

FMP060-25-IPM

FlexPro[™] Series

Product Status: Active

SPECIFICATIONS

Current Peak 50 A Current Continuous 25 A

DC Supply Voltage 10 – 55 VDC Network Communication Ethernet IP



The **FMP060-25-IPM** is a servo drive and integration board assembly for a FE060-25-IPM FlexPro[™] series servo drive with IMPACT[™] architecture. Connections to the controller, motor, power, and feedback are simplified through the standard connectors. The assembly is housed within a case, allowing vertical and horizontal panel mounting orientations.

The **FMP060-25-IPM** offers full tuning control of all servo loops and is designed to drive brushed and brushless servo motors, stepper motors, and AC induction motors. The drive assembly accepts a variety of external command signals, or can use the built-in Motion Engine, an internal motion controller used with Sequencing and Indexing commands. Programmable digital and analog I/O are included to enhance interfacing with external controllers and devices.

The **FMP060-25-IPM** utilizes Ethernet IP network communication and is configured via USB. All drive and motor parameters are stored in non-volatile memory.

IMPACTTM (Integrated Motion Platform And Control Technology) combines exceptional processing capability and high-current components to create powerful, compact, feature-loaded servo solutions. IMPACTTM is used in all FlexProTM drives and is available in custom products as well.

FEATURES

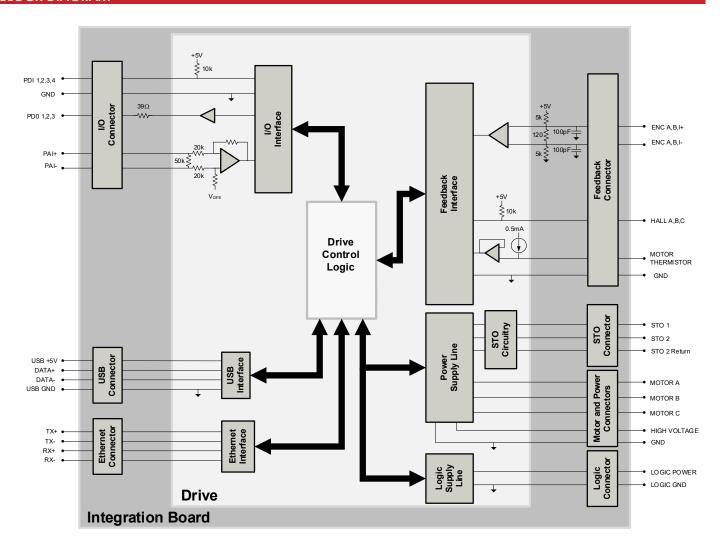
- Four Quadrant Regenerative Operation
- Programmable Gain Settings
- PIDF Velocity Loop
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching

- Dedicated Safe Torque Off (STO) Inputs
- Bridge Status, Fault and Network Status LEDs
- Integrated Cooling Fan
- Standard Connections for Easy Setup

Feedback Supported	 Incremental Encoder Hall Sensors ±10 VDC Position Tachometer (±10V) 	Motors Supported	Three PhaseSingle PhaseStepper	Modes of Operation	 Profile Modes Cyclic Synchronous Modes Current Velocity Position
Command Sources	 Over the Network ±10V Analog Sequencing Indexing Jogging 	Inputs / Outputs	 4 Programmable Digital Inputs 3 Programmable Digital Outputs 1 Programmable Analog Input 	Agency Approvals	RoHSUL (Pending)CE (Pending)TUV Rheinland (STO) (Pending)



BLOCK DIAGRAM



INFORMATION ON APPROVALS AND COMPLIANCES



The RoHS Directive restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

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	Electric	al Specifications		
Description	Units	Value		
Nominal DC Supply Voltage Range	VDC	12 – 48		
DC Supply Input Range	VDC	10 – 55		
DC Supply Undervoltage	VDC	8		
DC Supply Overvoltage	VDC	58		
Logic Supply Input Range (optional)	VDC	10 – 55		
Safe Torque Off Voltage	VDC	24		
Bus Capacitance	μF	221		
Maximum Peak Current Output ¹	A (Arms)	50 (35.3)		
Maximum Continuous Current Output ²	A (Arms)	25 (25)		
Efficiency at Rated Power	%	99		
Maximum Continuous Output Power	W	1361		
Maximum Power Dissipation at Rated Power	W	14		
Minimum Load Inductance (line-to-line) ³	μН	150 (@ 48VDC supply); 75 (@24VDC supply); 40 (@12VDC supply)		
Switching Frequency	kHz	20		
Maximum Output PWM Duty Cycle	%	83		
	Contro	l Specifications		
Description	Units	Value		
Communication Interfaces	-	Ethernet IP (USB for configuration)		
Command Sources	-	±10 V Analog, Over the Network, Sequencing, Indexing, Jogging		
Feedback Supported	_	Incremental Encoder, Hall Sensors, ±10 VDC Position, Tachometer		
<u>''</u>		(±10V)		
Commutation Methods	-	Sinusoidal, Trapezoidal		
Modes of Operation	-	Profile Modes, Cyclic Synchronous Modes, Current, Velocity, Position		
Motors Supported ⁴	-	Three Phase (Brushless Servo), Single Phase (Brushed Servo, Voice Coi Inductive Load), Stepper (2- or 3-Phase Closed Loop)		
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage		
Programmable Digital Inputs/Outputs	-	4/3		
Programmable Analog Inputs/Outputs	-	1/0		
Primary I/O Logic Level	VDC	24		
Current Loop Sample Time	μS	50		
Velocity Loop Sample Time	μS	100		
Position Loop Sample Time	μS	100		
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)		
Transfer England Transfer Transfer		cal Specifications		
Description	Units	Value		
Size (H x W x D)	mm (in)	190.50 x 88.90 x 41.28 (7.50 x 3.50 x 1.63)		
Weight	g (oz)	484.8 (17.1)		
Relative Humidity	-	0-95%		
Ambient Operating Temperature	°C (°F)	0 – 40 (32 – 104)		
Storage Temperature	°C (°F)	-20 - 85 (-4 - 185)		
Shock	-	15g, 11ms, Half-sine		
Vibration	-	30 grms for 5 minutes in 3 axes		
IP Rating	-	IP20		
P1 POWER CONNECTOR	-	2-port, 7.62mm spaced, enclosed, friction lock header		
P2 MOTOR POWER CONNECTOR	-	3-port, 7.62mm spaced, enclosed, friction lock header		
P3 IO CONNECTOR	-	15-pin high-density female D-Sub		
P4 FEEDBACK CONNECTOR	-	15-pin high-density female D-Sub		
P5 ETHERNET COMMUNICATION CONNECTORS	-	Shielded, Dual RJ-45 socket with LEDs		
P6 STO / LOGIC CONNECTOR	-	9-pin female D-sub		
P7 USB COMMUNICATION CONNECTOR	_	5-pin, Mini USB B Type port		
Notes		1 0 p, 000 b 1/p0 port		

- Notes

 1. Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.

 2. Continuous A_{rms} value attainable when RMS Charge-Based Limiting is used.

 3. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.

 4. Maximum motor speed for stepper motors is 600 RPM. Consult the hardware installation manual for 2-phase stepper wiring configuration.



PIN FUNCTIONS P1 - Power Connector Description / Notes Power Ground. (Common with Signal Ground) DC Supply Input (10-55 VDC). POWER GROUND GND 2 HIGH VOLTAGE 2-port, 7.62mm spaced, enclosed, friction POWER GROUND 2-Connector Information lock header HIGH VOLTAGE 1 -Amphenol: P/N ET0201500000G **Mating Connector Details** Mating Connector Included Yes

			P2 - Moto	or Power Connector	
Pin	No	ame		Description / Notes	I/O
1	MOTOR A		Motor Phase A.		0
2	MOTOR B		Motor Phase B.		0
3	MOTOR C		Motor Phase C.		0
Conr	nector Information	3-port, 7.62mm spaced, enclosed, friction lock header		MOTORA 1 — MOTORB 2 — MOTORC 3 —	
Mating	g Connector Details	Amphenol: P/N ET0301500000G			
Mating	Connector Included	Yes			

			P7 –	IO Connector	
Pin	No	ame		Description / Notes	I/O
1	PDI-1		General Purpose Prograr	mmable Digital Input	I
2	PDI-2		General Purpose Prograr	mmable Digital Input	I
3	1 0 0				I
4	PDI-4		General Purpose Prograr	mmable Digital Input	I
5	PDO-1		General Purpose Prograr	mmable Digital Output (24V Open Drain/1A)	0
6	PDO-2		General Purpose Programmable Digital Output (24V Open Drain/1A)		
7	PDO-3		General Purpose Programmable Digital Output (24V Open Drain/1A)		
8	RESERVED		Reserved.		
9	GND		Signal Ground. (Common with Power Ground)		
10	GND		Ground.	<u>'</u>	GND
11	PAI-1+		General Purpose Differer	I	
12	PAI-1-		±10VDC Range (12-bit Resolution)		
13	RESERVED		Reserved.		
14	RESERVED		Reserved.		
15	15 RESERVED Reserved.				-
Conn	ector Information	15-pin high-densit	y female D-Sub	PDO-2 6 5 PDO-1 PDO-3 7 4 PDI-4 RESERVED 8 3 PDI-3 GND 90 2 PDI-2 GND 10 1 PDI-1	·



			P4 – Fee	edback Connector	
Pin	No	ame		Description / Notes	I/O
1	HALL A			<u> </u>	1
2	2 HALL B		Single-ended Commute	ation Sensor Inputs.	I
3	HALL C				I
4	4 ENC 1 A+		Differential Incremental	I Encoder A	I
5	ENC 1 A-		Dillererillarincremental	i Liicodei A.	1
6	6 ENC 1 B+		Differential Incremental	I Fnooder B	1
	7 ENC 1 B-		Birererinar irrerementar	TENEGOGO B.	I
8	ENC 1 I+		Differential Incremental	l Encoder Index.	<u> </u>
9	ENC 1 I-				I
10	RESERVED		Reserved.		-
11			Reserved.		
12	GND		Ground.		GND
13	+5V OUT		+5V Supply Output. Short-circuit protected. (500ma total load capacity)		0
14	THERMISTOR RESERVED		Motor Thermal Protection. Reserved.		l
15	RESERVED		Reserved.		-
Conr	nector Information	15-pin high-densit	y female D-Sub	ENC B+ 6 5 ENC A- ENC B- 7 4 ENC A+ ENC H 8 3 HALL C ENC I- 9 2 HALL B RESERVED 10 1 HALL A	
Mating	Mating Connector Details TYCO: Plug P/N 7-5748677-2; Termin (loose) or 1658670				
Mating	Connector Included	No		11 RESERVED 12 GND 13 +5V OUT 14 THERMISTOR 15 RESERVED	

			P4 – Ethernet Com	nmunication Connectors	
Pin	No	ame		Description / Notes	I/O
1	RX+		Receiver + (100Base-TX)		I
2	RX-		Receiver - (100Base-TX)		I
3	TX+		Transmitter + (100Base-TX)		0
4	RESERVED		Reserved.		-
5	RESERVED		Reserved.		-
6	TX-		Transmitter - (100Base-TX)		0
7	RESERVED		Reserved.		-
8	8 RESERVED Reserved.				-
Conn	ector Information	Shielded, dual RJ	-45 socket with LEDs	LINK MODULE STATUS LINK NETWORK STATUS	
Mating	Connector Details	ector Details CAT 5 Cable		N OUT	
Mating	Connector Included	No		TX+ 6	

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			P6 – STC	O / Logic Connector	
Pin	No	ame		Description / Notes	I/O
1	STO RETURN		Safe Torque Off Return		STORET
2	STO-1 INPUT		Safe Torque Off – Input	1	I
3	STO RETURN		Safe Torque Off Return		STORET
4	STO-2 INPUT		Safe Torque Off – Input	2	I
5	RESERVED		Reserved.		-
6	LOGIC POWER		Logic Supply Input.		1
7	RESERVED		Reserved.		-
8	8 LOGIC GND Logic Supply Ground. (Common with Signal Ground)				GND
Conn	ector Information	9-pin, female D-su	b	5 RESERVED 4 STO-2INPUT 3 STORETURN 2 STO-1INPUT 1 STORETURN	
Mating	Connector Details	TYCO: P/N 205204-4 (Plug); 5748677-1 (Housing); 1658540-5 (Terminals – Loose); 1658540-4 (Terminals – Strip)			
Mating	Mating Connector Included No			6 LOGIC POWER 7 RESERVED 8 LOGIC GND 9 RESERVED	

			P7 – USB Comm	nunication Connector	
Pin	No	ame		Description / Notes	I/O
1	VBUS	Su	oply Voltage		0
2			ta -		1/0
3	DATA+	Do	Data +		1/0
4	4 RESERVED		Reserved.		-
5	GND	Gr	Ground		GND
Conr	nector Information	5-pin, Mini USB B Type port TYCO: 1496476-3 (2-meter STD-A to MINI-B ASSY) No		GND 5 — RESERVED 4 — DATA+ 3 —	
Mating	g Connector Details			DATA- 2 VBUS 1	
Mating	Connector Included				

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BOARD CONFIGURATION

Status LED Functions

LED	Description
STATUS	Indicates drive power bridge status. GREEN when DC bus power is applied and the drive is enabled. RED when the drive is in a fault state.
POWER	Indicates that power is available to the drive. GREEN when power is applied.

Communication Status LED Functions (on RJ-45 Communication Connectors)

LED	Description		
	Off	No power	
	Green	Device Operational	
MODULE STATUS	Flashing Green	Standby	
WODULE STATUS	Flashing Red	Minor Fault	
	Red	Major Fault	
	Flashing Green/Red	Self-test Self-test	
	Off	Not powered, no IP address	
	Flashing Green	No connections	
NETWORK STATUS	Green	Connected	
NEIWORK STATUS	Flashing Red	Connection Timeout	
	Red	Duplicate IP address	
	Flashing Green/Red	Self-test Self-test	

IP Address Selector Switches

Switch Diagram	Description					
3 ⁴⁵ 6.	et of the IP o	ddress of th	.168.1.xxx. Hexadecimal switch setting the drive within the Ethernet network. The purpose is not the setting of	•		
	SW1	SWO	Last Octet			
0 (41) 8 0 (41) 8 9	0	0	Address stored in NVM			
	0	1	001			
(vos vos	0	2	002			
0)4/6						
SW0 SW1	F	D	253			
	F	E	254			
	F	F	255			

Safe Torque Off (STO) Inputs

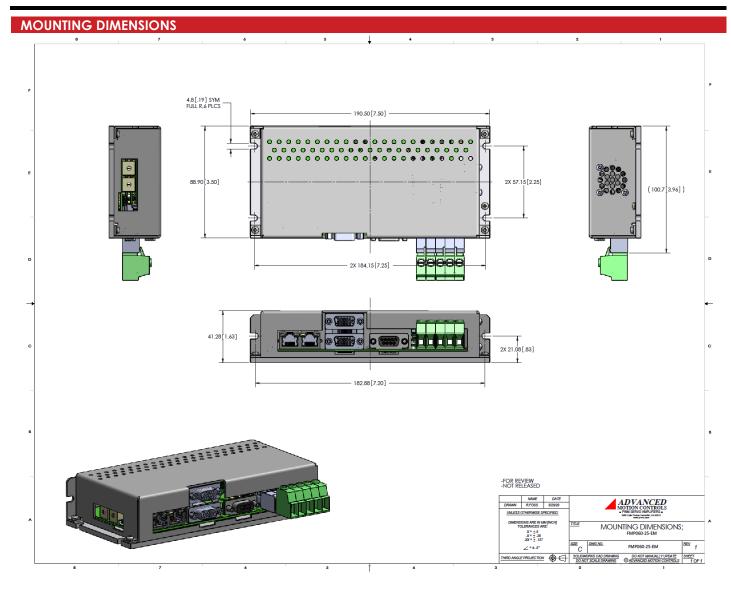
The Safe Torque Off (STO) inputs are dedicated +24VDC sinking single-ended inputs. For applications not using STO functionality, disabling of the STO feature is required for proper drive operation. STO may be disabled by installing the included mating connector for the STO connector and following the STO Disable wiring instructions as given in the hardware installation manual. Consult the hardware installation manual for more information. Alternatively, a dedicated STO Disable Key connector is available for purchase for applications where STO is not in use. Contact the factory for ordering information.

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CUSTOMIZATION INFORMATION

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- Optimized Footprint
- OEM Specified Connectors
- No Outer Case
- ✓ Increased Current Resolution
- Increased Temperature Range
- Custom Control Interface
- ✓ Integrated System I/O

- Tailored Project File
- ▲ Silkscreen Branding
- Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- Conformal Coating
- ▲ Multi-Axis Configurations
- Reduced Profile Size and Weight

Feel free to contact us for further information and details!

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.

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