

# MC1XZBHE

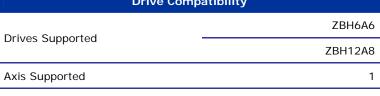


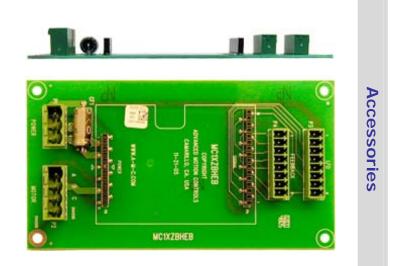
Features	Drive Compatibility

- Mounts ZBH type drives
- On-board bus capacitance
- Screw terminal mating connectors included
- Standard DIN tray dimensions

Single axis mounting card

All detachable connections





#### Description

The MC1XZBHE mounting card is designed to host a ZBH type servo This mounting card offers convenient quick-disconnect connectors (mating screw terminals included) for easy interfacing.





# **SPECIFICATION SUMMARY**

Mechanical Specifications	
Drive Power Connector: P1	3-port, 5.08 mm spaced insert connector
Motor Power Connector: P2	4-port, 5.08 mm spaced insert connector
Input/Output Connector: P3	8-port, 3.5 mm spaced insert connector
Feedback Connector: P4	8-port, 3.5 mm spaced insert connector
Mounting Signal Connector: PA	16-pin, 2.54 mm pitch socket
Mounting Power Connector: PB	12-pin, 2.54 mm pitch socket
Size (L x W x H)	5.22 x 2.48 x 0.56 inches 132.5 x 63.0 x 14.3 mm
Weight	(TBA)

# **PIN FUNCTIONS**

	P1 - Drive Power Connector		
Pin	Name	Description	1/0
1	N/C	Not Connected	-
2	GND	Ground	GND
3	+HV	DC motor power input. This input is used to supply power to the motor.	I

P2 - Motor Power Connector			
Pin	Name	Description	1/0
1	MOTOR A	Motor phase A	0
2	MOTOR B	Motor phase B	0
3	MOTOR C	Motor phase C	0
4	CHASSIS	Chassis	PE

P3 - Input/Output Connector			
Pin	Name	Description	1/0
1	REF+ IN	Positive terminal of differential analog input	I
2	GROUND	Ground	GND
3	REF- IN	Negative terminal of differential analog input	I
4	CURRENT MONITOR	Output voltage proportional to motor output current. Scaling: 3.85 A/V.	0
5	INHIBIT IN	Inhibit/enable input.	I
6	CURRENT REFERENCE	Monitors the signal at the input of the internal current amplifier stage. Scaling: 1.6 A/V.	0
7	FAULT OUT	Logic output for indication of a drive fault.	0
8	OFFSET	Connection to external resistance for command offset adjustments.	-





P4 – Feedback Connector			
Pin	Name	Description	1/0
1	RESERVED	Reserved.	I
2	RESERVED	Reserved.	I
3	VELOCITY MONITOR	When used in current or Hall velocity mode, voltage is proportional to the speed of the motor. In open-loop mode, voltage is proportional to the PWM duty cycle.  Scaling: 100 Hz/V	GND
4	HALL 1		I
5	HALL 2	Hall sensor inputs for commutation.	I
6	HALL 3		I
7	GND	Ground	GND
8	+5V	5V output from 5V logic supply	0

## PA - Mounting Signal Connector

This connector mates directly to the drive. For pin functions refer to the drive datasheet.

## **PB – Mounting Power Connector**

This connector mates directly to the drive. For pin functions refer to the drive datasheet.

# **CONNECTOR INFORMATION**

P1 – Drive Power Connector	
Connector Information	3-port, 5.08 mm spaced insert connector
Mating Connector Example	Phoenix Contact: P/N 1757022 or 1777293 (vertical screw terminal)
	2 GND

P2 – Motor Power Connector	
Connector Information	4-port, 5.08 mm spaced insert connector
Mating Connector Example	Phoenix Contact: P/N 1757035 or 1777303 (vertical screw terminal)
	4 CHASSIS  3 MOTOR C  2 MOTOR B  1 MOTOR A





P3 - Input/Output Connector	
Connector Information	8-port, 3.5 mm spaced insert connector
Mating Connector Example	Phoenix Contact: P/N 1840421
	5 INHIBIT IN  6 CURRENT REFERENCE  7 FAULT OUT  8 OFFSET  4 CURRENT MONITOR  3 REF- IN  2 GROUND  1 REF+ IN

P4 - Feedback Connector	
Connector Information	8-port, 3.5 mm spaced insert connector
Mating Connector Example	Phoenix Contact: P/N 1840421
	5 HALL 2 6 HALL 3 7 GND 7 8 +5V 8 8 8 8 8 8 8 8 8 4 HALL 1 3 VELOCITY MONITOR 2 RESERVED 1 RESERVED

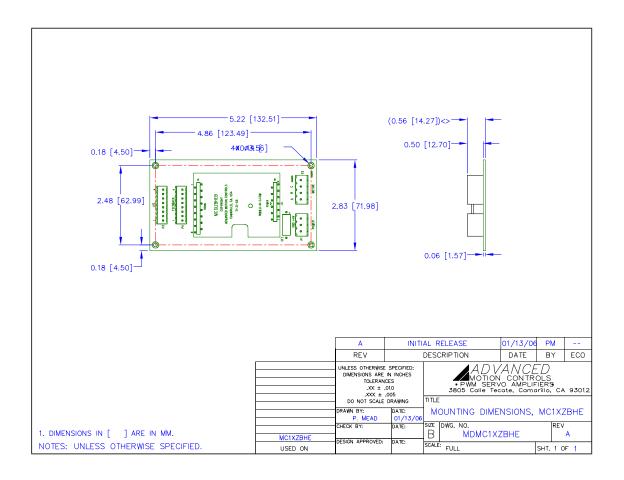
P1 - Mounting Signal Connector	
Connector Information 16-pin, 2.54 mm pitch socket	
Mating Connector Example No mating connector required. Mate directly to drive.	

P2 - Mounting Power Connector	
Connector Information 12-pin, 2.54 mm pitch socket	
Mating Connector Example No mating connector required. Mate directly to drive.	

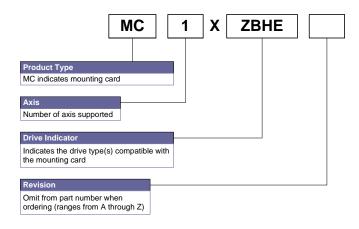




#### MOUNTING DIMENSIONS



## **ORDERING INFORMATION**



#### Notes:

Revision

