

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a CANopen interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare® 7, available for download at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Range	
Peak Current	30 A (21.2 A _{RMS})
Continuous Current	15 A (10.6 A _{RMS})
Supply Voltage	200 - 480 VAC



Features

- ▲ Four Quadrant Regenerative Operation
- Space Vector Modulation (SVM) Technology
- ✓ Fully Digital State-of-the-art Design
- Programmable Gain Settings
- Fully Configurable Current, Voltage, Velocity and Position Limits
- PIDF Velocity Loop

- ✓ PID + FF Position Loop
- Compact Size, High Power Density
- ▲ 16-bit Analog to Digital Hardware
- Built-in brake/shunt regulator
- Internal brake/shunt resistor
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching

MODES OF OPERATION

- Profile Current
- Profile Velocity
- Profile Position
- Cyclic Synchronous Current Mode
- Cyclic Synchronous Velocity Mode
- Cyclic Synchronous Position Mode

COMMAND SOURCE

- ±10 V Analog
- PWM and Direction
- Encoder Following
- Over the Network
- Sequencing
- Indexing
- Jogging

FEEDBACK SUPPORTED

- ±10 VDC Position
- Auxiliary Incremental Encoder
- Heidenhain EnDat®
- Stegmann Hiperface®
- Tachometer (±10 VDC)

INPUTS/OUTPUTS

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 1 Programmable Analog Output (10-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

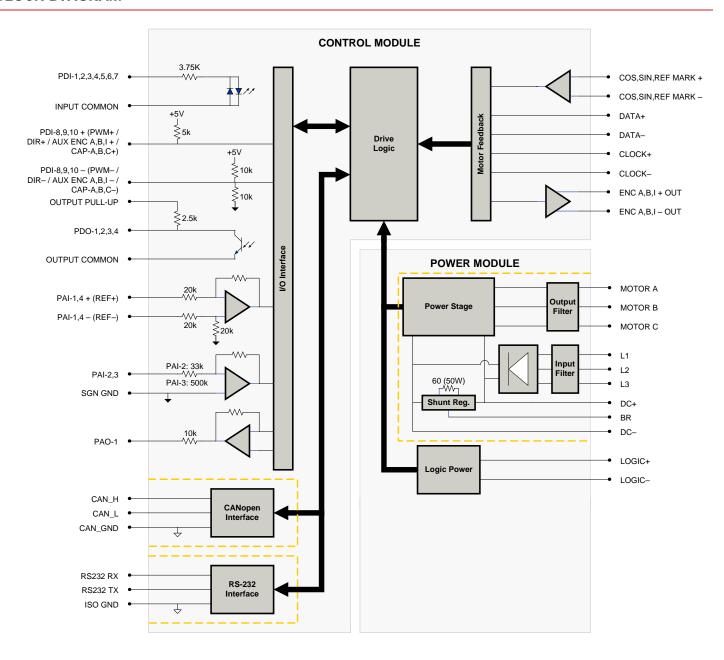
Sold & Serviced By: COMPLIANCES & AGENCY APPROVALS

ELECTROMATECE Class A (LVD)
CE Class A (EMC)

Toll Free Phone (877) SERVQ98 RoHS
Toll Free Fax (877) SERV099
www.electromate.com
sales@electromate.com



BLOCK DIAGRAM



Information on Approvals and Compliances



Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock.



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and section equipment.



Toll Free Phone (877) SERV098 Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com



SPECIFICATIONS

5		Power Specifications
Description Rated Voltage	Units VAC (VDC)	Value 480 (678)
AC Supply Voltage Range	VAC (VDC)	200 - 480
AC Supply Voltage Kange AC Supply Minimum	VAC	180
AC Supply Maximum	VAC	528
AC Input Phases	VAC	3
AC Supply Frequency	Hz	50 - 60
DC Supply Voltage Range ¹	VDC	255 - 747
DC Bus Over Voltage Limit	VDC	850
DC Bus Under Voltage Limit	VDC	230
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)
Maximum Peak Output Current ²	A (Arms)	30 (21.2)
Maximum Continuous Output Current	A (Arms)	15 (10.6)
Max. Continuous Output Power @ Rated Voltage ³	W (Allis)	6840
Max. Continuous Power Dissipation @ Rated Voltage	W	360
Internal Bus Capacitance	μF	330
External Shunt Resistor Minimum Resistance	μι -	
		Contact factory before using an external shunt resistor 3000
Minimum Load Inductance (Line-To-Line) ⁴	μH kHz	10
Switching Frequency Maximum Output PWM Duty Cyclo	KHZ %	100
Maximum Output PWM Duty Cycle Low Voltage Supply Outputs	- %	+5 VDC (250 mA)
Low voltage Supply Outputs		
Description	Units	Control Specifications Value
Communication Interfaces	-	CANopen (RS-232 for configuration)
Command Sources	-	±10 V Analog, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Heidenhain EnDat®, Stegmann Hiperface®, Tachometer (±10 VDC)
Commutation Methods	-	Sinusoidal
Modes of Operation	-	Profile Current, Profile Velocity, Profile Position, Cyclic Synchronous Current Mode, Cyclic Synchronous Velocity Mode, Cyclic Synchronous Position Mode
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/1
Primary I/O Logic Level	-	24 VDC
Current Loop Sample Time	μs	100
Velocity Loop Sample Time	μs	200
Position Loop Sample Time	μs	200
Maximum Sin/Cos Encoder Frequency	kHz	200
Maximum Sin/Cos Interpolation	-	2048 counts per sin/cos cycle
Internal Shunt Regulator	-	Yes
Internal Shunt Resistor	-	Yes
	Me	chanical Specifications
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), RoHS
Size (H x W x D)	mm (in)	300.5 x 232.1 x 91.8 (11.8 x 9.1 x 3.6)
Weight	g (oz)	5437 (191.8)
Heatsink (Base) Temperature Range ⁵	°C (°F)	0 - 75 (32 - 167)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
Cooling System	-	Natural Convection
IP Rating	-	IP10
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header
AUX COMM Connector	-	3-pin, 2.5 mm spaced, enclosed, friction lock header
AUX ENCODER Connector	-	15-pin, high-density, male D-sub
COMM Connector		Shielded, dual RJ-45 socket with LEDs
DC BUS Connector		4-port, 7.62 mm spaced, enclosed, friction lock header
FEEDBACK Connector	-	15-pin, high-density, female D-sub
I/O Connector	-	26-pin, high-density, female D-sub
MOTOR POWER Connector	Sold &	Servipsel Bg2 mm spaced, enclosed, friction lock header
		E1-port 7.12 prints are a enclosed, friction lock header

Notes

- DC supply operation through the L1, L2, or L3 terminals will reduce the Kidot Power range by Story See Installation manual for details.

 Capable of supplying drive rated peak current for 2 seconds with 10 reduced to comply observations of the same possible with lower current limits. P = (DC Rated Voltage) * (Cont. RMS Current) * 0.95.

 Lower inductance is acceptable for bus voltages well below maximum. Use Very Control of Con



PIN FUNCTIONS

	+24V LOGIC - Logic Power Connector		
Pin	Name	Description / Notes	1/0
1	LOGIC PWR	Logic Supply Input	I
2	LOGIC GND	Logic Supply Ground	GND

	AUX COMM - RS232 Communication Connector			
Pin	Name	Description / Notes	I/O	
1	RS232 RX	Receive Line (RS-232)	I	
2	RS232 TX	Transmit Line (RS-232)	0	
3	ISO GND	Isolated Signal Ground	IGND	

	AUX EI	NCODER - Auxiliary Feedback Connector	
Pin	Name	Description / Notes	1/0
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)	Single-Ended Signals Leave Negative Terminal Open)	I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)	(For Single-Ended Signals Leave Negative Terminal Open)	
8	PDI-10 + (AUX ENC I+ / CAP-A+)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended	I
9	PDI-10 - (AUX ENC I- / CAP-A-)	Signals Leave Negative Terminal Open)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-4 +	Differential Programmable Angles Input (42 bit Becelution)	I
15	PAI-4 -	Differential Programmable Analog Input (12-bit Resolution)	

	COMM - CAN Communication Connector			
Pin	Name	Description / Notes	1/0	
1	CAN_H	CAN_H Line (Dominant High)	I	
2	CAN_L	CAN _L Line (Dominant Low)	I	
3	CAN_GND	CAN Ground	CGND	
4	RESERVED	Reserved	-	
5	RESERVED	Reserved	-	
6	RESERVED	Reserved	-	
7	CAN_GND	CAN Ground	CGND	
8	RESERVED	Reserved	-	

	DC BUS - Power Connector ¹		
Pin	Name	Description / Notes	1/0
1	DC-	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	I/O
2	2 BR External Brake Resistor Connection -		-
3	DC+	Brake Resistor DC+. Connection for brake resistor.	0
4	DC+	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	I/O

^{1.} Contact factory before using an external shunt regulator or brake resistor.

Sold & Serviced By:

ELECTROMATE



		FEEDBACK - Feedback Connector	
Pin	Name	Description / Notes	1/0
1	COS+	Cosine Input	I
2	COS -	Cosine input	I
3	SIN +	Sine Input	I
4	SIN -	Sine input	I
5	SGN GND	Signal Ground	SGND
6	DATA-	Differential Data Line	I/O
7	DATA+	Diliciential Data Line	I/O
8	CLOCK+	Differential Clock Line	0
9	CLOCK-	Differential Clock Line	0
10	REF MARK +	Reference mark from sine/cosine encoder	I
11	RESERVED	Reserved	-
12	RESERVED	Reserved	-
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	REF MARK -	Reference mark from sine/cosine encoder	I

		I/O - Signal Connector	
Pin	Name	Description / Notes	1/0
1	PDO-1	Isolated Programmable Digital Output	0
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	0
4	PAI-1 + (REF+)	D''' 5 1 D 1 1 A 1 A 1 A 1 A 1 A 1 A 1 A 1 A 1	I
5	PAI-1 - (REF-)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	PAO-1	Programmable Analog Output (10-bit Resolution)	0
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	0
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	0
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4	Isolated Programmable Digital Input	I
18	PDI-6	Isolated Programmable Digital Input	I
19	PDI-7	Isolated Programmable Digital Input	I
20	ENC A+ OUT	5 1 1 1 5 1 0 1 1 0 1 1	0
21	ENC A- OUT	Emulated Encoder Channel A Output	0
22	ENC B+ OUT	Frederick Freedom Observal B Outset	0
23	ENC B- OUT	Emulated Encoder Channel B Output	0
24	ENC I+ OUT	Familiate d Familia Indian Outside	0
25	ENC I- OUT	Emulated Encoder Index Output	0
26	SGN GND	Signal Ground	SGND

	MOTOR POWER - Power Connector			
Pin	Name	Description / Notes	1/0	
1	SHIELD	Motor cable shield. Internally connected to protective earth ground.	-	
2	MOTOR C	Motor Phase C	0	
3	MOTOR B	Motor Phase B	0	
4	MOTOR A	Motor Phase A	0	

	POWER - Power Connector		
Pin	Name	Description / Notes	1/0
1	L3		I
2	L2	AC Supply Input (Three Phase)	I
3	L1		I

Sold & Serviced By:



Toll Free Phone (877) SERV098 Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com



HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	ting
	Description	On	Off
1	Bit 0 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0

Additional Details

The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Bit Rate (kbits/sec)	Value For Bit Rate Setting
Load from non-volatile memory	0
500	1
250	2
125	3

Jumper Settings

Jumper	Description		Configuration	
	Header Jumper	Not Installed	Pins 1-2	Pins 2-3
J1	CAN bus termination. Install this jumper (2.54mm) on the last drive in a CAN network. This jumper is located on a 4-pin header adjacent to the RS-232 connector. It consists of the two pins furthest from the connector.	Non- terminating Node	Terminating Node	N/A
J2	Reserved.	-	-	N/A

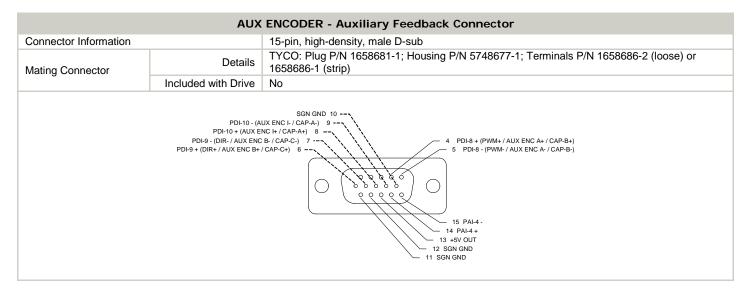




MECHANICAL INFORMATION

+24V LOGIC - Logic Power Connector		
Connector Information		2-port, 5.08 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1757019
	Included with Drive	Yes
LOGIC GND 1 LOGIC PWR		

AUX COMM - RS232 Communication Connector		
Connector Information		3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix: Plug P/N 1881338
	Included with Drive	Yes
3 ISO GND 2 RS232 TX 1 RS232 RX		







COMM - CAN Communication Connector		
Connector Information Shielded, dual RJ-45 socket with LEDs		
Mating Connector	Details	AMP: Plug P/N 5-569552-3
Mating Connector	Included with Drive	No
A CAN_GND 7 CAN_GND 3 CAN_L 2 CAN_L 1 T CAN_GND T CAN_GND		

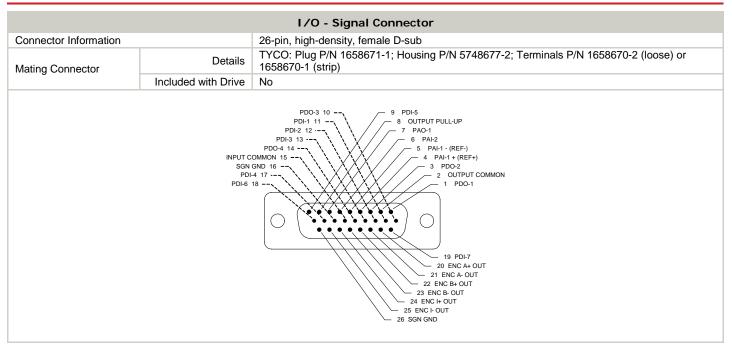
DC BUS - Power Connector		
Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804920
Mating Connector	Included with Drive	Yes
Included with Drive Yes		

FEEDBACK - Feedback Connector			
Connector Information 15-pin, high-density, female D-sub		15-pin, high-density, female D-sub	
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)	
	Included with Drive	No	
	DATA- 6 5 SGN GND CLOCK+ 8 2 COS - REF MARK + 10 1 COS + 13 +5V OUT 14 PAL3 15 REF MARK -		



Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com





MOTOR POWER - Power Connector			
Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header	
Mating Connector	Details	Phoenix Contact: P/N 1804920	
Mating Connector	Included with Drive	Yes	
Included with Drive Yes			

POWER - Power Connector		
Connector Information		3-port, 7.62 mm spaced, enclosed, friction lock header
Moting Connector	Details	Phoenix Contact: P/N 1804917
Mating Connector	Included with Drive	Yes
1 L3 L1 L3		

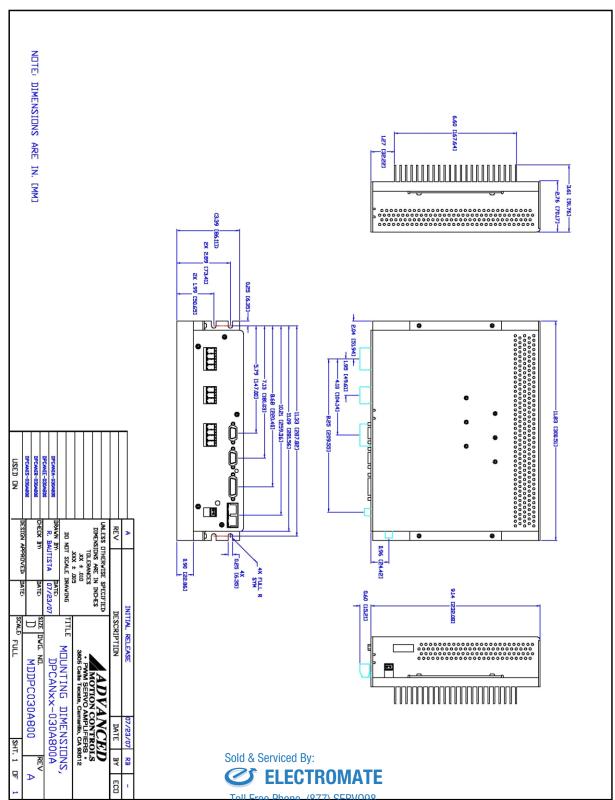




Toll Free Phone (877) SERV098 Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com



MOUNTING DIMENSIONS

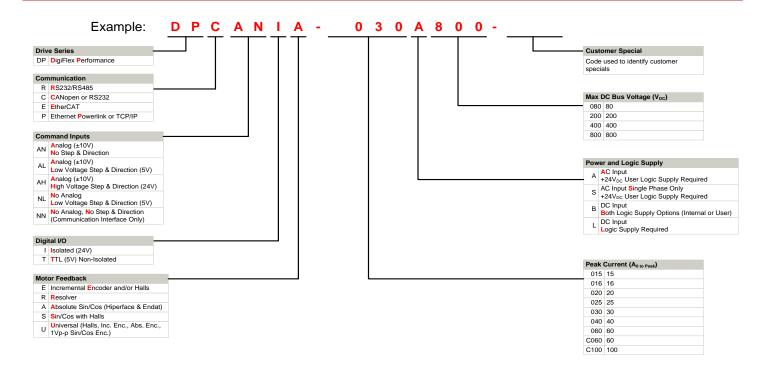


Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com

To Motor



PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quickturn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- Optimized Footprint
- Private Label Software
- **OEM Specified Connectors**
- No Outer Case
- **Increased Current Resolution**
- Increased Temperature Range
- Custom Control Interface
- Integrated System I/O

- Tailored Project File
- 4 Silkscreen Branding
- Optimized Base Plate
- **Increased Current Limits**
- Increased Voltage Range
- Conformal Coating 4
- Multi-Axis Configurations 4
- Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



www.electromate.com