Description

The MC1XDZPC01 mounting card is designed to host a DZCANTU series $DigiFlex^{\otimes}$ PerformanceTM digital servo drive. The drive plugs into the bottom side of the mounting card, providing a compact assembly with connectors and switches readily accessible. The MC1XDZPC01 is ideal for prototyping and integrating a DZCANTU series digital servo drive in your machine.

The MC1XDZPC01 utilizes side-entry right angle fixed screw terminals for the motor and power connectors, quick-disconnect signal, feedback, communication connectors.

DZCANTU series Digiflex[®] Performance[™] digital servo drives communicate on a CANopen network.

Drive Compatibility

DZCANTU Drive Models

80V Drive Models 175V Drive Models

40A

20A

20A



Features

- Mounts DZCANTU DigiFlex® Perfomance™ Digital Servo Drives
- Single Axis Mounting Card

On-board CANopen Transceiver for CANopen Communication

DRIVES SUPPORTED

- DZCANTU-020B080
- DZCANTU-040B080
- DZCANTU-020B200

FEEDBACK SUPPORTED (DRIVE FIRMWARE **DEPENDENT)**

- Incremental Encoder
- Auxiliary Incremental Encoder
- Hall Sensors
- 1Vp-p Sine/Cosine Encoder
- Absolute Encoder (Heidenhain EnDat® or Stegmann Hiperface®)
- ±10 VDC Position
- Tachometer (±10 VDC)

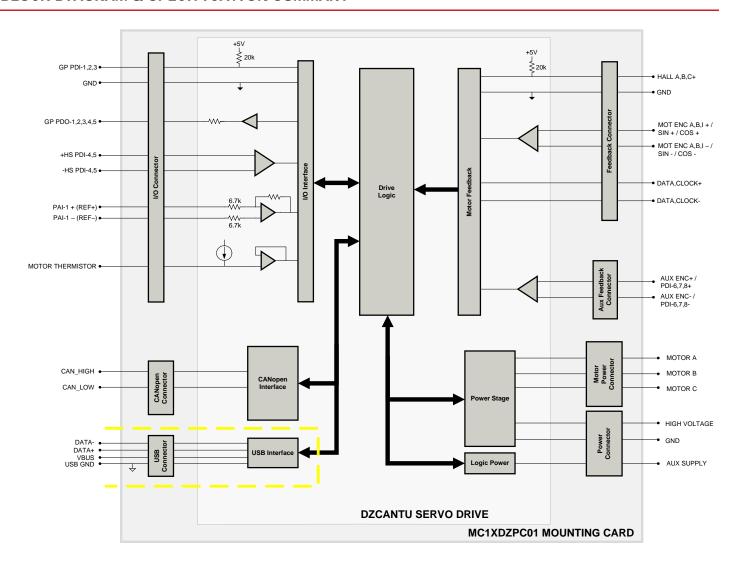
COMPLIANCES & AGENCY APPROVALS

RoHS





BLOCK DIAGRAM & SPECIFICATION SUMMARY



	echanical Specifications
Mounting Signal Connector: Mates Directly to Drive	96-port, 1.27mm spaced, dual-row socket
Mounting Power Connector: Mates Directly to Drive	50-pin, 2.0mm spaced, dual-row socket
Motor Power Connector: P1	4-port screw terminal
Power Connector: P2	4-port screw terminal
CANopen Communication Connector: P5*	8-pin, dual-row, 2.00 mm spaced plug terminal, vertical mount
USB Connector: P6	5-pin, Mini USB B Type port
I/O Connector: P7*	20-pin, dual-row, 2.00 mm spaced plug terminal, vertical mount
Auxiliary Feedback Connector: P8*	10-pin, dual-row, 2.00 mm spaced plug terminal, vertical mount
Feedback Connector: P9*	18-pin, dual-row, 2.00 mm spaced plug terminal, vertical mount
Size (L x W x H) / mm (in)	63.5 x 88.9 x 26.3 (2.5 x 3.5 x 1.0)
Weight / g (oz)	68 (2.4)

*Mating Connector Kit

Mating connector housing and crimp pins can be ordered as a kit using *ADVANCED* Motion Controls part number **KC-MC1XDZPO1**. This includes mating connector housing and crimp style contacts for the I/O, Feedback, Auxiliary Feedback, and Communication connectors. The recommended tool for crimping the contacts is Molex part number **63811-6300**.





PIN FUNCTIONS

Mounting Signal Connector

This connector mates directly to the drive. For pin functions refer to the drive datasheet.

Mounting Power Connector

This connector mates directly to the drive. For pin functions refer to the drive datasheet.

	P1 - Motor Power Connector		
Pin	Name	Description / Notes	1/0
1	MOTOR C	Motor Phase C	0
2	MOTOR B	Motor Phase B	0
3	MOTOR A	Motor Phase A	0
4	CHASSIS	Shield Connection	-

		P2 - Power Connector	
Pin	Name	Description / Notes	1/0
1	CHASSIS	Shield Connection	-
2	AUX SUPPLY	Logic Supply	I
3	GND	Ground	GND
4	HV	DC Power Supply	I

	P5 - CANopen Communication Connector			
Pin	Name	Description / Notes	1/0	
1	CAN_H	CAN H bus line (dominant high)	I/O	
2	CAN_H	CAN_H bus life (doffillant fligh)	I/O	
3	CAN_L	CAN L bus line (dominant low)	I/O	
4	CAN_L	SAN_L bus life (dominant low)	I/O	
5	GND	Ground	GND	
6	GND	Ground	GND	
7	RESERVED	Decembed	-	
8	RESERVED	Reserved	-	

	P6 - USB Communication Connector		
Pin	Name	Description / Notes	1/0
1	VBUS	Supply Voltage	0
2	DATA -	USB Data -	I/O
3	DATA +	USB Data +	I/O
4	RESERVED	Reserved	-
5	GND	USB Ground	UGND





		P7 – I/O Connector	
Pin	Name	Description	1/0
1	CHASSIS	Shield Connection	-
2	RESERVED	Reserved	-
3	PDI-1	Programmable Digital Input	1
4	PDI-4+	High Speed Differential Programmable Digital Input	I
5	PDI-2	Programmable Digital Input	I
6	PDI-4-	High Speed Differential Programmable Digital Input	I
7	PDI-3	Programmable Digital Input	I
8	PDI-5+	High Speed Differential Programmable Digital Input	I
9	RESERVED	Reserved	-
10	PDI-5-	High Speed Differential Programmable Digital Input	I
11	PDO-1	Programmable Digital Output	0
12	RESERVED	Reserved	-
13	PDO-2	Programmable Digital Output	0
14	+5V OUT	+5V Output from Logic Supply	0
15	PDO-3	Programmable Digital Output	0
16	GND	Ground	GND
17	PDO-4	Programmable Digital Output	0
18	PAI-1+	Differential Programmable Analog Input or Reference Signal Input (12-bit resolution)	I
19	PDO-5	Programmable Digital Output	0
20	PAI-1-	Differential Programmable Analog Input or Reference Signal Input (12-bit resolution)	I

P8 - Auxiliary Feedback Connector			
Pin	Name	Description	1/0
1	CHASSIS	Shield Connection	-
2	RESERVED	Reserved	-
3	AUX ENC I+	Auxiliary Incremental Encoder Channel I or Differential Programmable Digital Input 8	I
4	AUX ENC A+	Auxiliary Incremental Encoder Channel A or Differential Programmable Digital Input 6	I
5	AUX ENC I-	Auxiliary Incremental Encoder Channel I or Differential Programmable Digital Input 8	I
6	AUX ENC A-	Auxiliary Incremental Encoder Channel A or Differential Programmable Digital Input 6	I
7	+5V USER	+5V User Supply Output (current shared with pin P9-17)	0
8	AUX ENC B+	Auxiliary Incremental Encoder Channel B or Differential Programmable Digital Input 7	I
9	GND	Ground	GND
10	AUX ENC B-	Auxiliary Incremental Encoder Channel B or Differential Programmable Digital Input 7	I

			P9 – Fee	edback Connector*	
Pin	Incremental Encoder	Absolute Encoder	1Vp-p Sin/Cos Encoder	Description / Notes	1/0
1	CHASSIS	CHASSIS	CHASSIS	Shield Connection	-
2	RESERVED	RESERVED	RESERVED	Reserved	-
3	MOT ENC I+	RESERVED	RESERVED	Differential Encoder Index	I
4	MOT ENC A+	SIN+	SIN+	Differential Encoder A / Differential Sine Input	I
5	MOT ENC I-	RESERVED	RESERVED	Differential Encoder Index	I
6	MOT ENC A-	SIN-	SIN-	Differential Encoder A / Differential Sine Input	I
7	HALL A	RESERVED	HALL A	Commutation sensor input.	I
8	MOT ENC B+	COS+	COS+	Differential Encoder B/ Differential Cosine Input	I
9	HALL B	RESERVED	HALL B	Commutation sensor input.	I
10	MOT ENC B-	COS-	COS-	Differential Encoder B/ Differential Cosine Input	I
11	HALL C	RESERVED	HALL C	Commutation sensor input.	I
12	RESERVED	CLK+	RESERVED	Differential Clock Line	-
13	MOTOR THERMISTOR	MOTOR THERMISTOR	MOTOR THERMISTOR	Motor Thermal Protection	I/O
14	RESERVED	CLK-	RESERVED	Differential Clock Line	I/O
15	+5V USER	+5V USER	+5V USER	+5V User Supply Output (current shared with pin P8-7)	I/O
16	RESERVED	DATA+	RESERVED	Differential Data Line	I/O
17	GND	GND	GND	Ground	GND
18	RESERVED	DATA-	RESERVED	Differential Data Line	I/O

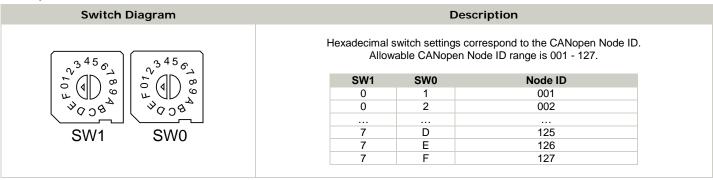
*Note: Feedback supported (Incremental Encoder, Absolute Sin/Cos Encoder, or 1Vp-p Sin/Cos Encoder) will be dependent on drive firmware.





BOARD CONFIGURATION

CANopen Node ID Switches



CANopen Bit Rate Jumpers

The CANopen bit rate is controlled by jumpers JF12 and JF13, located near the USB communication connector, P6. Use the table below to configure the bit rate.

Bit Rate (kbits/sec)	JF12	JF13
Load from non-volatile memory	Not Installed	Not Installed
500	Installed	Not Installed
250	Not Installed	Installed
125	Installed	Installed

CANopen Termination Node Jumper

CANopen bus termination is controlled by jumper JF1. The last device in a CAN network requires a termination resistor across the CAN_H and CAN_L lines. JF1 is located near the CANopen communication connector, P5.

CANopen Termination	JF1
Non-terminating Node	Not Installed
Terminating Node	Installed

LED Functions

The MC1XDZPC01 contains LEDs that indicate DC Power Supply status, Logic Power Supply status, and the drive Bridge status. The Power LED (P) will light up green when power is applied to P2-Power Connector, and the Logic LED (L) will light up green when the Logic Power is applied to P3-Auxiliary Logic Connector. The Bridge Status LED (STS) indicates the servo drive's power bridge state, and will be green when the drive is enabled, and red when the drive is in a fault state.

Mounting Configuration



MC1XDZPC01

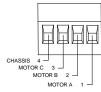


CONNECTOR INFORMATION

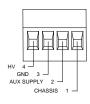
Mounting Signal Connector		
Connector Information	96-pin, 1.27 mm spaced, dual-row socket	
Mating Connector Example	No Mating Connector Required. Mate directly to drive	

Mounting Power Connector	
Connector Information	50-pin, 2.0 mm spaced, dual-row socket
Mating Connector Example No Mating Connector Required. Mate directly to drive	

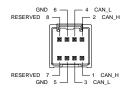
P1 - Motor Power Connector			
Connector Information		4-port screw terminal	
Mating Connector	Details	Not Applicable	
	Included with Card	Not Applicable	



P2 – Power Connector		
Connector Information		4-port screw terminal
Mating Connector	Details	Not Applicable
	Included with Card	Not Applicable



P5 - CANopen Communication Connector			
Connector Information		8-pin, dual-row, 2.00 mm spaced plug terminal, vertical mount	
Mating Connector	Details	Molex: P/N 51353-0800 (housing); 56134-9100 (contacts)	
	Included with Card	No	







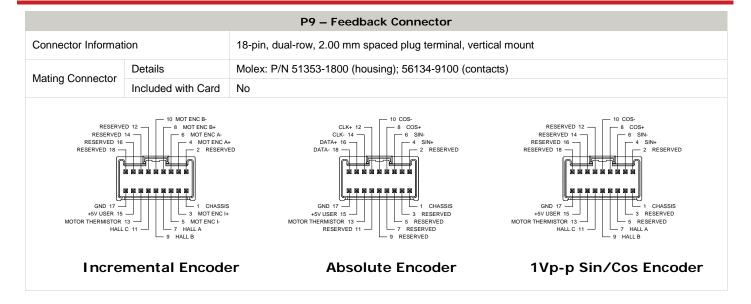
P6 – USB Connector				
Connector Information		5-pin, Mini USB B Type port		
Mating Connector	Details	TYCO: 1496476-3 (2-meter STD-A to MINI-B ASSY)		
	Included with Card	No		
GND 5 RESERVED 4 DATA + 3 DATA - 2 VBUS 1				

P7 – I/O Connector					
Connector Information		20-pin, dual-row, 2.00 mm spaced plug terminal, vertical mount			
Mating Connector	Details	Molex: P/N 51353-2000 (housing); 56134-9100 (contacts)			
	Included with Card	No			
	RESERVED 12 -5V OUT 14 -5V OUT 14 -6 PDI-4- -7 PDI-4- -7 PDO-5 19 -7 PDO-3 15 -7 PDO-2 13 -7 PDI-3 -7 PDI-3				

P8 - Auxiliary Feedback Connector			
Connector Information		10-pin, dual-row, 2.00 mm spaced plug terminal, vertical mount	
Mating Connector	Details	Molex: P/N 51353-1000 (housing); 56134-9100 (contacts)	
	Included with Card	No	
AUX ENC B+ 8 AUX ENC B- 10 AUX ENC A- 4 AUX ENC A- 2 RESERVED GND 9 AUX ENC B- 10 AUX ENC B- 10 AUX ENC A- 2 RESERVED AUX ENC B- 10 AUX ENC A- 2 RESERVED AUX ENC B- 10			



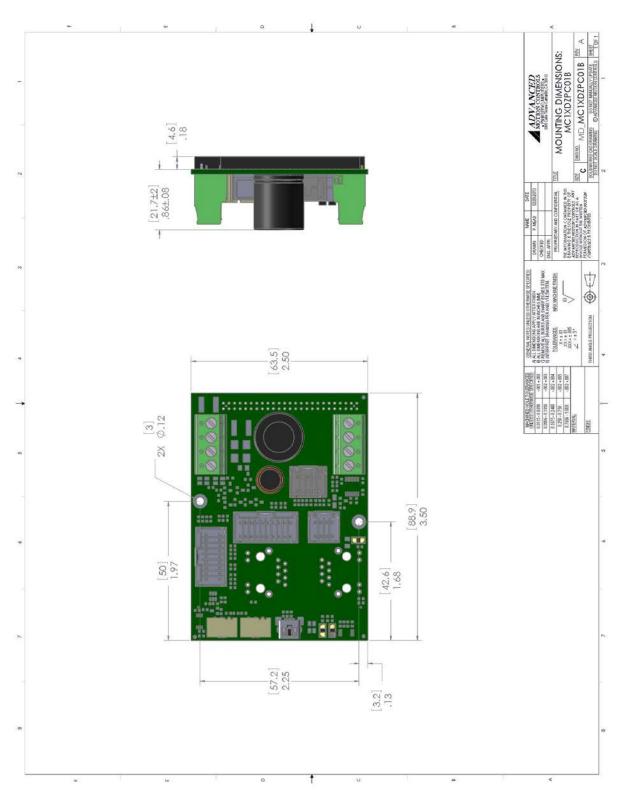








MOUNTING DIMENSIONS

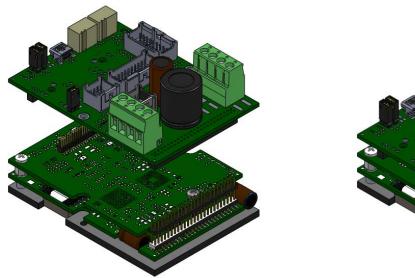


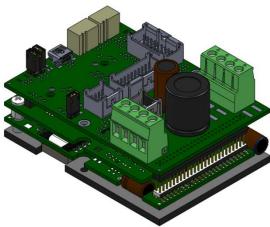




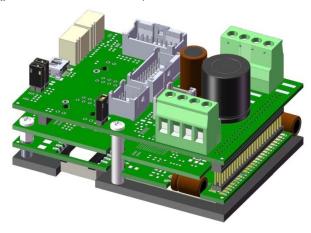
MOUNTING CONFIGURATION

Note that a DZCANTU servo drive plugs into the MC1XDZPC01 from the underside of the mounting card to allow easy access to the mounting card switches and connectors. The drive and mounting card assembly can be secured to a panel or heatsink through the mounting holes in the drive baseplate and the sides of the mounting card.





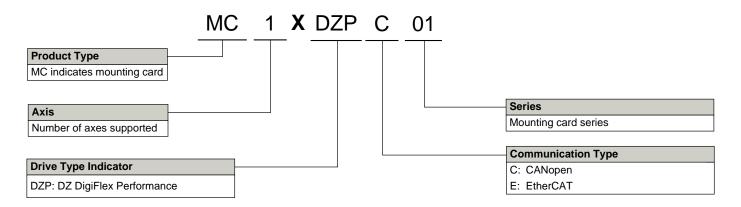
The mounting card chassis should be secured to the drive baseplate by using the two spacers included with the MC1XDZPC01 between the MC1XDZPC01 mounting holes and the drive baseplate as shown in the below image.







PART NUMBERING INFORMATION



DigiFlex® Performance TM series of products are available in many configurations. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- Custom Control Interface
- ▲ Integrated System I/O

- ▲ Tailored Project File
- ▲ Silkscreen Branding
- Optimized Base Plate
- ▲ Increased Current Limits
- Increased Voltage Range
- ▲ Conformal Coating
- Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

Feel free to contact Applications Engineering for further information and details.

