

# STAC6



**High performance AC Input stepper drives with advanced features & control options.**

- ✓ **Advanced Current Control**
- ✓ **Anti-Resonance**
- ✓ **Torque Ripple Smoothing**
- ✓ **Microstep Emulation**

## Specifications

### POWER SUPPLY:

STAC6 94-135 VAC  
STAC6-220 94-265 VAC

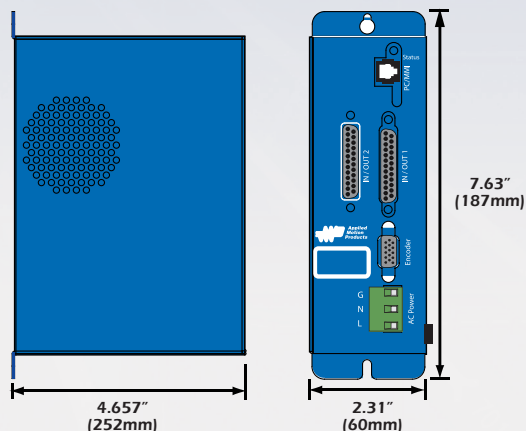
### OUTPUT CURRENT:

STAC6 0.5 - 6.0A Peak  
STAC6-220 0.5 - 3.2A Peak

### PROTECTION:

- Over-Voltage
- Under voltage
- Over-Temp
- External Output Shorts
- Regeneration

## Dimensions



## Models

*S*

- Pulse & Direction
- CW/CCW Pulse
- A/B Quadrature
- Analog Velocity (Oscillator) mode
- Host commands (SCL compatible)
- SiNet Hub compatible
- *ST Configurator™* software for setup

*Q*

- Stand-alone Operation
- *Q Programmer™* for programming
- Conditional Processing
- Math Functions
- Multi-tasking
- Register Manipulation
- Encoder Following
- Third HMI compatibility

*Si*

- *Si Programmer™* with built-in Configurator
- Point-and-click indexing software
- Friendly GUI
- I/O and motion programming
- MMI-01 compatibility

*C*

- CANopen protocols DS301 and DSP402
- Profile Position, Profile Velocity, and Homing modes
- Up to 127 axis per channel
- Execute stored Q programs

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# STAC6 technical specs.

## POWER AMPLIFIER SECTION

AMPLIFIER TYPE.....	MOSFET , Dual H-Bridge, 4 Quadrant
CURRENT CONTROL.....	4 state PWM at 20 Khz
OUTPUT CURRENT.....	STAC6                    0.5— 6.0 in 0.01 amp increments (6A peak of sine)
.....	STAC6-220            0.5— 3.2 in 0.01 amp increments (3.2A peak of sine)
POWER SUPPLY.....	STAC6                    Line operated nominal 120 VAC, 50/60 Hz
.....	STAC6-220            Line operated nominal 220 VAC, 50/60 Hz
AC INPUT VOLTAGE.....	STAC6                    94—135VAC, 50/60Hz
.....	STAC6-220            94—265VAC, 50/60Hz
PROTECTION.....	Over-voltage, under-voltage, over-temp, external output shorts (phase-to-phase, phase-to-ground), internal amplifier shorts
IDLE CURRENT REDUCTION.....	Reduction to any integer percent of full-current after delay selectable in milliseconds.
MOTOR REGENERATION.....	Built in regeneration circuit - 25 watts max.

## CONTROLLER SECTION

NON-VOLATILE STORAGE.....	Configurations are saved in FLASH memory on board the DSP.
STEP AND DIRECTION INPUTS.....	Optically Isolated: 5 Volt. Minimum pulse width = 200 ns. Maximum pulse frequency = 2 MHz
RESOLUTION.....	Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev
ANTI-RESONANCE.....	Raises the system damping ratio to eliminate midrange instability and allow stable operation throughout the speed range and improves settling time.
TORQUE SMOOTHING.....	Allows for fine adjustment of phase current waveform harmonic content to reduce low-speed torque ripple in the range 0.25 — 1.5 rps.
AUTO SETUP.....	Measures motor parameters and configures motor current control and anti-resonance gain settings.
SELF TEST.....	Checks internal & external power supply voltages, diagnoses open motor phases.
MICROSTEP EMULATION.....	Performs low resolution stepping by synthesizing fine microsteps from coarse steps.
COMMAND SIGNAL SMOOTHING.....	Software configurable filtering reduces jerk and excitation of extraneous system resonances (step & direction mode only).
ENCODER OPTION.....	Employs encoder (hi or low resolution) to provide failsafe stall detect and perform stall prevention and position maintenance. Differential line receivers suitable for 500 kHz or greater. Minimum encoder resolution is 1000 lines.
INTERFACE.....	RS-232 and RS-485 , CANopen standard on STAC6-C models.
AMBIENT TEMPERATURE.....	0 to 55 °C (32- 158 °F)
HUMIDITY.....	90% non-condensing

## INPUTS AND OUTPUTS

IN / OUT 1 connector - All Drives S, SE, Q, QE, Si, C

### 7 Inputs

X1, X2	Optically Isolated, Differential, 5 Volt. Minimum pulse width = 250ns. Maximum pulse, frequency = 2 MHz Function: Step & Direction, Encoder Following, Sensor, Home or Branch Select
X3	Optically isolated, 12 - 24V, sourcing or sinking. Function: Motor Enable, Sensor, Home or Branch Select
X4	Optically isolated, 12 - 24V, sourcing or sinking. Function: Alarm Reset, Sensor, Home or Branch Select
X5	Optically isolated, 12 - 24V. Function. Function; general Purpose Input.
X6,X7	Optically isolated, 12 - 24V. Function: CW & CCW Limits, Sensor, Home or Branch Select

### 3 Outputs

Y1	Optical darlington, 30V, 100mA max, NPN/sinking, shared common with Y2 & Y3. Function: Brake or general purpose programmable
Y2	Optical darlington, 30V, 100mA max, NPN/sinking, shared common with Y1 & Y3. Function: Motion, tach or general purpose programmable
Y3	Optical darlington, 30V, 100mA max, NPN/sinking, shared common with Y1 & Y2. Function: Fault or general purpose programmable

### Analog Inputs

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## STAC6 technical specs (cont)

Software selectable: 0-5V, ±5V, 0-10V, ±10V  
 RESOLUTION 12 bits (with ±10V signal range)  
 11 bits (with 0-10V or ±5V signal range)  
 10 bits (with 0-5V signal range)

IN / OUT 2 connector - SE, QE and Si

8 digital Inputs

IN1-IN6 Optically isolated, 12 - 24V. Function. Function; general Purpose Input.  
 IN7/IN8 Optically isolated, differential. 12 - 24V. Function; general Purpose Input.

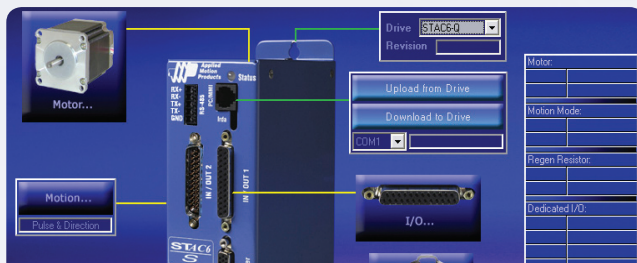
4 DigitalOutputs

OUT 1-4 Optical darlington, 30V, 100mA max, sinking or sourcing. Function: general purpose programmable

1 Analog Input

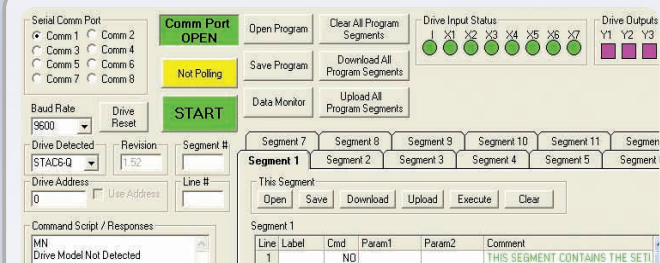
0-5VDC analog input - for use with Q or SCL software only

## Software



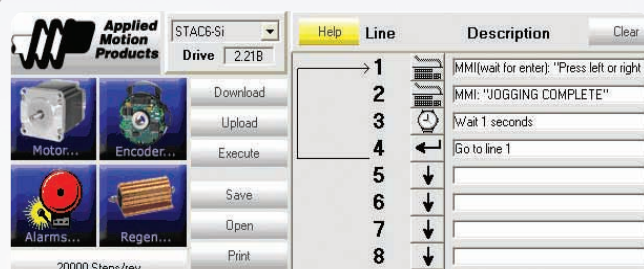
### ST Configurator™

Used for setup, configuration, uploading and downloading programs to the STAC6. For more information about the *ST Configurator™* visit the STAC6 webpage: [applied-motion.com/STAC6](http://applied-motion.com/STAC6)



### Q Programmer™

*Q Programmer™* is used to create and edit stand-alone programs for Q-compatible drives. The functions of these drives include multi-tasking, math, register manipulation, encoder following, and more.



### Si Programmer™

Intended for use in stand-alone applications, *Si Programmer™* provides a friendly, point-and-click, graphical interface that doesn't require any previous programming experience.



### Help Manuals - "Printable Pages"

*ST Configurator™* incorporates new help menus. All the technical data, application information and advice on setting up the drive is now just a mouse click away.

Runs on IBM-compatible PC's running Windows 7, XP, Vista, 2000, NT, ME, 98.

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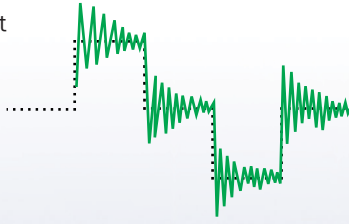
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### Anti Resonance

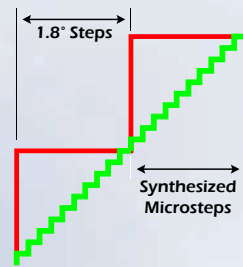
Step motor systems have a natural tendency to resonate at certain speeds. The STAC6 drives automatically calculate the system's natural frequency and apply damping to the control algorithm. This greatly improves midrange stability, allows higher speeds and greater torque utilization, and also improves settling times.



**Delivers better motor performance and higher speeds**

### Micro Step Emulation

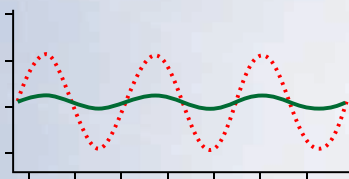
With Microstep Emulation, low resolution systems can still provide smooth motion. The drive can take low-resolution step pulses and create fine resolution micro-step motion.



**Allows the use of PLC type pulse trains**

### Torque Ripple Smoothing

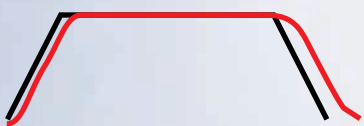
All step motors have an inherent low speed torque ripple that can affect the motion of the motor. By analyzing this torque ripple the system can apply a negative harmonic to negate this effect, which gives the motor much smoother motion at low speed.



**Smooth, even motion from a stepper system**

### Command Signal Smoothing

Command Signal smoothing can soften the effect of immediate changes in velocity and direction, making the motion of the motor less jerky. An added advantage is that it can reduce the wear on mechanical components.



**Assures smooth acceleration/deceleration ramps**

### Self Test & Auto Setup

At start-up the drive measures motor parameters, including the resistance and inductance, then uses this information to optimize the system performance. The drive can also detect open and short circuits.

### Inputs & Outputs

S	Q	Si	C
7 digital inputs 3 digital outputs 2 analog inputs	7 digital inputs 3 digital outputs 2 analog inputs	15 digital inputs 7 digital outputs	7 digital inputs 3 digital outputs 2 analog inputs

**CANopen**

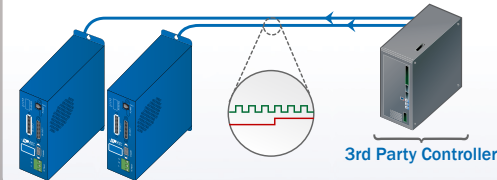
### Power Ratings

	STAC6	STAC6-220
Input Voltage:	94-135 VAC	94-265 VAC
Output Current:	6.0A Peak	3.2A Peak

For more information go to [www.applied-motion.com/STAC6](http://www.applied-motion.com/STAC6)

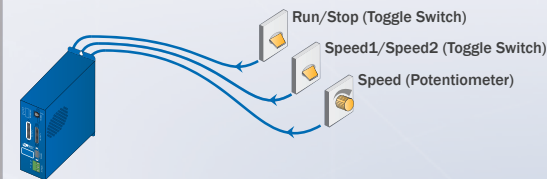


### Step & Direction



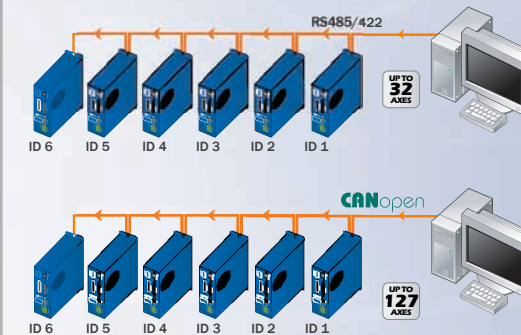
- Step & Direction
- CW & CCW Pulse
- A/B Quadrature

### Oscillator / Run-Stop



- Software Configuration
- Two Speeds
- Vary speed with analog input
- Joystick Compatible

### Host Control

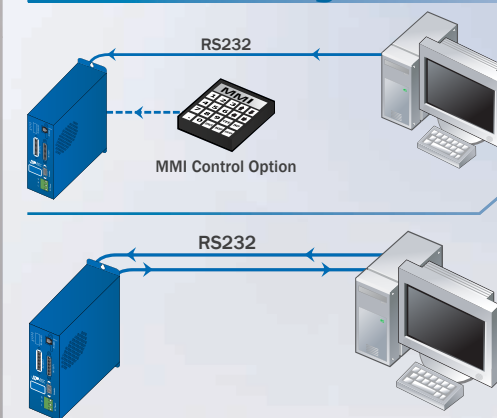


- Accepts Host Commands from PC or PLC
- Multi-axis Capable
- Real Time Control



- Connect to CANopen network
- DS301 and DSP402 protocols

### Stand Alone Programmable



- Point & Click Graphical Interface
- Download, store & execute programs
- MMI Option

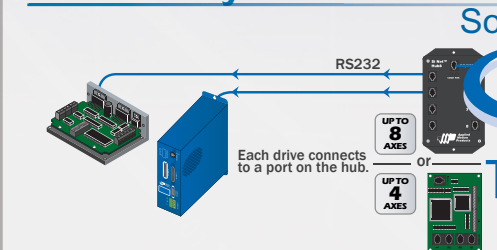


- Comprehensive text based language
- Download, store & execute programs
- High Level Features
  - Multi Tasking
  - Conditional Programming
  - Math Functions
- Host interface while executing internal programs

### Q over CANopen

The STAC6 drive with the CANopen option board has the unique ability to access, modify and trigger a program stored on the drive. The user develops and downloads a program using the Q programmer™ software. The program sequences can then be triggered via the CANopen network, creating a powerful distributed motion control system.

### Multi axis Systems

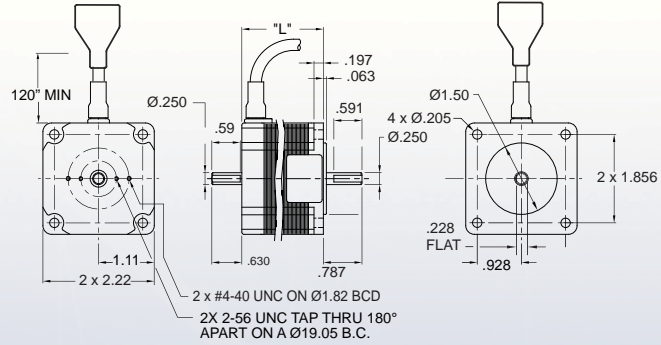


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 Use SiNet Hub Programmer software to develop your sequence of events, then download them to the hub for a stand alone system or send serial commands to the drives from a PLC, PC, HMI, or other host controller.  
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# STAC6 NEMA 23 Motors

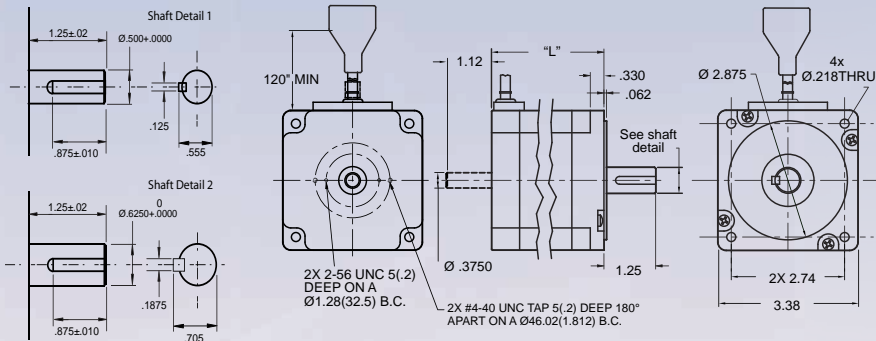


MOTOR PART NO.	STAC6 (120)		STAC6-220		HOLDING TORQUE oz-in	ROTOR INERTIA oz-in-sec <sup>2</sup>	MOTOR LENGTH inch (mm)
	Connection	Drive Current Setting amps/phase	Connection	Drive Current Setting amps/phase			
HT23-552	parallel	1.50	series	0.75	84.4	1.70E-03	1.71 (43.5)
HT23-553	parallel	1.50	series	0.75	167	4.25E-03	2.17 (55)
HT23-554	parallel	1.80	series	0.90	255	6.80E-03	3.05 (77.5)

Notes -

- 1) Drawing shown with optional rear shaft.
- 2) Encoder holes only on dual shaft version.
- 3) The "Drive Current Setting" shown here differs from the rated current of each motor because the rated current is RMS and the drive current setting is peak sine.
- 4) These motors include a 10ft cable.

# STAC6 NEMA 34 Motors



MOTOR PART NO.	STAC6 (120)		STAC6-220		HOLDING TORQUE oz-in	ROTOR INERTIA oz-in-sec <sup>2</sup>	MOTOR LENGTH inch (mm)	FRONT SHAFT DIAMETER inch (mm)
	Connection	Drive Current Setting amps/phase	Connection	Drive Current Setting amps/phase				
HT34-495	parallel	5.10	series	2.55	555	2.27E-02	3.11 (79)	0.5 (12.7)
HT34-496	parallel	5.10	series	2.55	1110	4.53E-02	4.63 (117.5)	0.5 (12.7)
HT34-497	parallel	5.80	series	3.20	1694	6.80E-02	6.14 (156)	0.625 (15.875)

Notes -

- 1) Drawing shown with optional rear shaft.
- 2) Encoder holes only on dual shaft version.
- 3) The "Drive Current Setting" shown here differs from the rated current of each motor because the rated current is RMS and the drive current setting is peak sine.
- 4) These motors include a 10ft cable.

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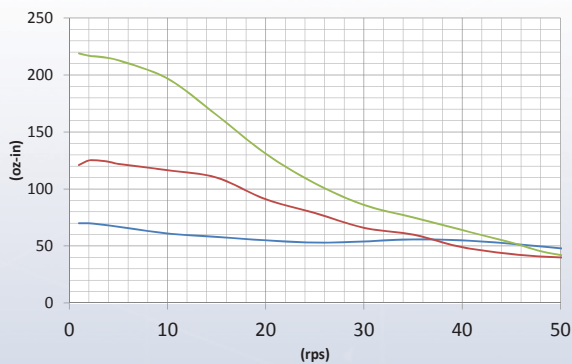


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# STAC6 - TORQUE CURVES

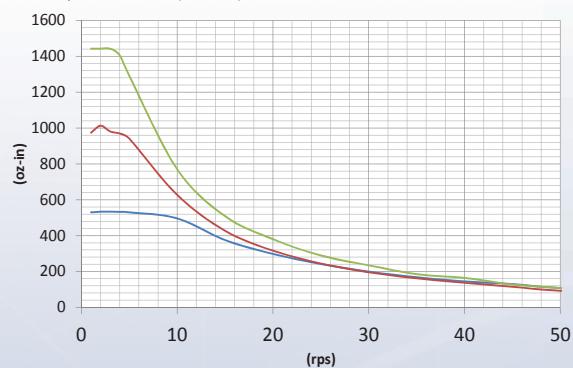
HT23-552/553/554, STAC6 (120)

Connection: parallel  
Step resolution: 1/100 (20,000 s/r)



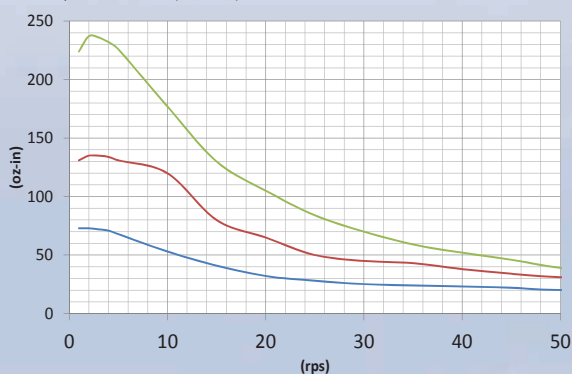
HT34-495/496/497, STAC6 (120)

Connection: parallel  
Step resolution: 1/100 (20,000 s/r)



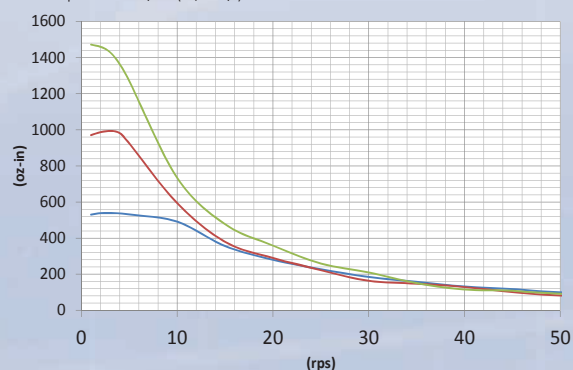
HT23-552/553/554, STAC6-220

Connection: series  
Step resolution: 1/100 (20,000 s/r)



HT34-495/496/497, STAC6-220

Connection: series  
Step resolution: 1/100 (20,000 s/r)



## Option - Encoder

With the addition of an encoder on the motor the STAC6 can provide additional functions:

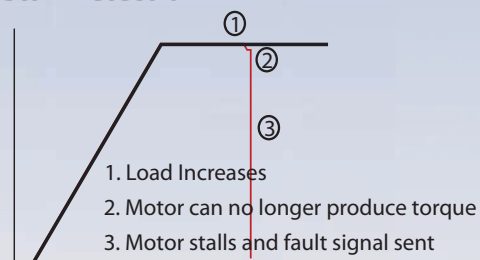
- Stall Detection:** If an external force or increased load is placed on the system, the motor will reach a point at which it can no longer produce sufficient torque. At this point the motor will stall and stop rotating – a basic step motor system will not know this has happened and will assume the move has been completed. With the addition of an encoder on the motor the STAC6 can detect this stall and generate a fault signal which can be sent to an output, or used within the Q or Si program to branch to a fault handling routine.

- Stall Prevention:** If at some point during a motor's pre-programmed move the load on the system increases, the drive will detect that the lead angle of the motor is lagging. This may otherwise cause the motor to stall due to the lack of available torque.

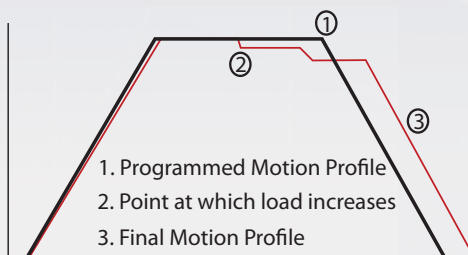
The Stall Prevention feature of the drive reduces the motor's velocity (step motors have more torque at lower speeds) so that it can continue with the move. In this way the correct move distance is achieved, though the move has taken longer than programmed.

- Position Maintenance:** When a motor is at zero speed holding position, it is possible for external forces to move the load out of position. With an encoder and position maintenance, this position error will be detected and the motor moved back to its correct position once the external force is removed.

### Stall Detection



### Stall Prevention



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## Other Products

### Stepper Drives & Motors

Stepper drives are offered in both open frame (DC input) and packaged versions (AC input), in full/half step and microstepping versions.

**Stepper Drives:** <http://www.applied-motion.com/products/stepper-drives>

**Stepper Motors:** <http://www.applied-motion.com/products/stepper-motors>

**Integrated Steppers:** <http://www.applied-motion.com/products/integrated-steppers>



### Servo Drives & Motors

Servo motors and drives from 50W to 1000W offered in AC and DC powered versions with options for host communication or Stand-alone control.

**Servo Drives:** <http://www.applied-motion.com/products/servo-drives>

**Servo Motors:** <http://www.applied-motion.com/products/servo-motors>



### Gearheads

Applied Motion offers a full range of planetary gearheads to compliment the offering of servo motors and step motors.

<http://www.applied-motion.com/products/gearheads/>



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