

AZBDC40A8

Description

The AZBDC40A8 PWM servo drive is designed to drive brushless and brushed DC motors at a high switching frequency. To increase system reliability and to reduce cabling costs, the drive is designed for direct integration into your PCB. The AZBDC40A8 is fully protected against over-voltage, under-voltage, overcurrent, over-heating and short-circuits. A single digital output indicates operating status. The drive interfaces with digital controllers that have digital PWM output. The PWM IN duty cycle determines the output current and DIR input determines the direction of rotation. This servo drive requires only a single unregulated isolated DC power supply, and is fully RoHS (Reduction of Hazardous Substances) compliant.

See Part Numbering Information on last page of datasheet for additional ordering options.

Power Range	
Peak Current	40 A
Continuous Current	20 A
Supply Voltage	10 - 80 VDC



Features

- High Power Density
- Compact Size
- Direct Board-to-Board Integration
- Lightweight
- High Switching Frequency
- Four Quadrant Regenerative Operation

- Wide Temperature Range
- High Performance Thermal Dissipation
- Differential Input Command
- Current Monitor Output
- Digital Fault Output Monitor
- 12VDC Operation

HARDWARE PROTECTION

- Over-Voltage
- Under-Voltage
- Over-Current
- Over-Temperature
- Short-circuit (phase-phase)
- Short-circuit (phase-ground)

INPUTS/OUTPUTS

- Digital Fault Output
- Digital Inhibit Input
- Analog Current Monitor
- Analog Command Input
- Analog Current Reference

FEEDBACK SUPPORTED

Hall Sensors

MODES OF OPERATION

- Current
- COMMUTATION

Trapezoidal

- MOTORS SUPPORTED Three Phase (Brush
 - Three Phase (Brushless)
- Single Phase (Brushed, Voice Coil, Inductive Load) COMMAND SOURCE
 - PWM

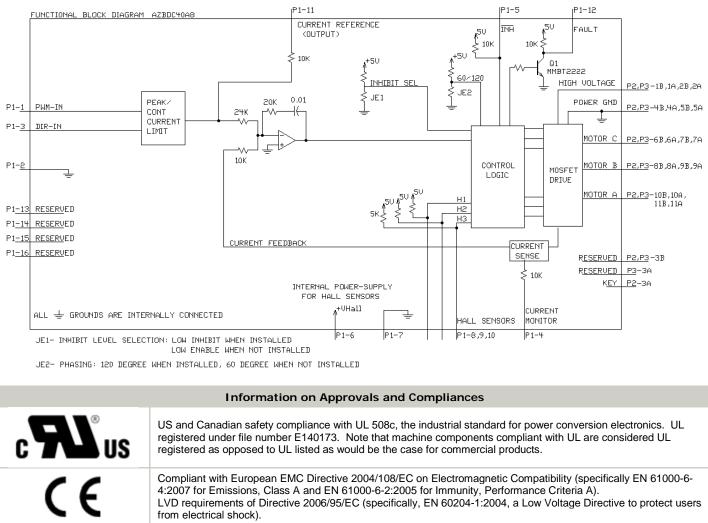
COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS





BLOCK DIAGRAM



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.





SPECIFICATIONS

Power Specifications			
Description Units		Value	
DC Supply Voltage Range	VDC	10 - 80	
DC Bus Under Voltage Limit	VDC	9	
DC Bus Over Voltage Limit	VDC	88	
Maximum Peak Output Current ¹	A	40	
Maximum Continuous Output Current	А	20	
Maximum Continuous Output Power	W	1520	
Maximum Power Dissipation at Continuous Current	W	80	
Minimum Load Inductance (Line-To-Line) ²	μH	100	
Internal Bus Capacitance ³	μF	141	
Low Voltage Supply Outputs	-	+6 VDC (30 mA)	
Switching Frequency	kHz	31	
Control Specifications			
Description	Units	Value	
Command Sources	-	PWM	
PWM Input Frequency Range	kHz	10 - 25	
Feedback Supported	-	Halls	
Commutation Methods	-	Trapezoidal	
Modes of Operation	-	Current	
Motors Supported	-	Three Phase (Brushless), Single Phase (Brushed, Voice Coil, Inductive Load)	
Hardware Protection	-	Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage, Under Voltage, Short Circuit (Phase-Phase & Phase-Ground)	
1	Mechanical	Specifications	
Description	Units	Value	
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL	
Size (H x W x D)	mm (in)	76.2 x 50.8 x 22.86 (3 x 2 x 0.9)	
Weight	g (oz)	119.7 (4.2)	
Heatsink (Base) Temperature Range ⁴	°C (°F)	0 - 75 (32 - 167)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
P1 Connector	-	16-pin, 2.54 mm spaced header	
P2 Connector	-	22-pin, 2.54 mm spaced, dual-row header	
P3 Connector	-	22-pin, 2.54 mm spaced, dual-row header	

Notes

1. Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive.

2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.

3. Requires a 470µF/100V electrolytic capacitor near the P2 Power Connector between High Voltage and Power Ground pins.

4. Additional cooling and/or heatsink may be required to achieve rated performance.





PIN FUNCTIONS

P1 - Signal Connector			
Pin	Name	Description / Notes	1/0
1	PWM / IN	10 – 25 kHz pulse width modulated digital input command (+5V). Input duty cycle commands the output current.	I
2	SIGNAL GND	Signal Ground	GND
3	DIRECTION	Direction Input (+5 V)	I
4	CURRENT MONITOR	Current Monitor. Analog output signal proportional to the actual current output. Scaling is 13.5 A/V. Measure relative to signal ground.	0
5	INHIBIT IN	TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices.	
6	+V HALL OUT	Low Power Supply For Hall Sensors (+6 V @ 30 mA). Referenced to signal ground. Short circuit protected.	
7	SIGNAL GND	Signal Ground	
8	HALL 1		I
9	HALL 2*	Single-ended Hall/Commutation Sensor Inputs (+5 V logic level)	
10	HALL 3		I
11	CURRENT REFERENCE	Measures the command signal to the internal current-loop. This pin has a maximum output of ±7.3 V when the drive outputs maximum peak current. Measure relative to signal ground.	
12	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, invalid Hall state, output short circuit, over voltage, over temperature, power-up reset.	
13	RESERVED		-
14	RESERVED	Reserved	
15	RESERVED		
16	RESERVED		

Р	in	Name	Description / Notes	1/0
1b	1a	HIGH VOLTAGE	DC Power Input. 3A Continuous Current Rating Per Pin. Requires at least 470 μF / 100 V	I
2b	2a	HIGH VOLTAGE	external electrolytic capacitor connected as close as possible to pins between High Voltage and Power Ground.	I
3b		NC	Not Connected (Reserved)	-
	3a	NC (KEY)	Key: No Connection (pin removed) for P2. Not Connected (Reserved) for P3.	
4b	4b	PWR GND	Deven Occurred (Occurrent Mith Circuit Occurred) - 24 Occutiences Occurrent Define Des Die	GND
5b	5a	PWR GND	Power Ground (Common With Signal Ground). 3A Continuous Current Rating Per Pin.	GND
6b	6a	MOTOR C		0
7b	7a	MOTOR C		0
8b	8a	MOTOR B	Motor Phase Outputs. Current output distributed equally across both P2 and P3 connectors	0
9b	9a	MOTOR B	 – 8 pins per motor phase, 3A continuous current carrying capacity per pin. 	0
10b	10a	MOTOR A		0
11b	11a	MOTOR A		

*For use with Single Phase (Brushed) motors, ground Hall 2 and only connect motor leads to Motor A and Motor B.

HARDWARE SETTINGS

Jumper Settings

Jumpers are SMT, 0 ohm resistors located on the underside of the drive PCB. By default, the drive is configured with the jumpers installed. Typical drive operation will not require the jumpers to be removed. Please contact the factory before jumper removal.

Jumper	Description	Configuration	
	SMT Jumper (0Ω Resistor)	Not Installed	Installed
JE1	Inhibit logic. Sets the logic level of inhibit pins. Labeled JE1 on the PCB of the drive.	Low Enable	Low Inhibit
JE2	Hall sensor phasing. Selects 120 or 60 degree commutation phasing. Labeled JE2 on the PCB of the drive.	60 degree	120 degree





MECHANICAL INFORMATION

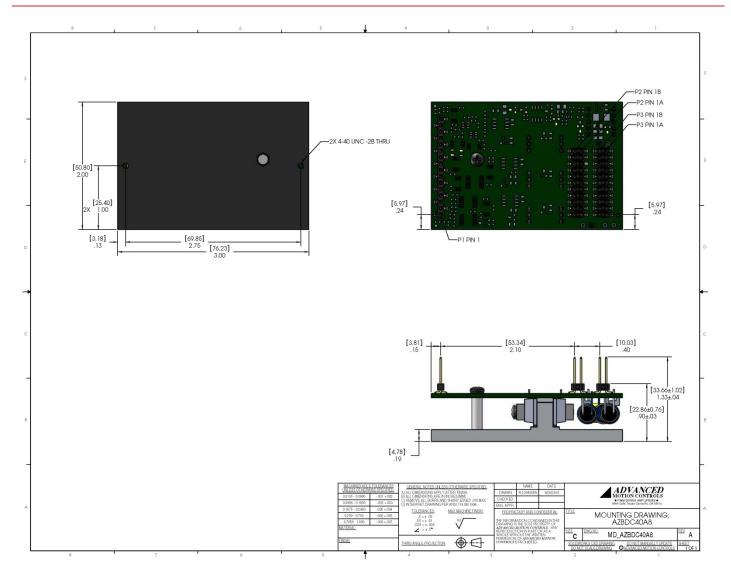
P1 - Signal Connector			
Connector Information 16-pin, 2.54 mm spaced header			
Details		Samtec: BCS-116-L-S-PE	
Mating Connector	Included with Drive	No	
		B B B B B B B B B B B B B B B B B B B	

P2 - Power Connector		
Connector Information 22-pin, 2.54 mm spaced, dual-row header		
Details		Samtec: BCS-111-L-D-PE
Mating Connector	Included with Drive	No
		PWR GND 5a PWR GND 4a HIGH VOLTAGE 1a HIGH VOLTAGE 1a HIGH VOLTAGE 1b PWR GND 5b PWR GND 5b

P3 - Power Connector			
Connector Information 22-pin, 2.54 mm spaced, dual-row header			
Nating Connector Details		Samtec: BCS-111-L-D-PE	
Mating Connector	Included with Drive	No	
	PWR GND 5a PWR GND 5a NC 3a HIGH VOLTAGE 1a HIGH VOLTAGE 1a PWR GND 5b PWR GND 5b		
	Toll Free Phone (877) SERV098 Toll Free Fax (877) SERV099 www.electromate.com sales@electromate.com		



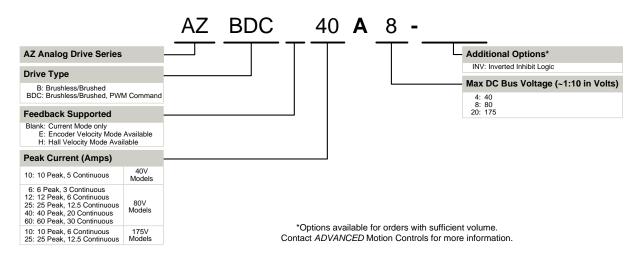
MOUNTING DIMENSIONS







PART NUMBERING INFORMATION



ADVANCED Motion Controls AZ series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, *ADVANCED* Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Modifications and Customized Products				
Integrat	ion of Drive into Motor Housing		Integrate OEM Circuitry onto Drive PCB	
Mount C	EM PCB onto Drive Without Cables		Custom Control Loop Tuned to Motor Characteristics	
Multi-ax	is Configuration for Compact System		Custom I/O Interface for System Compatibility	
Custom	PCB and Baseplate for Optimized Footprint		Preset Switches and Pots to Reduce User Setup	
🔺 RTV/Epo	oxy Components for High Vibration	-	Optimized Switching Frequency	
OEM Specific	ecified Connectors for Instant Compatibility	-	Ramped Velocity Command for Smooth Acceleration	

- OEM Specified Silkscreen for Custom Appearance
- Increased Thermal Limits for High Temp. Operation
- Remove Unused Features to Reduce OEM Cost
- Application Specific Current and Voltage Limits

Feel free to contact Applications Engineering for further information and details.



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CONTRACT CON

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