

### Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a single RS-485/RS-232 interface used for drive configuration and setup. Drive commissioning is accomplished using DriveWare<sup>®</sup> 7, available for download at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Ran	ge
Peak Current	100 A (70.7 A <sub>RMS</sub> )
Continuous Current	50 A (50 A <sub>RMS</sub> )
AC Supply Voltage	200 - 240 VAC
DC Supply Voltage	255 - 373 VDC





#### **Features**

- ▲ Four Quadrant Regenerative Operation
- Space Vector Modulation (SVM) Technology
- ✓ Fully Digital State-of-the-art Design
- Programmable Gain Settings
- Fully Configurable Current, Voltage, Velocity and Position Limits
- PIDF Velocity Loop

- ✓ PID + FF Position Loop
- Compact Size, High Power Density
- ▲ 16-bit Analog to Digital Hardware
- Built-in brake/shunt regulator
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching

#### MODES OF OPERATION

- Current
- Position
- Velocity

## **COMMAND SOURCE**

- PWM and Direction
- Encoder Following
- Over the Network
- ±10 V Analog
- Sequencing
- Indexing
- Jogging

### **FEEDBACK SUPPORTED**

- Resolver
- ±10 VDC Position
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

#### INPUTS/OUTPUTS

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 1 Programmable Analog Output (10-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

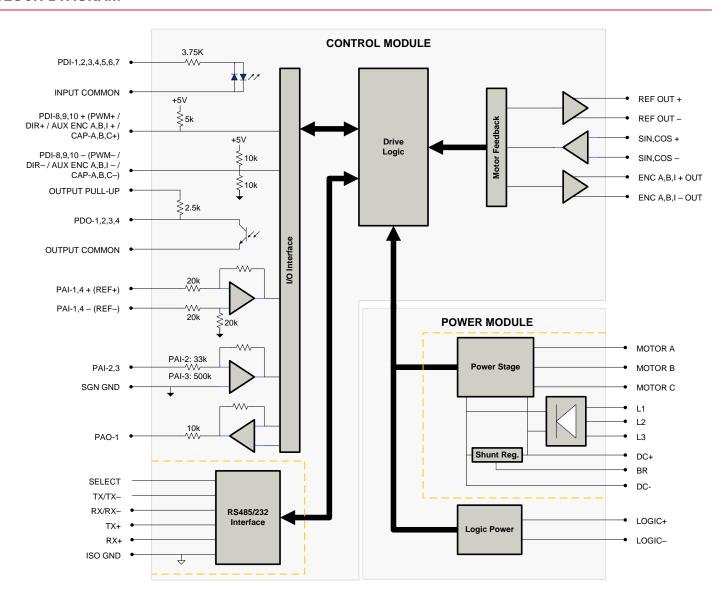
### **COMPLIANCES & AGENCY APPROVALS**

- RoHS
- UL/cUL Pending
- CE Pending





## **BLOCK DIAGRAM**



# Information on Approvals and Compliances



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.





## **SPECIFICATIONS**

Description	Units	Power Specifications Value
Rated Voltage	VAC (VDC)	240 (339)
AC Supply Voltage Range	VAC	200 - 240
AC Supply Minimum	VAC	180
AC Supply Maximum  AC Supply Maximum	VAC	264
AC Input Phases <sup>1</sup>	-	3
·	Hz	50 - 60
AC Supply Velters Pense?		
DC Supply Voltage Range <sup>2</sup>	VDC	255 – 373
DC Bus Over Voltage Limit	VDC	420
DC Bus Under Voltage Limit	VDC	205
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)
Maximum Peak Output Current <sup>3</sup>	A (Arms)	100 (70.7)
Maximum Continuous Output Current <sup>4</sup>	A (Arms)	50 (50)
Max. Continuous Output Power @ Rated Voltage <sup>5</sup>	W	16103
Max. Continuous Power Dissipation @ Rated Voltage	W	848
Internal Bus Capacitance	μF	1120
External Shunt Resistor Minimum Resistance <sup>6</sup>	Ω	25
Minimum Load Inductance (Line-To-Line) <sup>7</sup>	μH	600
Switching Frequency	kHz	10
Maximum Output PWM Duty Cycle	%	100
Low Voltage Supply Outputs	-	+5 VDC (250 mA)
		Control Specifications
Description	Units	Value Value
Communication Interfaces	-	RS-485/232
Command Sources	-	±10 V Analog, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Resolver, Tachometer (±10 VDC)
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Current, Position, Velocity
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/0
Primary I/O Logic Level	-	24 VDC
Current Loop Sample Time	μs	100
Velocity Loop Sample Time	μs	200
Position Loop Sample Time	μs	200
Resolver Reference/Excitation Signal	Vrms	4 Vrms @ 5 kHz
Expected Resolver Transformation Ratio	Vrms	0.5
Feedback Resolution / Emulated Encoder Resolution8	bit	High Res: 14 (16384 counts/resolver cycle), Low Res: 12 (4096 counts/resolver cycle)
Maximum Motor Speed Per Feedback Resolution	RPM	High Res: 5000, Low Res: 20000
Internal Shunt Regulator	-	Yes
Internal Shunt Resistor	-	No
	М	echanical Specifications
Description	Units	Value
Agency Approvals	-	RoHS, UL/cUL Pending, CE Pending
Size (H x W x D)	mm (in)	256.5 x 182.6 x 135.3 (10.1 x 7.2 x 5.3)
Weight	g (oz)	3560.7 (125.6)
Heatsink (Base) Temperature Range <sup>9</sup>	°C (°F)	0 - 75 (32 - 167)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
Cooling System - Forced Convection		
AUX ENCODER Connector	NCODER Connector - 15-pin, high-density, male D-sub	
COMM Connector - 9-pin, female D-sub		
FEEDBACK Connector	- 15-pin, high-density, female D-sub	
I/O Connector	-	26-pin, high-density, female D-sub
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header
FAN Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header
MOTOR POWER Connector	-	4-port, 10.16 mm spaced, enclosed, friction lock header
AC POWER Connector		4-port, 10.16 mm spaced, enclosed, friction lock header
DC POWER Connector	-	4-port, 10.16 mm spaced, enclosed, includinock header
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- Can operate on single-phase AC (208 VAC minimum) as long as output power does not exceed 3kW maximum. Current limits are de-rated to 30A cont. / 60A peak. Large inrush current may occur upon initial DC supply connection to DC Bus.

  Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.

  Continuous A<sub>min</sub> value attainable when RMS Charge-Based Limiting is used.

  P = (DC Rated Voltage) \* (Cont. RMS Current) \* 0.95.

  ADVANCED Motion Controls recommends using an external fuse in series with an external shunt resistor. A 5 amp time delay fuse is typical.

  Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.

  Higher and lower resolution options are available. Contact Applications Engineering for more information.

  Additional cooling and/or heatsink may be required to achieve rated performance.





# **PIN FUNCTIONS**

AUX ENCODER - Auxiliary Feedback Connector			
Pin	Name	Description / Notes	1/0
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)	Single-Ended Signals Leave Negative Terminal Open)	
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)	(For Single-Ended Signals Leave Negative Terminal Open)	
8	PDI-10 + (AUX ENC I+ / CAP-A+)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended	I
9	PDI-10 - (AUX ENC I- / CAP-A-)	Signals Leave Negative Terminal Open)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-4 +	Differential December 11 April 12 April 12 April 14 (40 kit December 12)	
15	PAI-4 -	Differential Programmable Analog Input (12-bit Resolution)	I

COMM - RS232/RS485 Communication Connector			
Pin	Name	Description / Notes	1/0
1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I
2	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	0
3	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I
4	RESERVED	Reserved	-
5	ISO GND	Isolated Signal Ground	IGND
6	RS485 TX+	Transmit Line (RS-485)	0
7	RESERVED	Reserved	-
8	RS485 RX+	Receive Line (RS-485)	I
9	RESERVED	Reserved	-

FEEDBACK - Feedback Connector			
Pin	Name	Description / Notes	1/0
1	RESERVED		-
2	RESERVED	Reserved	-
3	RESERVED		-
4	REF OUT +	Resolver Reference/Excitation Output	0
5	REF OUT -	Resolver Reference/Excitation Output	0
6	SIN+	Resolver Sine Input	I
7	SIN-	Resolver Sille Iliput	I
8	COS+	Resolver Cosine Input	I
9	COS-	Resolver Cosine input	I
10	RESERVED	Reserved	-
11	RESERVED	Keserved	-
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-3	Programmable Analog Input (12-bit Resolution)	l I
15	RESERVED	Reserved	-





		I/O - Signal Connector	
Pin	Name	Description / Notes	1/0
1	PDO-1	Isolated Programmable Digital Output	0
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	0
4	PAI-1 + (REF+)	Differential Draggammable Angles Input or Reference Cignel Input (46 hit Receivtion)	I
5	PAI-1 - (REF-)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	PAO-1	Programmable Analog Output (10-bit Resolution)	0
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	0
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	0
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4	Isolated Programmable Digital Input	I
18	PDI-6	Isolated Programmable Digital Input	I
19	PDI-7	Isolated Programmable Digital Input	I
20	ENC A+ OUT	Emulated Engager Channel A Output	0
21	ENC A- OUT	Emulated Encoder Channel A Output	0
22	ENC B+ OUT	Emulated Encoder Channel B Output	0
23	ENC B- OUT	Emulated Emodel Chamber & Output	0
24	ENC I+ OUT	Emulated Encoder Index Output	0
25	ENC I- OUT	Emulated Encoder Index Output	0
26	SGN GND	Signal Ground	SGND

		Logic Power Connector	
Pin	Name	Description / Notes	1/0
1	LOGIC GND	Logic Supply Ground	GND
2	LOGIC PWR	Logic Supply Input	I

Fan Power Connector				
Pin	Pin Name Description / Notes I/O			
1	FAN GND	Fan Ground	GND	
2	FAN PWR	Fan Power Input	I	

	AC Power Connector		
Pin	Name	Description / Notes	1/0
1	L1	100 L L L L T L D L L T L L L L L L L L L L	I
2	L2	AC Supply Input (Three Phase). External 20 A time delay fuses are recommended in series with the AC input lines.	I
3	L3	with the AC input lines.	I
4	CHASSIS	Chassis Ground	CGND

	DC Power Connector			
Pin	Name	Description / Notes	1/0	
1	GND	Power Ground	PGND	
2	DC+	DC Power Input	I	
3	DC+	External Shunt Resistor Connection. Connect resistor between DC+ and BR.	I	
4	BR	External Shufft Resistor Confidention. Confident resistor between DC+ and BR.	-	

	Motor Power Connector			
Pin	Name	Description / Notes	1/0	
1	CHASSIS	Chassis Ground	CGND	
2	MOTOR A	Motor Phase A	0	
3	MOTOR B	Motor Phase A	0	
4	MOTOR C	Motor Phase B	0	





## HARDWARE SETTINGS

### **Switch Functions**

Switch	Description	Set	ting
Switch	Description	On	Off
1	Bit 0 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0

#### Additional Details

The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Baud Rate (kbps)	Value For Bit Rate Setting
Load from non-volatile memory	0
9.6	1
38.4	2
115.2	3





# **MECHANICAL INFORMATION**

AUX ENCODER - Auxiliary Feedback Connector			
Connector Information	Connector Information 15-pin, high-density, male D-sub		
Mating Connector	Details	TYCO: Plug P/N 1658681-1; Housing P/N 5748677-1; Terminals P/N 1658686-2 (loose) or 1658686-1 (strip)	
· ·	Included with Drive	No	
SGN GND 10  PDI-10 - (AUX ENC I+ / CAP-A+) 9  PDI-9 - (DIR- / AUX ENC B+ / CAP-C+) 7  PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+) 6  PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+) 6  15 PAI-4 -  14 PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)  15 PAI-4 -  17 PAI-4 -  18 PAI-4 -  19			

COMM - RS232/RS485 Communication Connector			
Connector Information		9-pin, female D-sub	
Mating Connector	Details	TYCO: Plug P/N 205204-4; Housing P/N 5748677-1; Terminals P/N 1658540-5 (loose) or 1658540-4 (strip)	
_	Included with Drive	No	
		3 RS232 RX / RS485 RX- 2 RS232 TX / RS485 TX- 1 SELECT 6 RS485 TX+ 8 RS485 RX+	

FEEDBACK - Feedback Connector			
Connector Information	Connector Information 15-pin, high-density, female D-sub		
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)	
	Included with Drive	No	
		SIN- 6	



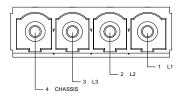


		I/O - Signal Connector
Connector Information 26-pin, high-density, female D-sub		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
ŭ	Included with Drive	No
PDO-3 10 9 PDI-5 PDI-1 11 8 OUTPUT PULL-UP PDI-2 12 6 PAI-2 PDO-4 14 6 PAI-2 INPUT COMMON 15 4 PAI-1 (REF-) SGN GND 16 2 OUTPUT COMMON PDI-6 18 19 PDI-7 20 ENC A- OUT 21 ENC A- OUT 22 ENC B- OUT 24 ENC B- OUT 24 ENC B- OUT 25 ENC I- OUT 26 SGN GND		

Logic Power Connector		
Connector Information		2-port, 5.08 mm spaced, enclosed, friction lock header
Details		Phoenix Contact: P/N 1757019
Mating Connector	Included with Drive	Yes
2 LOGIC PWR 1 LOGIC GND		

Fan Power Connector			
Connector Information	Connector Information 2-port, 5.08 mm spaced, enclosed, friction lock header		
Details		Phoenix Contact: P/N 1757019	
Mating Connector	Included with Drive	Yes	
2 FAN PWR 1 FAN GND			

AC Power Connector		
Connector Information 4-pin, 10.16 mm spaced, enclosed, friction lock header		4-pin, 10.16 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1913523
Mating Connector	Included with Drive	Yes







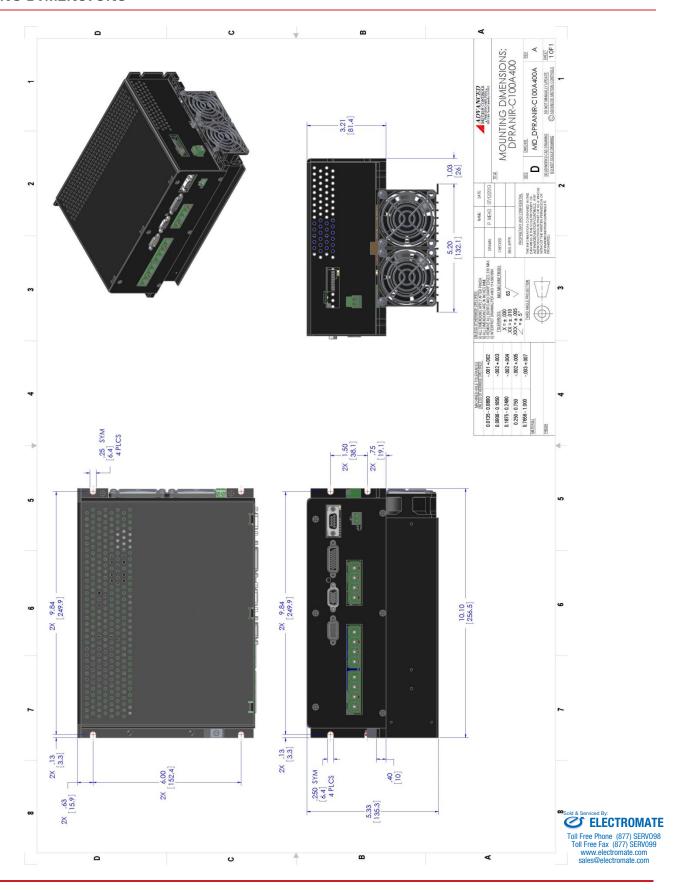
DC Power Connector			
Connector Information		4-pin, 10.16 mm spaced, enclosed, friction lock header	
Mating Connector	Details	Phoenix Contact: P/N 1913523	
Mating Connector	Included with Drive	Yes	
3 DC+ 1 DC-			

Motor Power Connector		
Connector Information		4-pin, 10.16 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1913523
Mating Connector	Included with Drive	Yes
4 MOT C MOT A CHASSIS		



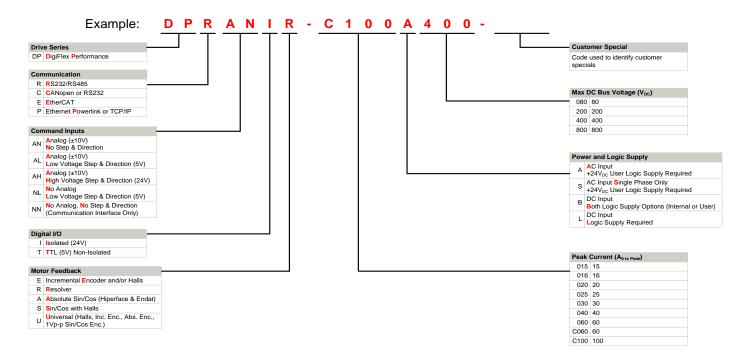


# MOUNTING DIMENSIONS





### PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quickturn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

### **Examples of Customized Products**

- Optimized Footprint
- Private Label Software
- **OEM Specified Connectors**
- No Outer Case
- **Increased Current Resolution**
- Increased Temperature Range
- **Custom Control Interface**
- Integrated System I/O

- Tailored Project File
- Silkscreen Branding
- Optimized Base Plate
- **Increased Current Limits**
- Increased Voltage Range
- Conformal Coating
- Multi-Axis Configurations
- Reduced Profile Size and Weight

### **Available Accessories**

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



Toll Free Phone (877) SERV098 Toll Free Fax (877) SERV099 www.electromate.com