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Linear Products



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Linear •

AxialPower Series 🗅

Drives lacktriangle

SA-Series (

DA-Series (

SC-Series



For over 60 years, ElectroCraft has been helping engineers translate innovative ideas into reality – one reliable motor at a time. As a global specialist in custom motor and motion technology, we provide the engineering capabilities and worldwide resources you need to succeed.





This guide has been developed as a quick reference tool for ElectroCraft products. It is not intended to replace technical documentation or proper use of standards and codes in installation of product.

Because of the variety of uses for the products described in this publication, those responsible for the application and use of this product must satisfy themselves that all necessary steps have been taken to ensure that each application and use meets all performance and safety requirements, including all applicable laws, regulations, codes and standards.

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Typical applications for

ElectroCraft Linear Products:

- Custom OEM applications (Our Specialty)
- Packaging
- Semiconductor handling and testing
- Antenna positioning
- Laboratory equipment
- Rapid prototyping machines
- Medical equipment
- Dispensing





An ElectroCraft linear actuator with a custom mechanical configuration helps keep liquid and this business flowing.

Medical Dispensing Pump

Situation: An existing ElectroCraft customer wished to expand their line of medical dispensing pumps. Critical performance metrics included linear speed, axial force, and precise linear positioning. The customer required a wide range of output performance and input power requirements to successfully complete the "family" product offering.

Solution: ElectroCraft was able to design custom windings for the complete linear product offering combining both the linear actuator and leadscrew motor configurations, reducing the number of parts required yet still cover the customer's broad range of linear speed, force, and positioning requirements.

Results: ElectroCraft was able to reduce inventories through design and combined this effort with a Lean manufacturing based pull-system and Kanban program to further reduce inventory while improving delivery performance regardless of the customer's fluctuations in demand.

Helicopter Autopilot

Situation: A manufacturer interested in introducing a completely new technology of autopilot system approached ElectroCraft for an innovative solution. Positional accuracy was critical in this application. The customer was looking for a collaborative effort into the design of the electro-mechanical device.

Solution: ElectroCraft modified a size 17 Linear Actuator with a custom Mil-spec cable assembly, special lead-screw insert and lubrication in order to deliver prototypes quickly. Further collaboration with our customer's innovative R&D team improved the overall performance on subsequent design iterations.



ElectroCraft helps steer the way for a new generation of helicopter auto-pilot systems.

Results: The customer is flying high. Their concept is turned into reality as their product is being final tested and approved for flight.



The pressure is on this high powered linear actuator at the heart of this analytical instrument.

Chromatography Platform

Situation: A leading manufacturer of high end chromatography instruments needed a cost effective solution for a high pressure requirement in a new platform chromatography instrument.

Solution: ElectroCraft incorporated ballscrew technology into our most powerful 34 frame Linear Actuator to produce a compact, yet powerful product. Capable of generating over 900 pounds of force, this linear actuator integrates a high precision ball-nut into the rotor assembly with the ballscrew providing the positional accuracy and the high linear force needed to generate pressures in excess of 15,000 psi.

Sold & Service By: The capability of the high force and compact linear actuator allowed the customer to expand their product into new markets and opportunities for their customer base.

Toll Free Phone (877) SERVID98



Select your Linear Products!





A true Push-Pull, axially translating screw.



Rotating screw with an axial translating external nut.

Guided Linear Actuator



Functionality:

Some linear applications do not restrict the leadscrew from rotating

The Guided Linear Actuator feature restricts the screw from rotating, allowing the leadscrew to translate axially

A mechanical assist to the linear actuator to restrict the leadscrew from rotating with the rotor.

Drive Product Matrix

	Bipolar Ste	pper Drive		PM	IDC Servo Dr	ive	
	SA4505	SA4510	DA4303	DA4709	DA4718	SCA-LS-30-03	SCA-SS-30-06
Product Description							
See on page	19	21	23	25	25	27	29
Power Features							
Min. Voltage (VDC)	11	11	11	11	11	11	11
Max. Voltage (VDC)	48	48	30	70	70	30	30
Dual Bridge MOSFET Driver	•	•	•	•	•	•	•
Switching Frequency (kHz)	50	50	Linear	50	50	50	50
Linear Output			•			•	
PWM Output				•	•		•
Trap Waveform				•	•		•
Power Ratings							
Peak Current	5	10	3	18	36	3	6
Nominal Current	5	10	3	9	18	3	6
Adjustable Current	•	•	•	•	•	•	•
Max Continuous Power (W)	240	480	75	1260	2520	75	150
Control Modes							
Max. Step Input Frequency (kHz)	40	40					
Microstepping up to 1/16	•	•					
Internal Oscillator (x8)	•	•					
External Pulse Train (5-24 Logic)	•	•					
Fallback Current	•	•					
Analog Command (VDC)	+1 to +5 VDC	+1 to +5 VDC	±10	±10	±10	±10	±10
Torque Control				•	•	•	•
I/R Compensation			•	•	•	•	•
Speed Control using Tach			•	•	•	•	•
Speed Control using Voltage			•	•	•	•	•
Speed Control using Encoder							
Communication / Compliance							
CE Compliance (LV Directive)	•	•	•	•	•	•	•
Physical Enclosure							
Totally Enclosed	•	•	•	•	•	•	•
Case Type	Book Shelf	Book Shelf	Book Shelf	Book Shelf	Book Shelf	Rack	Rack





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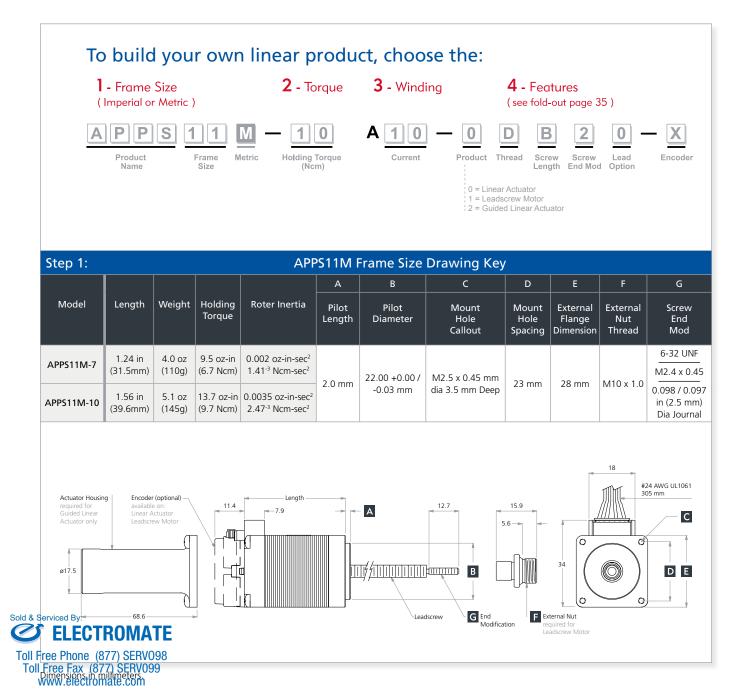
APPS11M: ElectroCraft AxialPower™ Plus | Linear Actuator Stepper

Size	Holding Torque oz-in (Ncm)	Linear Speed inch / sec (mm / sec)	Linear Force Pounds (Newton)
NEMA 11, 1.8°	14 (10)	16 (400)	32 (140)



Reliable. Precise.

The ElectroCraft size 11 stepper-based linear actuator is ultra-reliable and made to exacting standards incorporating precision materials all designed to provide reliable performance with axial resolution in the microns.





Step 2: APPS11M Torque and Mechanical Data (Bipolar) APPS11M-7 APPS11M-10 Step Angle = 1.8°, 9.5 oz-in hold torque Supply = 48 VDC X 1 amp/phase Step Angle = 1.8°, 9.5 oz-in hold torque Supply = 48 VDC X 1 amp/phase Supply = 24 VDC X 1 amp/phase = 24 VDC X 1 amp/phase 35 156 35 156 30 30 132 132 25 110 25 110 88 20 88 20 Poun Poun 15 66 15 66 10 44 10 22 5 22 5 M D M 4 (100) 8 (200) 12 (300) 16 (400) 4 (100) 8 (200) 12 (300) 16 (400) Speed, inch (mm) / second @ 48VDC Speed, inch (mm) / second @ 48VDC 0 2 (50) 4 (100) 6 (150) 8 (200) 2 (50) 4 (100) 6 (150) 8 (200) Speed, inch (mm) / second @ 24VDC Speed, inch (mm) / second @ 24VDC Curves are approximaned as straight line for ease of use. Thread Designation Thread Lead Inches (mm) / Rev Linear Travel Inch (mm) / Full-Step 3/16-20 ACME (1S) 0.050 (1.3) 0.00025 (0.0064) 3/16-24 ACME (3S) 0.125 (3.2) 0.00063 (0.0160) 3/16-24 ACME (8S) 0.333 (8.5) 0.00167 (0.0424)

Motor step rate calculation: Motor step rate (halfstep/sec) = [Speed (in/sec)*2] / [travel (in/fullstep)]

Example "L" thread pitch: @ 2 in/sec = 6,350 halfsteps/sec

Ste	р 3:			Available Wind	dings		
	Metric	7A05	7A10	7A15	10A05	10A10	10A15
_	Current Bipolar (A/Phase)	0.5	1.0	1.5	0.5	1.0	1.5
Bipolar	Phase Voltage VDC	5.0	2.5	1.7	6.2	3.1	2.1
B	Phase Resistance (ohm)	10.00	2.50	1.10	12.40	3.10	1.40
	Phase Inductance (mH)	6.8	1.5	0.7	10.4	2.7	1.1

Unipolar windings available upon request.



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APPS17 & APPS17M: ElectroCraft AxialPower™ Plus | Stepper

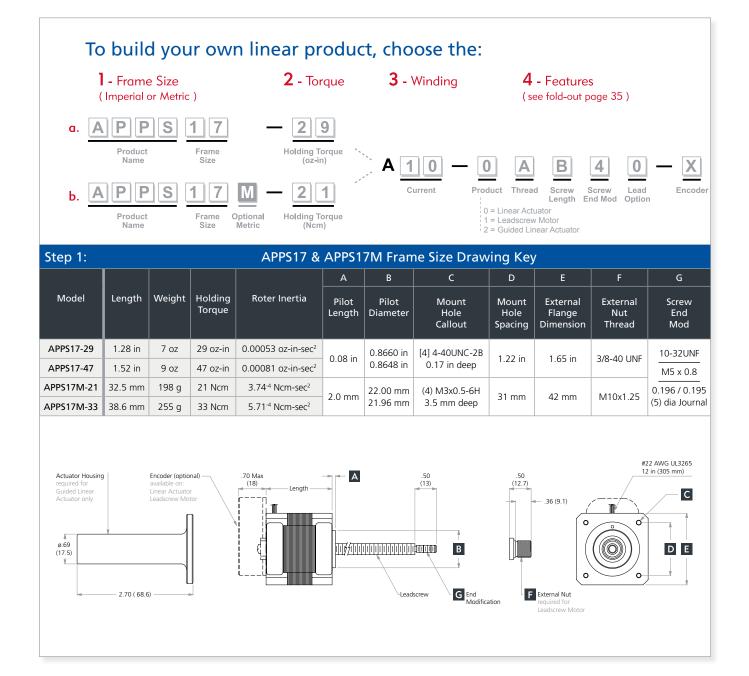
Size	Holding Torque oz-in (Ncm)	Linear Speed inch / sec (mm / sec)	Linear Force Pounds (Newton)
NEMA 17, 1.8°	47 (33)	20 (508)	70 (310)



ROHS

Precise. Quick.

The ElectroCraft NEMA 17 stepper-based linear actuator is reliable, made to be both precise and responsive with positional accuracy in the microns, load capabilities up to 70 Lbs (32kg), and linear speeds to 12 inches/second (305mm/second).





Step 2: APPS17 & APPS17M Torque and Mechanical Data (Bipolar) APPS17-29 APPS17-47 APPS17M-33 APPS17M-21 Supply = 40 VDC x 2 amp/phase = 24 VDC x 2 amp/phase Supply = 40 VDC x 2 amp/phase = 24 VDC x 2 amp/phase 50 225 80 360 70 315 180 40 60 270 50 225 30 135 Pounds 40 180 20 90 135 30 20 10 10 В 5 (125) 10 (250) 15 (375) 20 (500) 5 (125) 10 (250) 15 (375) 20 (500) Speed, inch (mm) / second @ 40VDC ed, inch (mm) / second @ 40VDC 3 (75) 6 (150) 9 (225) 12 (300) 0 3 (75) 6 (150) 9 (225) 12 (300) Speed, inch (mm) / second @ 24VDC Speed, inch (mm) / second @ 24VDC 29A20 (21A20) Curves are approximaned as straight line for ease of use. 47A20 (33A20) Thread Designation Thread Lead Inches (mm) / Rev Linear Travel Inch (mm) / Full-Step Y Intercept Pounds (N) X Intercept 24 Volt X Intercept 40 Volt Y Intercept Pounds (N) X Intercept 24 Volt X Intercept 40 Volt 0.02500 0.00013 40 1 35 2 25 80 1.00 1 68 J* 1/4-40 UN (1S) (0.6)(0.0033)(180)(35)(60)(355)(25)(40)0.03125 0.00016 38 1.69 2.81 76 1.25 2.12 ٧× 1/4-32 ACME (1S) (170)(340)(30)(0.8)(0.0041)(40)(70)(55)0.05000 0.00025 37 4 50 74 2.00 3.38 2.70 E* 1/4-20 ACME (1S) (1.3)(0.0064)(165)(70)(115)(330)(50)(85)0.06250 0.00031 36 3.37 5.62 72 2.55 4.25 Α 1/4-16 ACME (1S) (1.6)(0.0079)(160)(85)(140)(320)(65)(110)0.12500 0.00063 6.75 11.25 5.00 8.44 30 60 В 1/4-16 ACME (2S) (3.2)(0.0160)(135)(170)(285)(265)(130)(215)0.20000 0.00100 24 10.80 18.00 48 8.12 13.50 F* 1/4-20 ACME (4S) (105)(460)(205)(340)(5.1)(0.0254)(275)(215)

Motor step rate calculation: Motor step rate (halfstep/sec) = [Speed (in/sec)*2] / [travel (in/fullstep)]

0.00125

(0.0318)

0.25000

(6.4)

Example "B" thread pitch: @ 2 in/sec = 6,420 halfsteps/sec

10.12

(260)

16.88

(430)

40

(175)

Ste	р 3:						
	Imperial 29A10		29A15	29A20	29A20 47A10	47A15	47A20
	Metric	21A10	21A15	21A20	33A10	33A15	10A20
Bipolar	Current Bipolar (A/Phase)	1.0	1.5	2.0	1.0	1.5	2.0
<u>B</u>	Phase Resistance (ohm)	3.8	1.90	0.95	4.9	2.4	1.2
	Phase Inductance (mH)	4.8	2.3	1.2	9.1	4.9	2.3

20

(90)

13.50

(340)

22.5

(570)

Unipolar windings available upon request.

1/4-16 ACME (4S)



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^{*} Consult factory for availability.



APPS23 : ElectroCraft AxialPower™ Plus | Linear Actuator Stepper

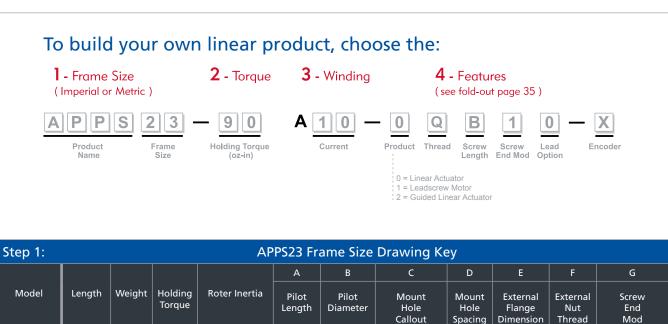
Size Holding To		Linear Speed	Linear Force
oz-in (No		inch / sec (mm / sec)	Pounds (Newton)
NEMA 23, 1.8°	150 (106)	7.5 (190)	

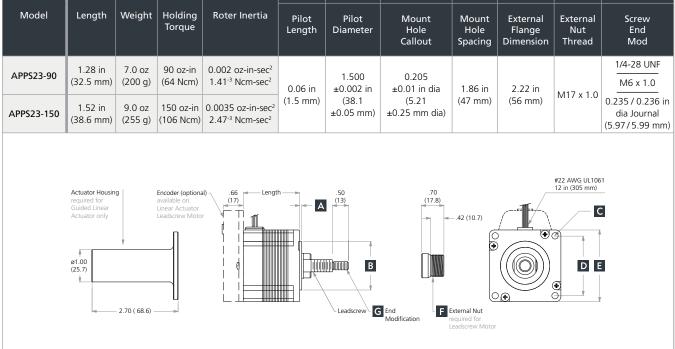




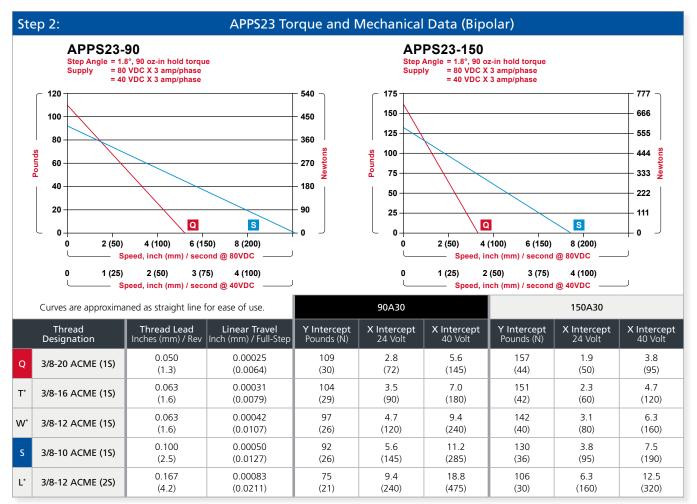
Quick. Powerful.

The ElectroCraft NEMA 23 stepper-based linear actuator is reliable, made to be both responsive and powerful, with positional accuracy in the microns, load capabilities up to 175 Lbs (80kg) and linear speeds to 5 inches/second (130mm/second).









Motor step rate calculation: Motor step rate (halfstep/sec) = [Speed (in/sec)*2] / [travel (in/fullstep)]

Example "S" thread pitch: @ 2 in/sec = 8,000 halfsteps/sec

Ste	р 3:						
	Imperial	90A10	90A20	90A30	150A10	150A20	150A30
_	Current Bipolar (A/Phase)	1.0	2.0	3.0	1.0	2.0	3.0
Bipolar	Phase Voltage VDC	5.8	3.0	1.8	7.9	3.8	2.4
B	Phase Resistance (ohm)	5.78	1.50	0.60	7.92	1.90	0.80
	Phase Inductance (mH)	20.3	5.2	2.0	35.0	8.6	3.5

Unipolar windings available upon request.



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Need an anti-backlash feature or don't see exactly what you need? Have ElectroCraft build you a custom winding, stack length or fully customized linear product ...

that's our specialty!

^{*} Consult factory for availability.



L3S: ElectroCraft 34 Frame | Linear Actuator Stepper

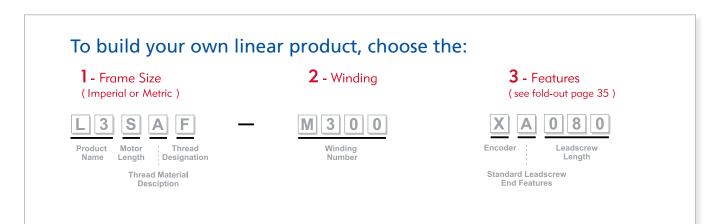
Size	Holding Torque oz-in (Ncm)	Linear Speed inch / sec (mm / sec)	Linear Force Pounds (Newton)	
NEMA 34, 1.8°	396 (280)	8.75 (225)	700 (3120)	

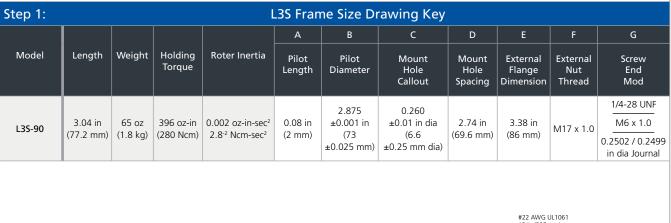


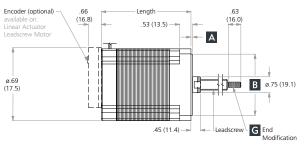


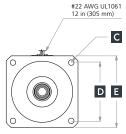
Powerful. Robust.

This NEMA 34 stepper-based linear actuator is the workhorse of linear motors. Made to move your most demanding loads with dual front bearings capable of up handling 700 Lbs (320kg) of linear force with precise resolution is a performance to be respected.



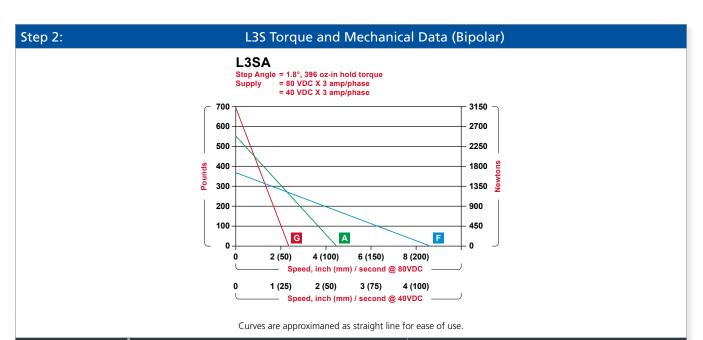






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	Thread Designation	Thread Lead Inches (mm) / Rev	Linear Travel Inch (mm) / Full-Step
(1/2-20 ACME (1S)	0.05 (1.3)	0.00025 (0.0064)
,	1/2-10 ACME (1S)	0.10 (2.5)	0.00050 (0.0127)
	1/2-10 ACME (2S)	0.20 (5.1)	0.00100 (0.0254)

Example "A" thread pitch: @ 2 in/sec = 8,000 halfsteps/sec

Ste	ep 3:		Available Windings			
	Imperial	M200	M300	M500		
_	Current Bipolar (A/Phase) 2.0		3.0	5.0		
Bipolar	Phase Voltage VDC	5.0	3.0	2.0		
<u> </u>	Phase Resistance (ohm)	2.50	1.00	0.40		
	Phase Inductance (mH)	21.9	8.7	3.4		

Uniploar winding available for OEM application upon request.



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APPD15 & APPD15M: ElectroCraft AxialPower™ | Linear Actuator PMDC

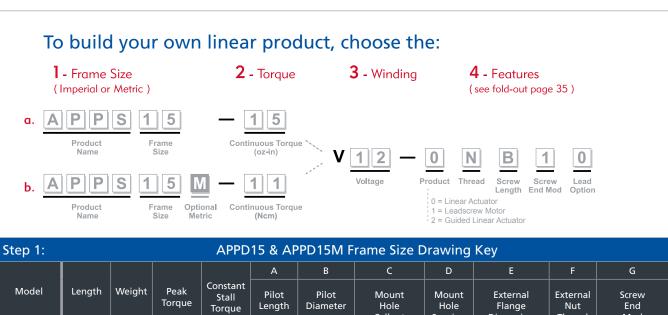
Size	Peak Torque oz-in (Ncm)	Linear Speed inch / sec (mm / sec)	Linear Force Pounds (Newton)	
15 FRAME	45 (32)	2.5 (64)	70 (315)	

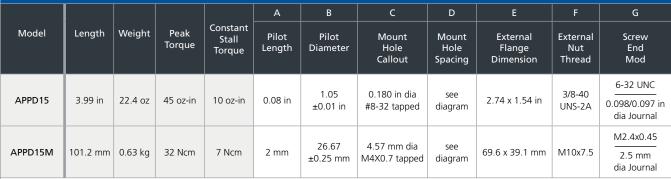


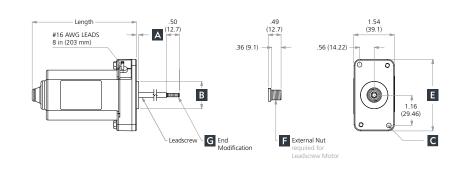


Simple. Direct.

The ElectroCraft 15 frame PMDC based linear actuators offers a simple on/off control for direct axial movement. Whether replacing an air cylinder, or introducing a simple electric actuator to your system, this simple, low cost solution is a reliable alternative.









Step 2: APPD15 & APPD15M Torque and Mechanical Data (Bipolar) **APPD15-15** APPD15M-11 Supply Voltage = 12 Volts 315 60 270 225 50 40 180 30 135 20 90 10 45 R Ν 0 1 (25) 2 (50) 3 (75) 4 (100) Speed, inch (mm) / second @ 12VDC Curves are approximaned as straight line for ease of use. Thread Designation Thread Lead Inches (mm) / Rev 10-32 (1S) 0.03 (0.762) 10-32 (2S) 0.06 (1.524) 10-32 (4S) 0.13 (3.302)

Step 3:	Available Windings
Imperial	15V12
Metric	11V12
Voltage (Vdc)	12.0
Voltage Constant V/kRPM	3.2
Torque Constant oz-in/A (Ncm/A)	4.3 (3)
Max Continuous Current (A)	3.7
Peak Current (A)	10.0

^{* 24} Volt windings for OEM applications are available upon request.









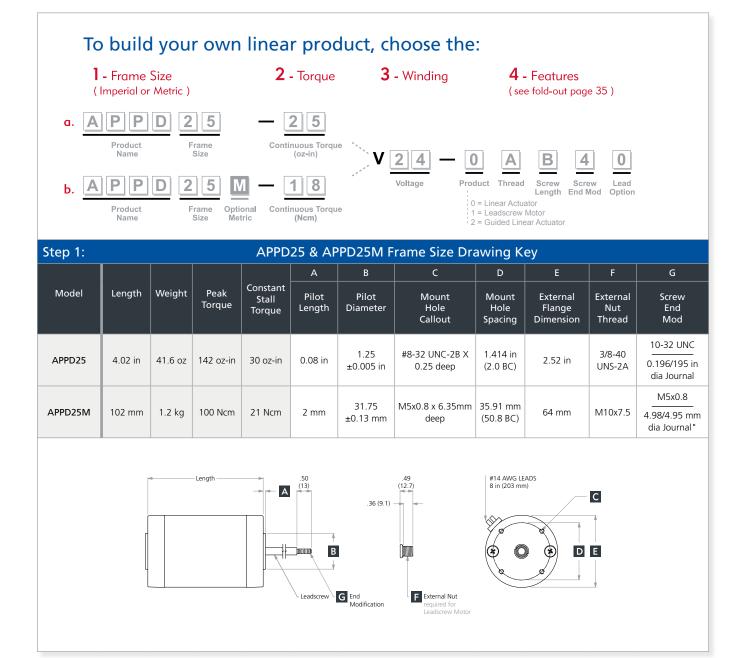
APPD25 & APPD25M: ElectroCraft AxialPower™ | Linear Actuator PMDC

Size	Peak Torque oz-in (Ncm)	Linear Speed inch / sec (mm / sec)	Linear Force Pounds (Newton)	
25 FRAME	215 (152)	1.6 (40)	180 (810)	

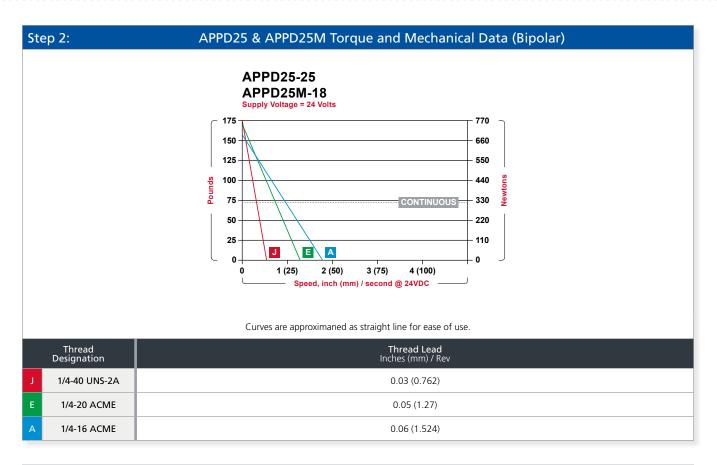


Simple. Direct.

The ElectroCraft 25 frame PMDC based linear actuators offers a simple on/off control for direct axial movement. Whether replacing an air cylinder, or introducing a simple electric actuator to your system, this simple, low cost solution is a reliable alternative.







Step 3:	Available Wind	ings		
Imperial	25V12*	25V24		
Metric	18V12*	18V24		
Voltage (Vdc)	12.0	24.0		
Voltage Constant V/kRPM	3.3	6.6		
Torque Constant oz-in/A (Ncm/A)	4.4 (3.1)	8.9 (6.2)		
Max Continuous Current (A)	9.2	4.6		
Peak Current (A)	32.0	16.0		

^{* 12} Volt windings for OEM applications are available upon request. More coarse threads (increased speed).









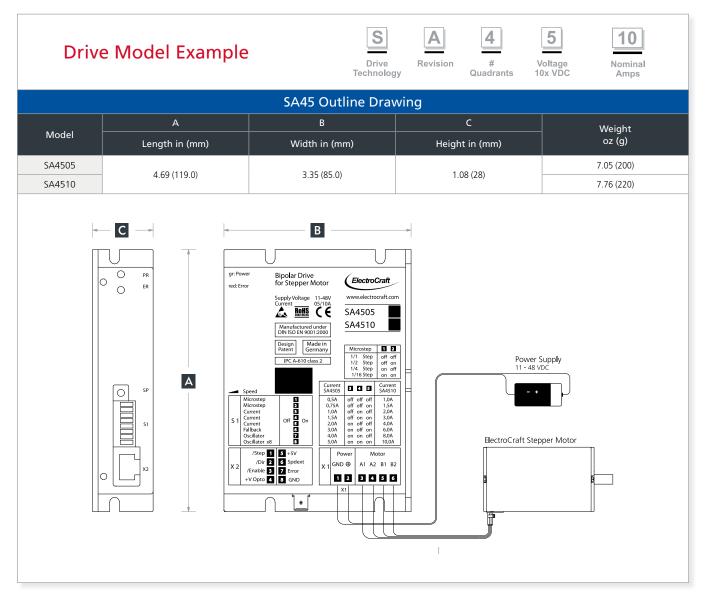
SA45: **Electrocraft CompletePower™** | Stepper Drive

Power Supply	Nominal	Nominal Phases Current	Operation Mode		Special Functions		
Voltage	Current		Fullstep	Micro stepping	Integrated Oscillator	Current Fallback	Anti-Resonance Anti-Noise
11 - 48	5 / 10	2	•	•	•	•	•



For Stepper Motors. Up to 480W.

This bipolar stepper drive provides microstepping to 1/16 built into a fully enclosed rugged aluminum case. It can be DIN-rail mounted or panel mounted for fast integration. The mode of operation is set by simple DIP switches. Features include an internal oscillator that allows operation of the drive at a internal speed set point or with an external analog speed reference that can scale this set point. Both the 5 A and 10 A versions of this drive can be powered by the same range of voltage supplies. This drive is protected against over-current and overtemperature and incorporates the state of the art dual full bridge MOSFET driver for maximum efficiency. Connectivity is tool-free with RJ45-CAT5 plugs for the control inputs and push-type terminals for power.



SA45 Specifications								
Model Number	Power Supply Voltage (VDC)	Nominal Current (Amps)	Max. Power with Heatsink (Watts)	Frequency of power output stage (kHz)	Efficiency (%)			
SA4505	11 - 48	5	240	50	95			
SA4510	11 - 48	10	480	50	95			
		Cor	trol Inputs					
	Enable			Optical, Ri = 1 kOhm; max. 20	O mA			
	Direction			Optical, Ri = 1 kOhm; max. 20	O mA			
	Step		Optio	cal, Ri = 1 kOhm; max. 20 mA	; 250 kHz			
	Speed ext.			+1to +5 VDC; Ri = 100 kOl	nm			
	Switches							
	Microstep			1/1; 1/2; 1/4; 1/16				
	Current			0,5 A to 5 A / 1 A to 10 A	4			
	Fallback			on / off				
	Oscillator			on / off				
	Oscillator x8			on / off				
		(Outputs					
	Auxiliary voltage sourc	e +5V		+5 VDC / 50 mA				
	Fault			Optical, max. 20 mA				
			Display					
	LEDs			green= Power / red = Erro	or			
		Function c	of Potentiometers					
	Speed		Rai	nge: 4 Hz - 500kHz / 40 Hz - 4	1800 Hz			
		Ambie	nt conditions					
	Operation temperatur	e (°C)		-10 to +45				
	Storage temperature	(°C)		-40 to +85				
	20 to 80 % rel.							
		Mode	of Operation					
	Fullstep; Microstep: 1/2, 1/4, 1/16							

	Available Accessories for SA45 (details see page 36)								
IA210x	CAxxx	HA3008	HA3018	HA3028	MA0025	WA2509			
<u> </u>	Q								



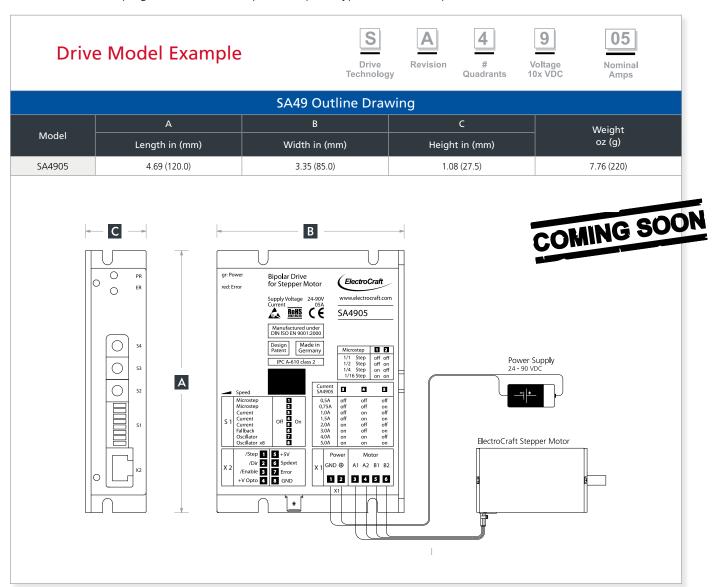
SA49 : Electrocraft CompletePower™ | Stepper Drive

Power Supply	Nominal	Phases	Operation	on Mode	Sį	pecial Fun	ctions
Voltage	Current		Fullstep	Micro stepping	Integrated Oscillator	Current Fallback	Anti-Resonance Anti-Noise
24 - 90	5	2	•	•	•	•	•



For Stepper Motors. Up to 450W.

This bipolar stepper drive provides microstepping to 1/16 built into a fully enclosed rugged aluminum case. It can be DIN-rail mounted or panel mounted for fast integration. The mode of operation is set by simple DIP switches. Features include an internal oscillator that allows operation of the drive at a internal speed set point. The current setting, internal speed and ramp time can easily be selected using BCD input switches then toggled into memory. This drive is protected against over-current and over-temperatureand incorporates the state of the art dual full bridge MOSFET driver for maximum efficiency. Connectivity is tool-free with RJ45-CAT5 plugs for the control inputs and push-type terminals for power.





		SA49 S _I	pecifications					
Model Number	Power Supply Voltage (VDC)	Nominal Current (Amps)	Max. Power with Heatsink (Watts)	Frequency of power output stage (kHz)	Efficiency (%)			
SA4905	24 - 90	5	450	50	95			
		Con	rol Inputs					
	Enable			Optical, Ri = 1 kOhm; max. 20	O mA			
	Direction			Optical, Ri = 1 kOhm; max. 20	D mA			
	Step (250 kHz)			Optical, Ri = 1 kOhm; max. 20	D mA			
		S	witches					
	Microstep			1/1; 1/2; 1/4; 1/16				
	Current Set			idle / set				
	Fallback			on / off				
	Speed Set			idle / set				
	I/O voltage			int / ext				
	Enable			int / ext				
	BCD Select		Speed / Current / Ramp					
		C	utputs					
	Auxiliary voltage sourc	e +5V		+5 VDC / 50 mA				
	Fault			Optical, max. 20 mA				
		[Display					
	LEDs			green = Ready / red = Erro	or			
		Function o	f Potentiometers					
	Speed			Range: 1,5 Hz - 1,2 kHz / 12 Hz - 9,6 kHz				
			nt conditions					
	Operation temperatur	e (°C)	-10 to +45					
	Storage temperature	(°C)	-40 to +85					
	Humidity Range Not Conder	nsing (%rel)		20 to 80 % rel.				

Mode of Operation

Fullstep; Microstep: 1/2, 1/4, 1/16

The information on these pages represents data that is preliminary in nature and is subject to change. Please contact the factory for the most current information.



	Available Accessories for SA49 (details see page 36)								
IA210x	CAxxx	HA3008	HA3018	HA3028	MA0025	WA2509			
<u></u>	Q		0						



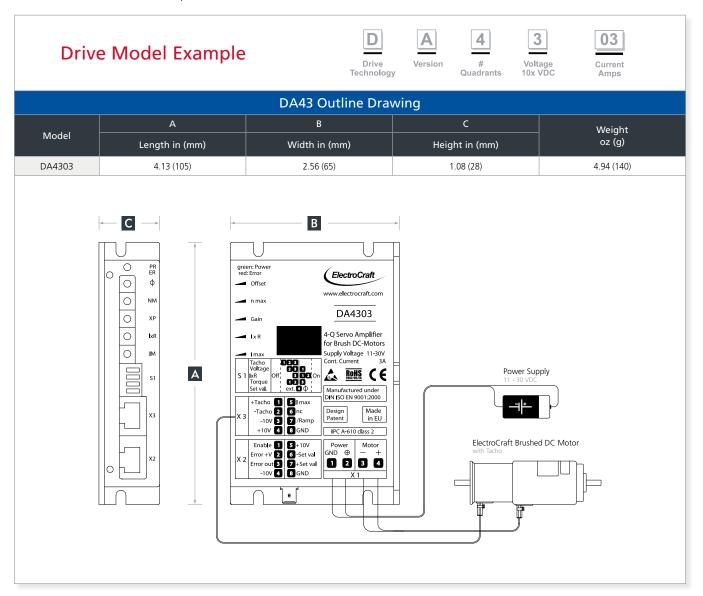
DA43 : Electrocraft CompletePower™ | Servo Amplifier

Danier Committee	oply Nominal Qu	Quadrants	Operation Mode					
Power Supply Voltage	Current		•	Analog Pos.	Speed Control			
			Control		I x R Comp.	DC-Tacho	Voltage	Encoder
11 – 30	3	4	•		•			



For Brush-Commutated Linear PMDC Motors. Up to 75 W.

This servo-amplifier is built into a fully enclosed rugged miniature aluminum case. Linear servo amplifiers are ideal for low friction applications requiring high bandwidth, low noise and minimal distortion from the power electronics. The drive can be configured in the following modes of operation with simple dip switch settings: I/R compensation, Tach mode, Voltage mode and Torque mode. Input power of 30 VDC combined with a mountable heat-sink provides up to 75 Watts of power. Inputs include current limit, max set value and gain functions. The drive handles continuous currents up to 3 A. The linear power stage is protected against overcurrent and over-temperature.





		DA4.	3 Spe	cifications			
Model Number	Power Supply Voltage (VDC)	Aux. Voltage Verror (VDC)	N	ominal Current (Amps)	Max. Power Heatsink (W		Efficiency (%)
DA4303	11 - 30	5 - 30		3	75		97
		(Contro	l Inputs			
	Set val	lue		-10 to +10 VDC; Ri = 20 kOhm			
	lmax	x			0 to +10 VDC;	Ri > 10 kO	hm
	Tach	0			max. 50 VDC;	Ri = 75 kOl	nm
	Enab	le			TTL/ +24 VDC;	Ri = 47 kO	hm
	Ram	р			active LO; Ri	= 100 kOhr	m
			Swit	ches			
	Tacho-, Voltage-, IxF	Not set / Set					
	Set value vi		extern .	/ intern			
			Out	puts			
	Auxiliary volta	age source		+10 VDC / 10 mA each			
	Auxiliary volta	age source		+10 VDC / 10 mA each			
	Erro	r		TTL / 24 VDC; Ri = 50 Ohm			
			Dis	olay			
	LEDs	s		green = Power / red = Error			
		P	otenti	ometers			
	Function of Pot	tentiometer			Offset; nmax;	Gain; lxR; In	nax
		Am	bient o	conditions			
	Operation temp	perature (°C)		-10 to +45			
	Storage tempe	erature (°C)		-40 to +85			
	Humidity Range Not (Condensing (%rel)		20 to 80 % rel.			
	1	Mo	de of (Operation			
Speed	-control by voltage	Torque-control		IxR-compe	ensation	Spe	ed-control by DC-tacho





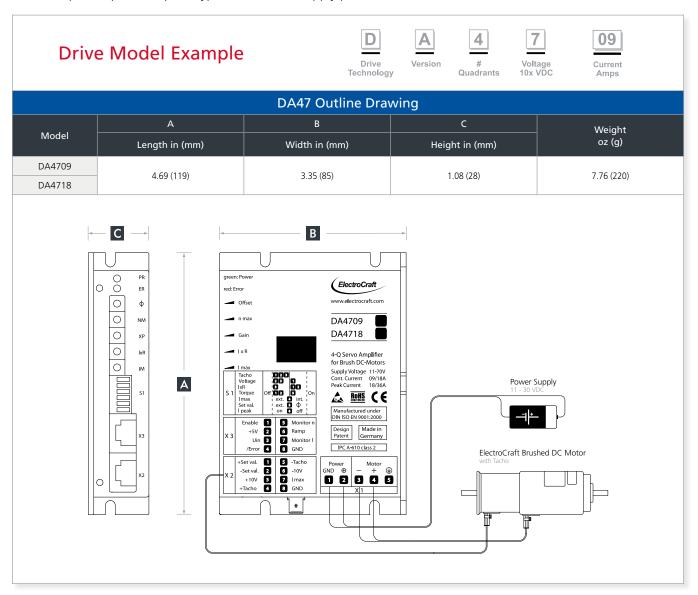
DA47 : Electrocraft CompletePower™ | Servo Amplifier

Danier Committee	Nominal Naminal	Quadrants	Operation Mode					
Power Supply Voltage	Nominal Current		•	Analog Pos.	Speed Control			
					I x R Comp.	DC-Tacho	Voltage	Encoder
11 – 70	9 / 18	4	•		•	•		



For Brush-Commutated PMDC Motors. Up to 1260 W.

This four-quadrant PWM brush DC servo amplifier is fully enclosed in a small, rugged aluminum case which can be DIN-rail mounted or panel mounted for easy integration. The drive can be configured in the following modes of operation with simple dip switch settings: I/R compensation, Tach mode, Voltage mode and Torque mode. Both the 9 A and 18 A versions have twice the rated current available as peak current for intermittent overload conditions. This drive is protected against over-current and over-temperature and incorporates state of the art MOSFET technology for maximum efficiency. Connectivity is tool-free with RJ-45-connectors for input/outputs and push-type terminals for supply power and motor connections.





			DA47	Specification	15				
Model Number	Power Supply Voltage (VDC)	Aux. Voltage Verror (VDC)	Nominal Current (Amps)	Peak current (Amps)	Max. Power with Heatsink (Watts)	Frequency of power output stage (kHz)	Efficiency (%)		
DA4709			9	18	630				
DA4718	11 - 70	5 - 30	18	36	1260	50	95		
			Со	ntrol Inputs					
		Set value			-10 to +10	VDC; Ri = 20 kOhm			
		Tacho			max. 50 \	/DC; Ri = 50 kOhm			
		Enable			TTL/ +24 \	/DC; Ri = 4.7 kOhm			
		I Limit			int	ern / extern			
		Ramp			TTL / +24 \	VDC; Ri = 4.7 kOhm			
		lmax			0 to +10 V	/DC; Ri > 100 kOhm			
	Switches								
	Tacho-, Volta	age-, IxR-, Torque-M	ode		N	ot set / Set			
	Set	value via Offset			extern / intern				
		I peak			on / off				
				Outputs					
	Auxilia	ary voltage source			+5 VDC / 50 mA				
	Auxilia	ry voltage sources			±10 VDC / 20 mA				
		Monitor I			1 / 0.5 V/A; Ri = 100 Ohm				
		Monitor n			0.1 V / 1 Vmotor ; Ri = 100 Ohm				
	Superv	isory output /Error			Open Collector / Push Pull / TTL / +24V; Ri = 50 Ohm				
				Display					
		LEDs			green = Power / red = Error				
			Pot	entiometers					
	Functio	n of Potentiometer			Offset; nmax; Gain; lxR; lmax				
			Ambi	ent conditions					
	Operation	on temperature (°C)			-10 to +45				
	Storage	e temperature (°C)			-40 to +85				
	Humidity Rang	ge Not Condensing	(%rel)		20 to 80 % rel.				
			Mode	of Operation	of Operation				
Speed	-control by voltage		Torque-control	b	R-compensation	Speed-control b	y DC-tacho		

	Available Accessories for DA47 (details see page 36)							
ASO-BM-70-30	IA210x	CAxxxx	HA3008	HA3018	HA3028	MA0025	WA2509	
	00	0		(A)	8			



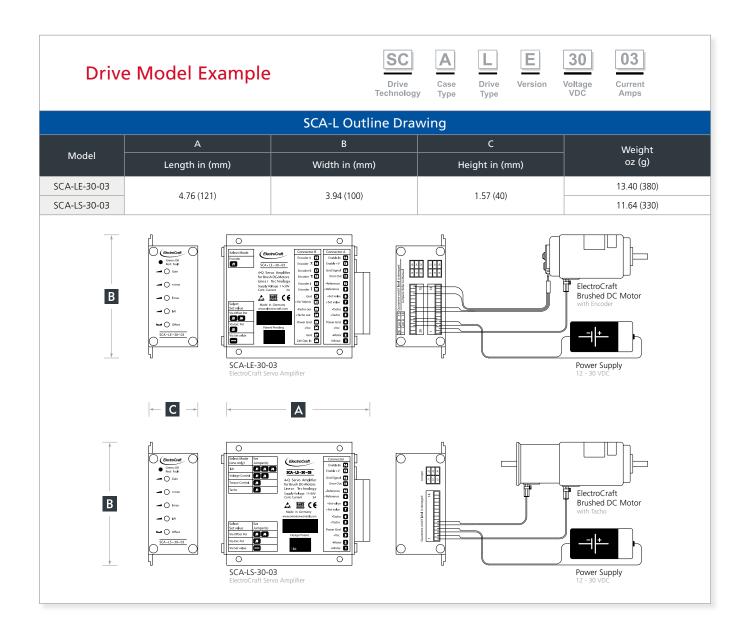
SCA-L: Electrocraft CompletePower™ | Servo Amplifier

Model	Power	Nominal	Quadrants			Operatio	n Mode		
	Supply	Current		Torque	Analog		Speed Cor	ntrol	
	Voltage			Control	Pos.	I x R Comp.	DC-Tacho	Voltage	Encoder
SCA-LE-30-03	11 – 30	3	4						•
SCA-LS-30-03	11 – 30	3	4			•		•	



For Brush-Commutated PMDC Motors. Up to 75 W.

This linear four-quadrant brushless DC servo amplifier is fully enclosed in a rugged aluminum case which can be panel mounted for easy integration. The drive is available in several configurations depending on your control requirements. The drive handles continuous currents up to 3 Amps and is protected against over-current, over-temperature and motor short-circuit.







		SCA-L Spec	ifications				
Model Number	Power Supply Voltage (VDC)	N	Iominal Current (Amps)	l,	Nax. Power with Heatsink (Watts)		
SCA-LE-30-03			_				
SCA-LS-30-03	11 - 30		3		75		
		Control	Inputs				
	Set value		-10 to +10 VDC; Ri = 100 kOhm				
	Tacho		ma	x. 50 VDC; Ri =	= 50 kOhm		
	Enable		+8	to +30 VDC; Ri	= 5 kOhm		
	Encoder input signals (SCA-LE	only)	Channel A & /A; B & /B; I & /I	; max. 600 kHz	; TTL/ +5 to +24 VDC; Ri > 10 kOhr		
		Outp	outs				
A	Auxiliary voltage source for encoder (S	CA-LE only)	+5 VDC / 100 mA				
	Auxiliary voltage source			+3,9 VDC / 2	0 mA		
	Auxiliary voltage source			-3,9 VDC / 20	0 mA		
	Auxiliary voltage source Enable	2 +V	Conne	cted with 4.7 k	Ohm to +VCC		
	Error		Open Collector max. +30 VDC; 20 mA				
		Disp	lay				
	LEDs		green = OK / red = Fault				
		Potentic	meters				
	Function of Potentiometer		Ga	in; nmax; lmax;	IxR; Offset		
		Ambient c	onditions				
	Operation temperature (°C)		-10 to +4	.5		
	Storage temperature (°C)		-40 to +85				
	Humidity Range Not Condensing	(%rel)	20 to 80 % rel.				
		Mode of C	peration				
SCA-LE-30-03		Speed-co	ontrol by Digital-Encoder				
SCA-LS-30-03	Speed-control by voltage	Torque-control	IxR-compen	sation	Speed-control by DC-tacho		

Available Accessories fo	r SCA-L (details see page 36)			
ASO-BM-70-30	ASX-RM-01-01			



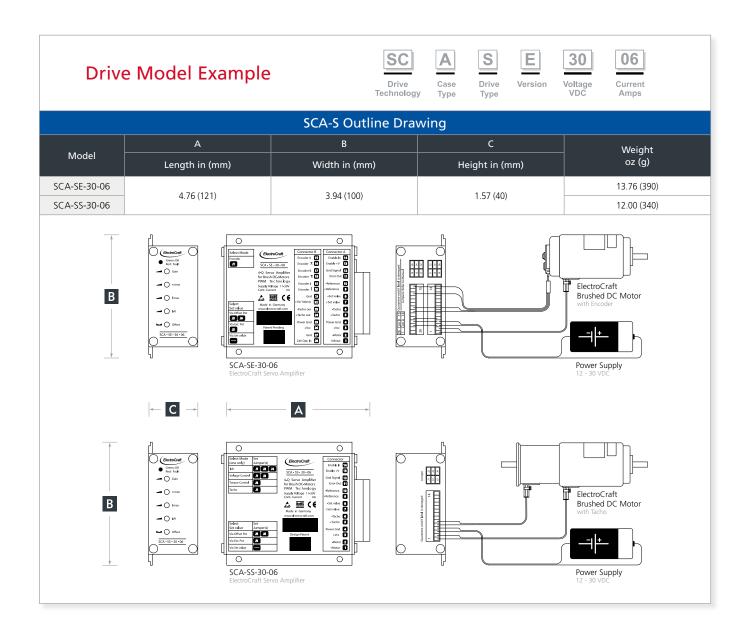
SCA-S: Electrocraft CompletePower™ | Servo Amplifier

Model	Power	Nominal Current	Quadrants	Operation Mode					
Supply					Analog	Speed Control			
	Voltage				Pos.	I x R Comp.	DC-Tacho	Voltage	Encoder
SCA-SE-30-06	11 – 30	6	4						•
SCA-SS-30-06	11 – 30	6	4	•		•	•	•	



For Brush-Commutated PMDC Motors. Up to 150 W.

This PWM four-quadrant brushless DC servo amplifier is fully enclosed in a rugged aluminum case which can be panel mounted for easy integration. The drive is available in several configurations depending on your control requirements. The drive handles continuous currents up to 6 Amps and is protected against over-current, over-temperature and motor short-circuit .



SCA-S Specifications								
Model Number	Power Supply Voltage (VDC)	Nominal Current (Amps)	Max. Po Heatsink	wer with (Watts)	Frequency of pov output stage (kF			
SCA-SE-30-06	11 - 30	6	1:	50	50	95		
SCA-SS-30-06	11 30	<u> </u>			30			
		C	ontrol Inputs					
	Set value			-10 to +10 VDC; Ri = 100 kOhm				
	Tacho			max. 50 VDC; Ri = 50 kOhm				
	Enable				+8 to +30 VDC; Ri	= 5 kOhm		
	Encoder input signals (S	CA-SE only)	Channe	el A & /A; B & /l	B; I & /I; max. 600 kHz ;	TTL/ +5 to +24 VDC; Ri > 10 kOhm		
			Outputs					
Auxiliary voltage source				+3.9 VDC / 20 mA				
Auxiliary voltage source				-3.9 VDC / 20 mA				
Auxiliary voltage source for encoder (SCA-SE only)				+5 VDC / 100 mA				
Auxiliary voltage source Enable +V				Connected with 27 kOhm to +VCC				
	Supervision output /Error				Open Collector max. +30 VDC; 20 mA			
			Display					
	LEDs				green = OK / red	= Fault		
		Po	otentiometer	s				
	Function of Potenti	ometer		Gain; nmax; lmax; lxR; Offset				
		Amb	pient condition	ons				
	Operation temperature (°C)				-10 to +45			
	Storage temperature (°C)				-40 to +85			
	Humidity Range Not Condensing (%rel)				20 to 80 % rel.			
		Mod	de of Operati	on				
SCA-SE-30-06	Speed-control by Digital-Encoder							
SCA-SS-30-06	Speed-control by voltage	e Torque-co	ntrol	IxR-c	compensation	Speed-control by DC-tacho		

Available Accessories for SCA-S (details see page 36)									
ASO-BM-70-30	ASX-RM-01-01	IA210x							



GO FIGURE.

Customize your options ...

To easily find a motor / motion system that best meets your needs:

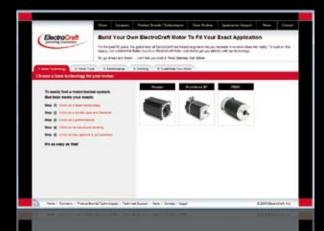
Step 1: Select a base technology

Step 2: Select a model type & features

Step 3: Select a performance

Step 4: Select an electrical winding

Step 5: Select any options & accessories



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System Matrix - Matching Linear Product and Drive Combinations

Linear Product			Drive Models							
	Motor P/N		Bipolar Stepper Drive PMDC Servo Drive							
	Imperial	Metric	SA4505	SA4510	SA4905	DA4303	DA4709	DA4718	SCA-LS-30-03	SCA-SS-30-06
		APPS11M-7A05	•		•					
		APPS11M-7A10	•		•					
		APPS11M-7A15	•		•					
		APPS11M-10A05	•		•					
		APPS11M-10A10	•		•					
		APPS11M-10A15	•		•					
	APPS17-29A10	APPS17M-21A10	•		•					
	APPS17-29A15	APPS17M-21A15	•		•					
	APPS17-29A20	APPS17M-21A20	•		•					
AxialPower	APPS17-47A10	APPS17M-33A10	•		•					
Stepper (APPS)	APPS17-47A15	APPS17M-33A15	•		•					
	APPS17-47A20	APPS17M-33A20	•		•					
	APPS17-58A10	APPS17M-41A10	•		•					
	APPS17-58A15	APPS17M-41A15	•		•					
	APPS17-58A20	APPS17M-41A20	•		•					
	APPS23-90A10	APPS23M-64A10	•		•					
	APPS23-90A20	APPS23M-64A20	•		•					
	APPS23-90A30	APPS23M-64A30	•		•					
	APPS23-150A10	APPS23M-106A10	•		•					
	APPS23-150A20	APPS23M-106A20	•		•					
	APPS23-150A30	APPS23M-106A30	•		•					
126	L3SAF-M200		•		•					
L3-Series Stepper	L3SAF-M300		•		•					
stepper	L3SAF-M500			•						
	APPD15-10V120	APPD15M-7V120						•		•
AxialPower	APPD15-10V240	APPD15M-7V240				•		•	•	
PMDC (APPD)	APPD25-30V120	APPD25M-21V120						•		
	APPD25-30V240	APPD25M-30V240					•			•



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- RapidPower™ I BLDC
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- SurePower™ I C-Frame AC



CompletePower™ I Drives



With meticulous engineering and advanced electronics, our CompletePower speed controls and servo drives offer reliability and precision servo motion control. From sensitive medical dosing systems to rugged professional power tools, our CompletePower devices can handle a wide variety of applications.

AxialPower™ I Linear Actuator



PMDC, and BLDC motors, our family of AxialPower linear actuators are built to last. Our unique approach to linear motion with low-friction, polymer rotating nuts and stainless steel leadscrews provides high force and linear precision in the smallest packages available.



TorquePower™ I Steppers



With non-cumulative position accuracies as low as ±3%, the precision of our TorquePower motor is matched only by the dependability of its performance. Bi-directional operation and enclosed, permanently lubricated ball bearings provide longlasting, smooth operation.

RapidPower™ I BLDC



Our BLDC motors provide the rapid acceleration and consistent speed needed for applications from centrifuges to x-y positioning systems. The RapidPower product line ensures a steady operation at any speed by utilizing sealed ball bearings and reduced torque ripple from skewed magnetization.

DirectPower™ I PMDC



Dynamically balanced armatures and precision ball bearings ensure that the DirectPower line maintains its characteristically smooth performance. This durable, totally enclosed, nonventilated (TENV) motor is available in a broad product line from lower cost, general purpose options to high performance PMDC servo motors.

MobilePower™ I Transmissions



With a choice of output ratios, our MobilePower line of products helps power battery-operated vehicles from wheelchairs to lift trucks. And, to increase durability and decrease noise levels, the robust all metallic gears are hobbed to a precision AGMA 9-Class.

SolidPower™ Plus I Housed AC



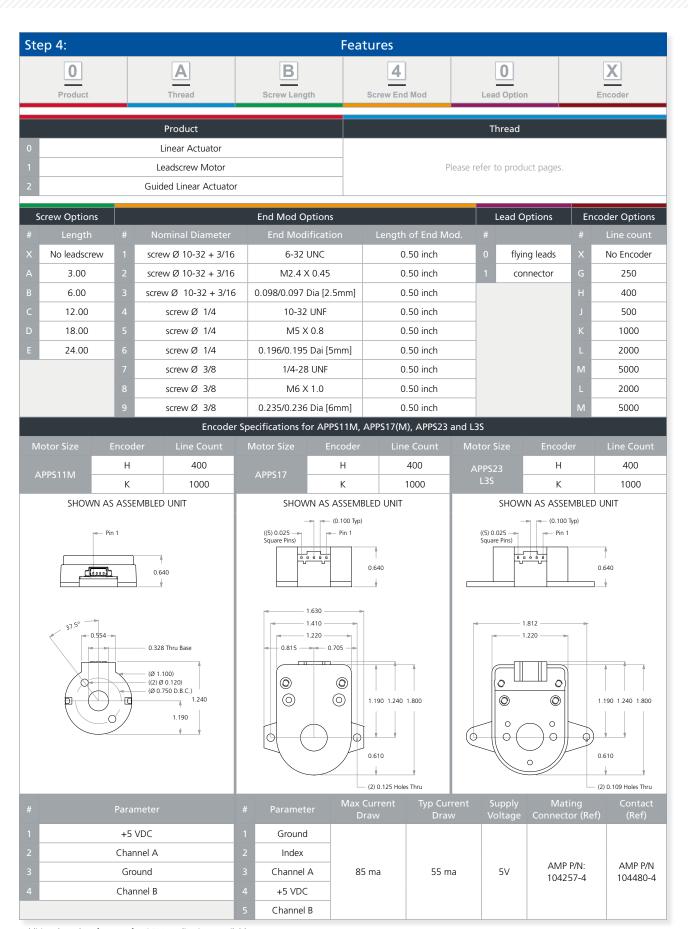
High starting torques and stator windings matched to your application ensure the SolidPower product provides lasting performance. The dynamically balanced, skewed rotor bars and precision-machined fits keep vibration levels at a minimum.

SurePower™ I C-Frame AC



Our AC shaded-pole motor, the SurePower product, can be utilized for a wide range of air-moving applications - perfect for the rigors of refrigeration and commercial food equipment applications.

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		Drive Ac	cessories				
		Patch	Cable				
	P/N	50cm	100cm	200cm	300cm		
	Red	CA2005	CA2010	CA2020	CA2030		
£ ,	Yellow	CA4005	CA4010	CA4020	CA4030		
	Gray	CA8005	CA8010	CA8020	CA8030		
	Aluminium Din Rail k	it		Braking module			
	Aluminium Din Rail kit with L-shaped bracket for units: SCA-Lx / SCA-Sx (not used for SCA-SS-70-30		The state of the s	Braking module in a rugged aluminium case. DA-Series SCA-Series	P/N ASO-BM-70-3		
	Passive heatsink			Passive heatsink			
	Passive heatsink optimized	for drives:	Passive heatsink optimized for drives:				
	DA43			SA45 SA49 DA47			
		P/N HA2008	_		P/N HA30		
	Fanned heatsink			Fanned heatsink			
	One fan heatsink optimizet (fan is 1 x 24 VDC, .8 W): DA43	l for drives	(1)	One fan heatsink optimized for (fan is 1 x 24 VDC, .8 W): SA45 SA49	r drives		
		P/N HA2018	_	DA47	P/N HA30		
	Fanned heatsink			Fanned heatsink			
	Two fan heatsink optimized (fans are 2 x 24 VDC, .8 W		C C C	Two fan heatsink optimized for (fans are 2 x 24 VDC, .8 W):	r drives		
		P/N HA2028		SA49 DA47	P/N HA31		
	Choke module	17N 11A2020		DIN Rail mounting kit	IMITAS		
		or DMDC drives					
0	Choke module optimized for Inductance: IA2100 = 2x50 Nominal current: 10 A			DIN Rail mounting kit for units: DA-Series			
	DA-Series		TI I	EA-Series			
	SCA-Series	P/N IA210x			P/N MA0		
	Break Out Board			DIN Rail mounting kit			
	Break Out Board for:		German	DIN Rail mounting kit for:			
	DA-Series EA-Series			ASO-BM-70-30			
		P/N WA2509	10.503		P/N MA30		