

Description

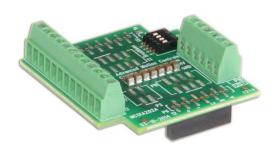
The MC1XAZ02 mounting card is designed to host a μZ -style AZ series analog servo drive. This mounting card offers convenient screw-terminal connectors. Easily accessible test points are available for I/O monitoring. The MC1XAZ02 can be screw-mounted directly to a PCB when assembled with a μZ -style AZ drive, and is ideal for both prototyping and production. The mounting card also features a keyed connector to prevent misaligned connections.

Drive Compatibility

μZ-style AZ

40 V Models

10A



Features

- ▲ Detachable Connections
- ▲ Lightweight

DRIVES SUPPORTED

- AZB10A4
- AZBDC10A4

- ▲ Small Footprint
- ▲ Keyed Connector

FEEDBACK SUPPORTED

Hall Sensors

COMPLIANCES & AGENCY APPROVALS

- RoHS
- UL / cUL Pending
- CE Pending





SPECIFICATIONS



Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	RoHS, UL / cUL Pending, CE Pending
Size (H x W x D) (mounting card only)	mm (in)	38.1 x 38.1 x 16.2 (1.5 x 1.5 x 0.64)
Size (H x W x D) (with drive installed)	mm (in)	38.1 x 38.1 x 23.6 (1.5 x 1.5 x 0.93)
Weight (mounting card only)	g (oz)	11.3 (0.4)
Bus Capacitance	μF	33
P4 Connector	-	12-port, 1.27 mm spaced header, vertical mount (pin 7 keyed)
P5 Connector	-	12-port, 1.27 mm spaced header, vertical mount
P10 Connector	-	6-port, 2.54 mm spaced fixed screw terminals
P11 Connector	-	12-port, 2.54 mm spaced fixed screw terminals

Information on Approvals and Compliances



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.





PIN FUNCTIONS

P4 - Drive Mounting Power / Motor Connector

12-port vertical header for drive insertion – direct connection to the drive. Pin 7 keyed to avoid incorrect drive orientation. For pin functions refer to the drive datasheet.

P5 - Drive Mounting Signal Connector

12-port vertical header for drive insertion – direct connection to the drive. For pin functions refer to the drive datasheet.

P10 - Power / Motor Connector			
Pin	Name	Description / Notes	1/0
1	MOTOR A	Motor Phase Outputs. Current output distributed equally across 2 pins per motor phase, 3A continuous current carrying capacity per pin. For single phase (brushed) motors, set DIP Switch SW1 to ON and use only Motor A and Motor B.	0
2	MOTOR B		0
3	MOTOR C		0
4	PWR GND	Power Ground (Common With Signal Ground). 3A Continuous Current Rating Per Pin	GND
5	HV IN	DC Power Input. 3A Continuous Current Rating Per Pin. Requires a minimum of 47 μF external capacitance between HV IN and PWR GND pins.	I
6	RESERVED	Reserved	-

P11 – I/O Connector			
Pin	Name	Description	1/0
1	-REF IN	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)	I
2	+REF IN	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)	I
3	SIGNAL GND	Signal Ground (Common With Power Ground).	GND
4	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, invalid Hall state, output short circuit, over voltage, over temperature, power-up reset.	0
5	INHIBIT IN	TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices.	I
6	CURRENT MONITOR	Current Monitor. Analog output signal proportional to the actual current output. Scaling is 2 A/V. Measure relative to signal ground.	0
7	HALL 3		I
8	HALL 2	Single-ended Hall/Commutation Sensor Inputs (+5 V logic level). For single phase (brushed) motors, set DIP Switch SW1 to ON and leave all Hall signals open.	I
9	HALL 1	Owner over to ore and reave an inal signals open.	I
10	+V HALL OUT	Low Power Supply For Hall Sensors (+5 V @ 30 mA). Referenced to signal ground. Short circuit protected.	0
11	SIGNAL GND	Signal Ground (Common With Power Ground).	GND
12	RESERVED	Reserved	-

HARDWARE NOTES

DIP Switch Settings

When set to the ON position, DIP Switch SW1 internally shorts Hall 2 to ground for use with single phase (brushed) motors. Note that in this configuration, all Hall signal pins should be left open, and only motor phase outputs A and B should be used. Default switch setting is OFF (three phase / brushless motors).

DIP Switches SW2, SW3, SW4 are reserved.





MECHANICAL INFORMATION

P4 - Drive Mounting Power / Motor Connector		
Connector Information	12-port, 1.27 mm spaced header, vertical mount	
Mating Connector	No mating connector required. Mate directly to drive.	

P5 – Drive Mounting Signal Connector		
Connector Information	12-port, 1.27 mm spaced header, vertical mount	
Mating Connector	No mating connector required. Mate directly to drive.	

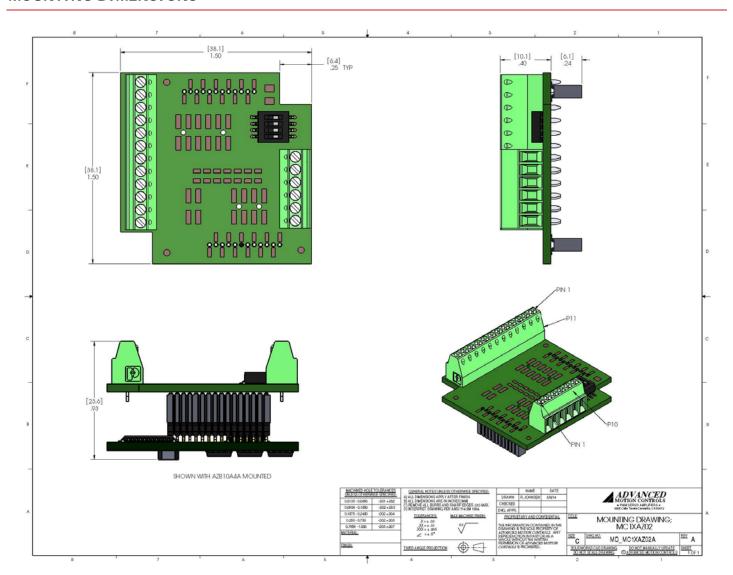
P10 – Power / Motor Connector		
Connector Information	Connector Information 6-port, 2.54 mm spaced fixed screw terminal	
Mating Connector	Details	Not Applicable
Mating Connector	Included with Drive	Not Applicable
MOTOR C 3 4 PWR GND MOTOR B 2 5 HV IN MOTOR A 1 6 RESERVED		

P11 – I/O Connector			
Connector Information	Connector Information 12-port, 2.54 mm spaced fixed screw terminal		
Mating Connector	Details Included with Drive		
CURRENT MONITOR 6 7 HALL 3 INHIBIT IN 5 8 HALL 2 FAULT OUT 4 9 HALL 1 SIGNAL GND 3 10 +V HALL OUT +REF IN 2 11 SIGNAL GND -REF IN 1 12 RESERVED			





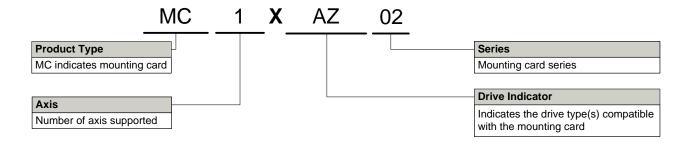
MOUNTING DIMENSIONS







PART NUMBERING INFORMATION



All analog servo drive accessories listed in the selection tables of the website are readily available, standard product offerings. However, additional features and/or options are available for select drives and other possibilities can be made available for OEMs with sufficient volume requests. Feel free to contact Applications Engineering for further information and details.

ELECTROMATE

All specifications in this document are subject to change without written notice. Actual product may differ from pictures product may differ from pictures product may differ from pictures of the picture of the pictur in this document.