→ A-25	-
Cable exit direction (Top)	CJT	→ A-25	-
Cable exit direction (Outside)	CJO		
Cable exit direction (Bottom)	CJB		
Power-saving	LA	→ A-32	-
Left-mounted Motor (Standard)	ML	→ A-33	-
Right-mounted motor	MR	→ A-33	-
Reversed-home	NM	→ A-33	-

Actuator Specifications

Item	Description
Drive System	Ball screw ø10mm C10 grade
Positioning Repeatability	±0.02mm
Lost Motion	0.1mm or less
Base	Material: Aluminum (special alumite treated)
Allowable Static Load Moment	Ma: 42.6 N·m Mb: 60.8 N·m Mc: 123.2 N·m
Allowable Dynamic Load Moment	Ma: 9.91 N·m Mb: 14.13 N·m Mc: 28.65 N·m
Overhang Load Length	Within the load moment range
Ambient Operating Temp./Humidity	0~40°C, 85% RH or less (non-condensing)



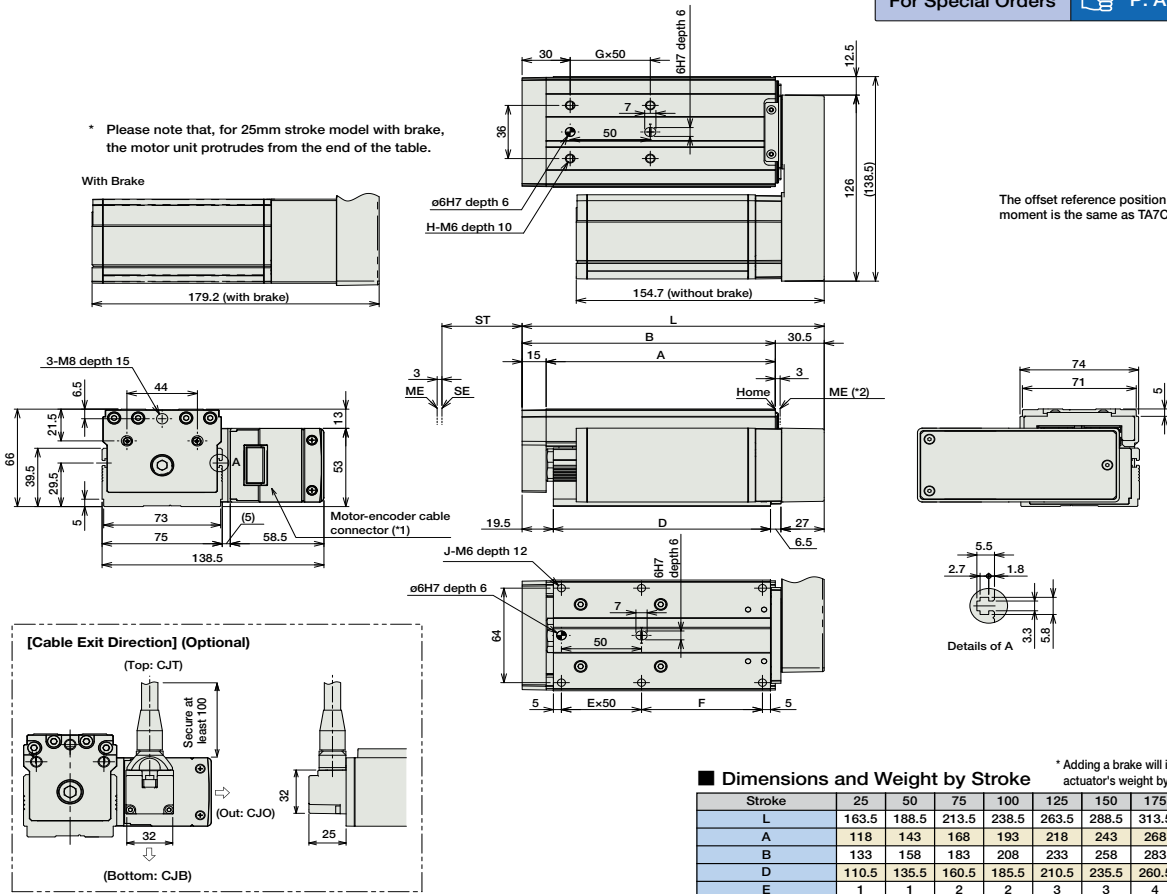
**315** RCA2-TA7R

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm /Flat Type
- Mini
- Standard
- Gripper/ Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash Proof
- Controllers
- PMEC /AMEC
- PSEP /ASEP
- ROBO NET
- ERC2
- PCON
- ACON
- SCON
- PSEL
- ASEL
- SSEL
- XSEL
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor

Dimensions

For Special Orders P. A-9

\* Please note that, for 25mm stroke model with brake, the motor unit protrudes from the end of the table.



The offset reference position of the moment is the same as TA7C (P308).

■ Dimensions and Weight by Stroke \* Adding a brake will increase the actuator's weight by 0.4kg.

Stroke	25	50	75	100	125	150	175	200
L	163.5	188.5	213.5	238.5	263.5	288.5	313.5	338.5
A	118	143	168	193	218	243	268	293
B	133	158	183	208	233	258	283	308
D	110.5	135.5	160.5	185.5	210.5	235.5	260.5	285.5
E	1	1	2	2	3	3	4	4
F	50.5	75.5	50.5	75.5	50.5	75.5	50.5	75.5
G	1	1	2	2	3	3	4	4
H	4	4	6	6	8	8	10	10
J	6	6	8	8	10	10	12	12
Weight (kg)	2.4	2.6	2.8	3.1	3.3	3.5	3.7	3.9

(\*1) The motor-encoder cable is connected directly to the motor cover of the actuator. See page A-39 for details on cables.  
 (\*2) After homing, the slider moves to the ME; therefore, please watch for any interference with the surrounding objects.  
 ME: Mechanical end  
 SE: Stroke end

② Compatible Controllers

The RCA2 series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page
Solenoid Valve Type		AMEC-C-30I①-NP-2-1	Easy-to-use controller, even for beginners	3 points	AC100V	2.4A rated	-	→ P477
		ASEP-C-30I①-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types. No homing necessary with simple absolute type.					→ P487
Splash-Proof Solenoid Valve Type		ASEP-CW-30I①-NP-2-0						
Positioner Type		ACON-C-30I①-NP-2-0	Positioning is possible for up to 512 points	512 points	DC24V	(Standard) 1.3A rated 4.0A max.	-	
Safety-Compliant Positioner Type		ACON-CG-30I①-NP-2-0						
Pulse Train Input Type (Differential Line Driver)		ACON-PL-30I①-NP-2-0	Pulse train input type with differential line driver support	(-)	DC24V	(Power-saving) 1.3A rated 2.2A max.	-	→ P535
Pulse Train Input Type (Open Collector)		ACON-PO-30I①-NP-2-0	Pulse train input type with open collector support					
Serial Communication Type		ACON-SE-30I①-N-0-0	Dedicated to serial communication	64 points				
Field Network Type		RACON-30①	Dedicated to field network	768 points				→ P503
Program Control Type		ASEL-C-1-30I①-NP-2-0	Programmed operation is possible. Operation is possible on up to 2 axes	1500 points				→ P567

\* This is for the single-axis ASEL.  
 \* ① is a placeholder for the code "LA", if the power-saving option is specified.

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm /Flat Type
- Mini
- Standard
- Cripper/ Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash Proof
- Controllers
- PMEC /AMEC
- PSEP /ASEP
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- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor