

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a single RS-232/RS-485 interface used for drive configuration and setup. Drive commissioning is accomplished using DriveWare, available at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Range

Peak Current	20 A (14.1 A _{RMS})
Continuous Current	10 A (7.1 A _{RMS})
Supply Voltage	20 - 80 VDC


Features

- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ▲ Fully Digital State-of-the-art Design
- ▲ Programmable Gain Settings
- ▲ Fully Configurable Current, Voltage, Velocity and Position Limits
- ▲ PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ Compact size, high power density
- ▲ 16-bit Analog to Digital Hardware

MODES OF OPERATION

- Current
- Position
- Velocity

COMMAND SOURCE

- PWM and Direction
- Encoder Following
- Over the Network
- ±10 V Analog
- 24V Step and Direction

FEEDBACK SUPPORTED

- ±10 VDC Position
- Auxiliary Incremental Encoder
- Heidenhain EnDat®
- Stegmann Hiperface®
- Tachometer (±10 VDC)

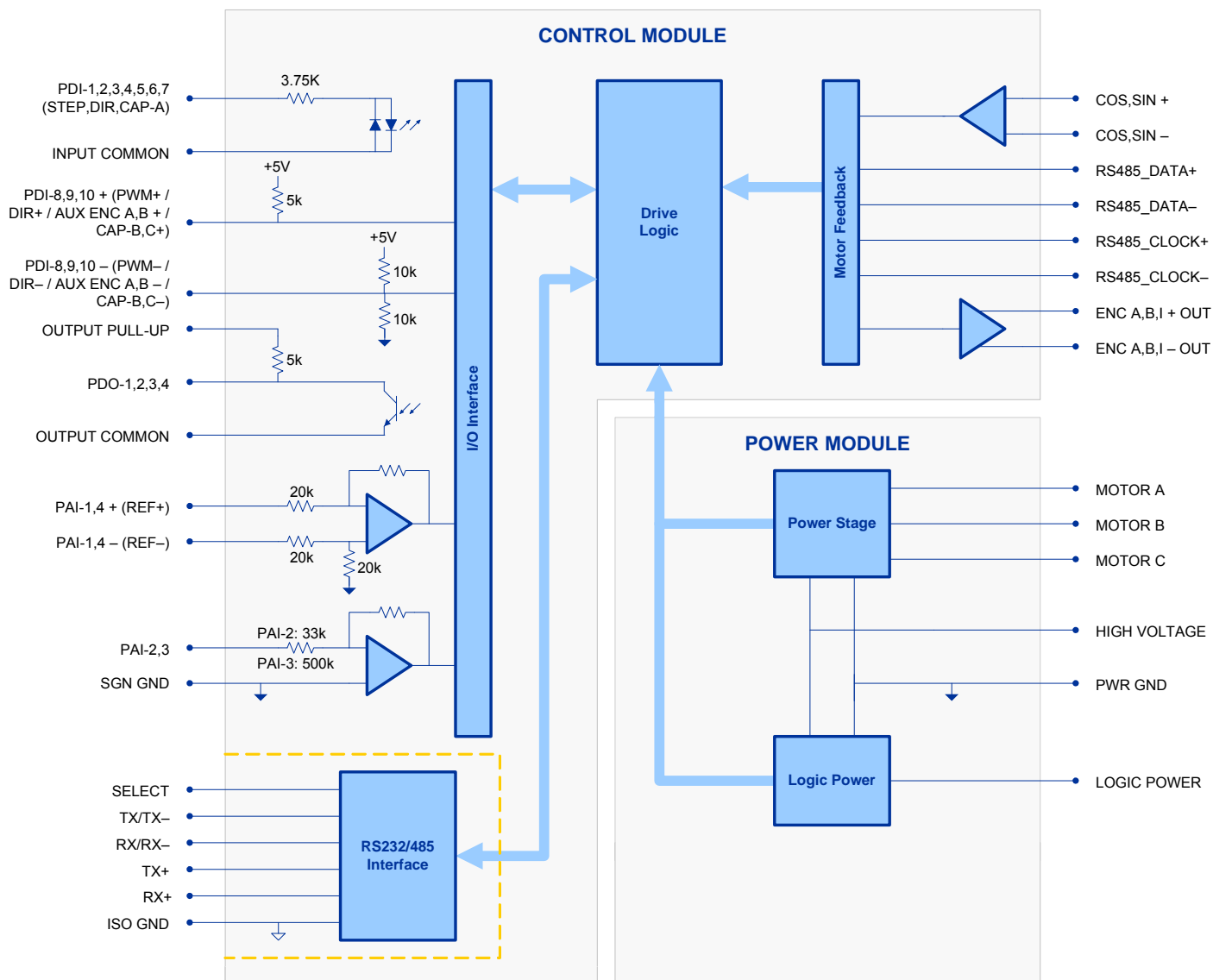
INPUTS/OUTPUTS

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

COMPLIANCES & AGENCY APPROVALS

- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

BLOCK DIAGRAM



Information on Approvals and Compliances*



Compliant with European CE for both the Class A EMC Directive 89/336/EEC on Electromagnetic Compatibility (specifically EN 61000-6-4:2001, EN 61000-6-2:2001, EN 61000-3-2:2000, and EN 61000-3-3:1995/A1:2001) and LVD requirements of directive 73/23/EEC (specifically EN 60204-1), a low voltage directive to protect users from electrical shock.



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

*Approvals may be pending. See "Compliances & Agency Approvals" on page 1 of datasheet for currently held approvals.

SPECIFICATIONS

Power Specifications		
Description	Units	Value
DC Supply Voltage Range	VDC	20 - 80
DC Bus Over Voltage Limit	VDC	89
DC Bus Under Voltage Limit	VDC	17.5
Logic Supply Voltage	VDC	20 - 80
Maximum Peak Output Current	A (Arms)	20 (14.1)
Maximum Continuous Output Current	A (Arms)	10 (7.1)
Maximum Continuous Output Power	W	760
Maximum Power Dissipation at Continuous Current	W	40
Internal Bus Capacitance	µF	33
Minimum Load Inductance (Line-To-Line) ¹	µH	250
Switching Frequency	kHz	20
Low Voltage Supply Outputs	-	+5 VDC (250 mA)
Control Specifications		
Description	Units	Value
Communication Interfaces	-	RS-485/232
Command Sources	-	±10 V Analog, 24V Step and Direction, Encoder Following, Over the Network, PWM and Direction
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Heidenhain EnDat®, Stegmann Hiperface®, Tachometer (±10 VDC)
Commutation Methods	-	Sinusoidal
Modes of Operation	-	Current, Position, Velocity
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/0
Primary I/O Logic Level	-	24 VDC
Current Loop Sample Time	µs	50
Velocity Loop Sample Time	µs	100
Position Loop Sample Time	µs	100
Maximum Sin/Cos Encoder Frequency	kHz	200
Maximum Sin/Cos Interpolation	-	2048 counts per sin/cos cycle
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), RoHS
Size (H x W x D)	mm (in)	167 x 89.5 x 35.9 (6.6 x 3.5 x 1.4)
Heatsink (Base) Temperature Range ²	°C (°F)	0 - 65 (32 - 149)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Cooling System	-	Natural Convection
Form Factor	-	Panel Mount
IP Rating	-	IP10
AUX ENCODER Connector	-	15-pin, high-density, male D-sub
COMM Connector	-	9-pin, female D-sub
FEEDBACK Connector	-	15-pin, high-density, female D-sub
I/O Connector	-	26-pin, high-density, female D-sub
POWER Connector	-	6-pin, 3.96 mm spaced, friction lock header

Notes

- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

AUX ENCODER - Auxiliary Feedback Connector			
Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)		I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)		I
8	PDI-10 +	Programmable Digital Input (For Single-Ended Signals Leave Negative Terminal Open)	I
9	PDI-10 -		I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-4 +	Differential Programmable Analog Input (12-bit Resolution)	I
15	PAI-4 -		I

COMM - RS232/RS485 Communication Connector			
Pin	Name	Description / Notes	I/O
1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I
2	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	O
3	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I
4	RESERVED	Reserved	-
5	ISO GND	Isolated Signal Ground	IGND
6	RS485 TX+	Transmit Line (RS-485)	O
7	RESERVED	Reserved	-
8	RS485 RX+	Receive Line (RS-485)	I
9	RESERVED	Reserved	-

FEEDBACK - Feedback Connector			
Pin	Name	Description / Notes	I/O
1	COS +	Cosine Input	I
2	COS -		I
3	SIN +	Sine Input	I
4	SIN -		I
5	SGN GND	Signal Ground	SGND
6	RS485_DATA-	Differential Data Line	I/O
7	RS485_DATA+		I/O
8	RS485_CLOCK+	Differential Clock Line	O
9	RS485_CLOCK-		O
10	REF MARK +	Reference mark from sine/cosine encoder	I
11	RESERVED	Reserved	-
12	RESERVED	Reserved	-
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	REF MARK -	Reference mark from sine/cosine encoder	I

I/O - Signal Connector			
Pin	Name	Description / Notes	I/O
1	PDO-1	Isolated Programmable Digital Output	O
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	O
4	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
5	PAI-1 - (REF-)		I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	SGN GND	Signal Ground	SGND
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	O
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	O
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4 (STEP)	Isolated Programmable Digital Input or Step	I
18	PDI-6 (DIR)	Isolated Programmable Digital Input or Direction	I
19	PDI-7 (CAP-A)	Isolated Programmable Digital Input or High Speed Capture	I
20	ENC A+ OUT	Emulated Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Emulated Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT		O
25	ENC I- OUT	Emulated Encoder Index Output	O
26	SGN GND	Signal Ground	SGND

POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	MOTOR A	Motor Phase A	O
2	MOTOR B	Motor Phase B	O
3	MOTOR C	Motor Phase C	O
4	HIGH VOLTAGE	DC Power Input	I
5	PWR GND	Power Ground (Common With Signal Ground)	PGND
6	LOGIC PWR	Logic Supply Input	I

HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0

Additional Details

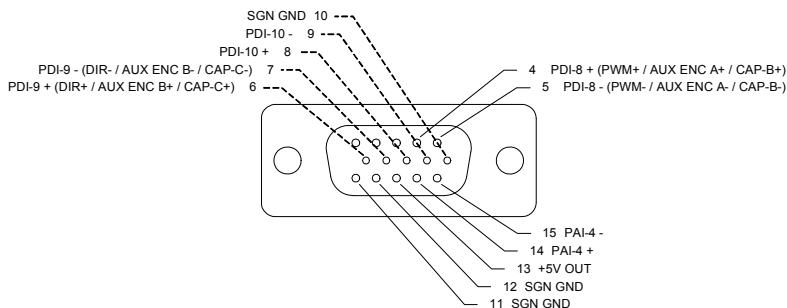
The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Baud Rate (kbps)	Value For Bit Rate Setting
Load from non-volatile memory	0
9.6	1
38.4	2
115.2	3

MECHANICAL INFORMATION

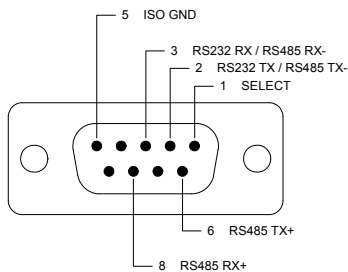
AUX ENCODER - Auxiliary Feedback Connector

Connector Information		15-pin, high-density, male D-sub
Mating Connector	Details	AMP: Plug P/N 748364-1; Housing P/N 748677-1; Terminals P/N 748610-4 (loose) or 748610-2 (strip)
	Included with Drive	No



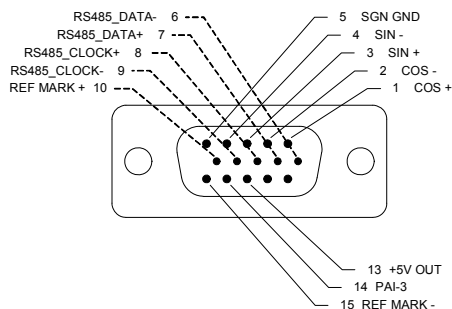
COMM - RS232/RS485 Communication Connector

Connector Information		9-pin, female D-sub
Mating Connector	Details	AMP: Plug P/N 205204-4; Housing P/N 748677-1; Terminals P/N 5-66507-7 (loose) or 3-66507-0 (strip)
	Included with Drive	No



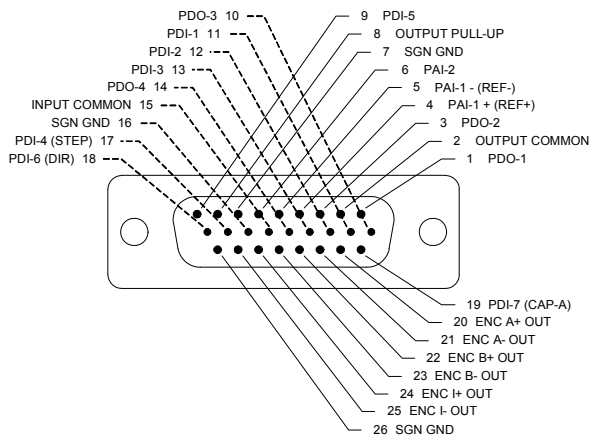
FEEDBACK - Feedback Connector

Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	AMP: Plug P/N 748364-1; Housing P/N 748677-1; Terminals P/N 748333-4 (loose) or 748333-2 (strip)
	Included with Drive	No



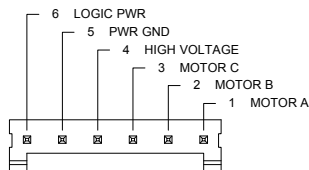
I/O - Signal Connector

Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	AMP: Plug P/N 748365-1; Housing P/N 748677-2; Terminals P/N 748333-4 (loose) or 748333-2 (strip)
	Included with Drive	No

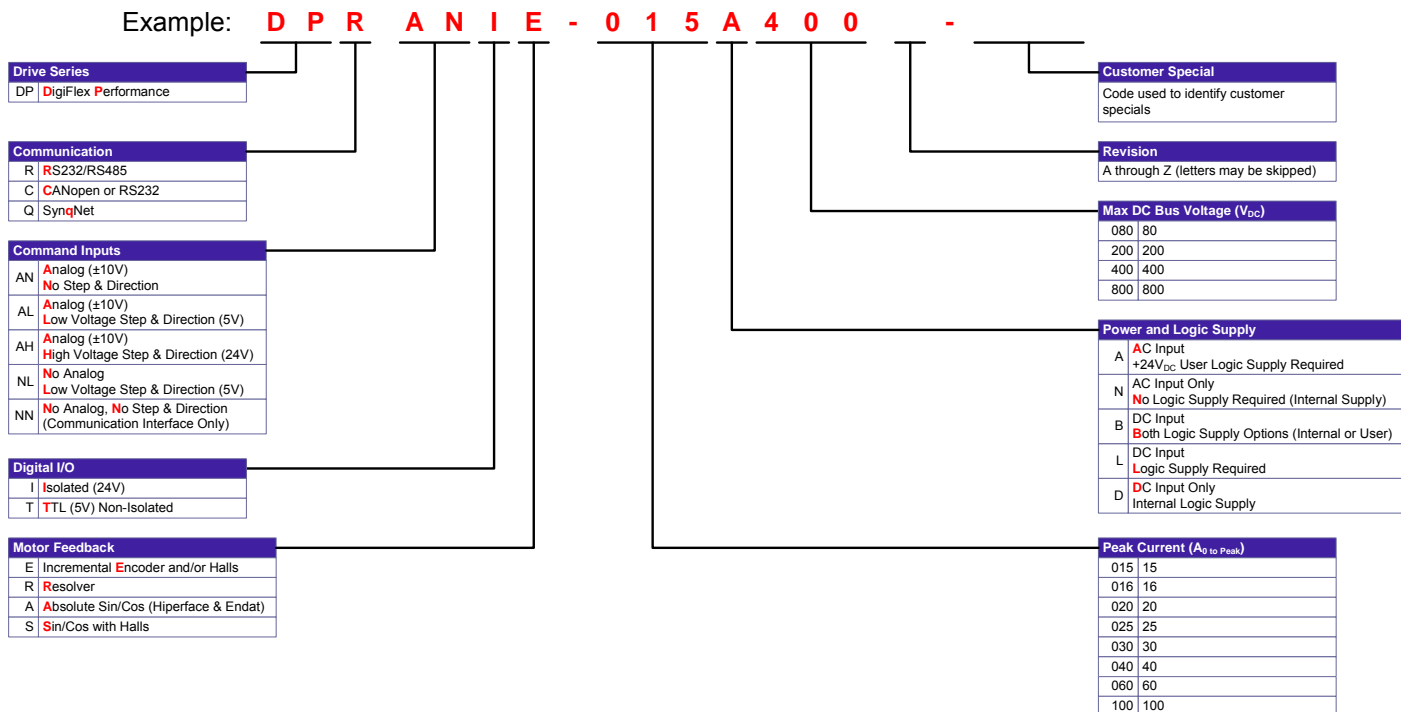


POWER - Power Connector

Connector Information		6-pin, 3.96 mm spaced, friction lock header
Mating Connector	Details	AMP: Plug P/N 770849-6; Terminals P/N 770522-1 (loose) or 770476-1 (strip)
	Included with Drive	Yes



PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- ▲ Optimized Footprint
 - ▲ Private Label Software
 - ▲ OEM Specified Connectors
 - ▲ No Outer Case
 - ▲ Increased Current Resolution
 - ▲ Increased Temperature Range
 - ▲ Custom Control Interface
 - ▲ Integrated System I/O
- ▲ Tailored Project File
 - ▲ Silkscreen Branding
 - ▲ Optimized Base Plate
 - ▲ Increased Current Limits
 - ▲ Increased Voltage Range
 - ▲ Conformal Coating
 - ▲ Multi-Axis Configurations
 - ▲ Reduced Profile Size and Weight

Feel free to contact Applications Engineering for further information and details.