

FD100-50-CM

FlexPro® Series
Product Status: Active



SPECIFICATIONS

Current Peak	100 A
Current Continuous	50 A
DC Supply Voltage	20 – 90 VDC
Network Communication	CANopen

The **FD100-50-CM** is a servo drive and development board assembly for a FE100-50-CM FlexPro® series servo drive with IMPACT™ architecture. Connections to the controller, motor, power, and feedback are simplified through the standard connectors featured on the board. The **FD100-50-CM** is ideal for prototyping and can be used in production and industrial environments as well.

The **FD100-50-CM** offers full tuning control of all servo loops and is designed to drive brushed and brushless servo motors, AC Induction, and closed loop stepper motors. The drive assembly accepts a variety of external command signals, or can use the built-in Motion Engine, an internal motion controller used with Sequencing and Indexing commands. Programmable digital and analog I/O are included to enhance interfacing with external controllers and devices.

The **FD100-50-CM** utilizes CANopen network communication and is configured via USB. All drive and motor parameters are stored in non-volatile memory.

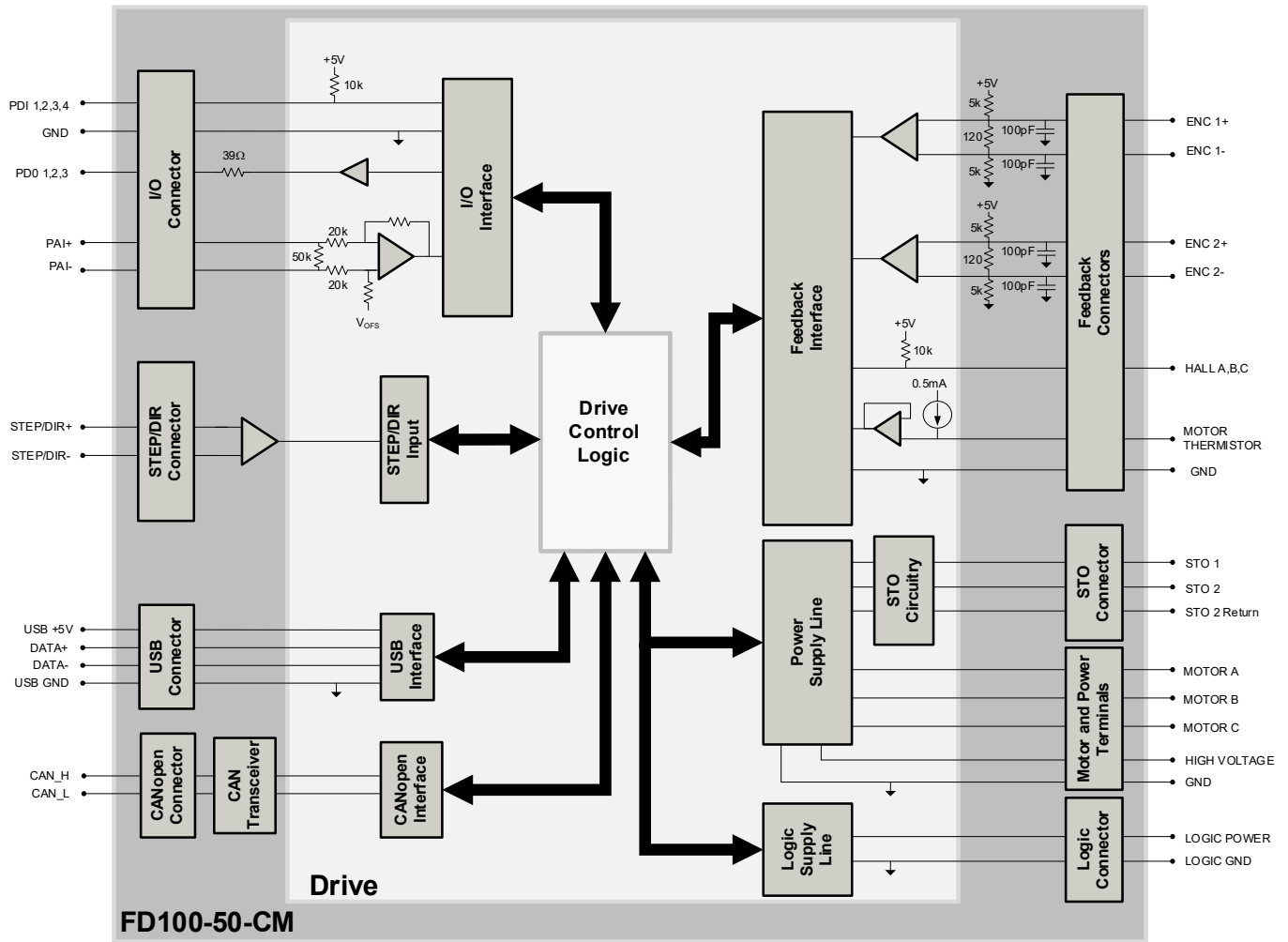
IMPACT™ (Integrated **M**otion **P**latform **A**nd **C**ontrol **T**echnology) combines exceptional processing capability and high-current components to create powerful, compact, feature-loaded servo solutions. IMPACT™ is used in all FlexPro® drives and is available in custom products as well.

FEATURES

- Follows the CAN in Automation (CiA) 301 Communications Profile and 402 Device Profile
- Four Quadrant Regenerative Operation
- Programmable Gain Settings
- PIDF Velocity Loop
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching
- Dedicated Safe Torque Off (STO) Inputs
- Bridge Status, Fault and Network Status LEDs
- I/O Status LEDs
- Standard Connections for Easy Setup

Feedback Supported	<ul style="list-style-type: none"> • Absolute Encoder <ul style="list-style-type: none"> ◦ BiSS C-Mode ◦ EnDat 2.2 • Incremental Encoder • Hall Sensors • Aux Incremental Encoder • ±10 VDC Position • Tachometer (±10V) 	Motors Supported	<ul style="list-style-type: none"> • Three Phase • Single Phase • AC Induction • Stepper 	Modes of Operation	<ul style="list-style-type: none"> • Profile Modes • Cyclic Synchronous Modes • Current • Velocity • Position • Interpolated Position Mode (PVT)
Command Sources	<ul style="list-style-type: none"> • Over the Network • ±10V Analog • Sequencing • Indexing • Jogging • Step & Direction • Encoder Following 	Inputs / Outputs	<ul style="list-style-type: none"> • 4 Programmable Digital Inputs • 3 Programmable Digital Outputs • 1 Programmable Analog Input 	Agency Approvals	<ul style="list-style-type: none"> • RoHS • UL (Pending) • CE (Pending) • TUV Rheinland (STO) (Pending)

BLOCK DIAGRAM



INFORMATION ON APPROVALS AND COMPLIANCES



The RoHS Directive restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

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SPECIFICATIONS

Description	Electrical Specifications		Value
	Units		
Nominal DC Supply Input Range	VDC	20 – 90	
DC Supply Undervoltage	VDC	15	
DC Supply Overvoltage	VDC	100	
Logic Supply Input Range (required)	VDC	10 - 55	
Safe Torque Off Voltage (Default)	VDC	5	
Bus Capacitance	μF	270	
Maximum Peak Current Output ¹	A (Arms)	100 (70.7)	
Maximum Continuous Current Output ²	A (Arms)	50 (50)	
Efficiency at Rated Power	%	99	
Maximum Continuous Output Power	W	4455	
Maximum Power Dissipation at Rated Power	W	45	
Minimum Load Inductance (line-to-line) ³	μH	150 (@ 48VDC supply); 75 (@24VDC supply)	
Switching Frequency	kHz	20	
Maximum Output PWM Duty Cycle	%	83	

Description	Control Specifications		Value
	Units		
Communication Interfaces	-	CANopen (USB for configuration)	
Command Sources	-	±10 V Analog, Over the Network, Sequencing, Indexing, Jogging, Step & Direction, Encoder Following	
Feedback Supported	-	Absolute Encoder (BiSS C-Mode, EnDat 2.2), Incremental Encoder, Hall Sensors, Auxiliary Incremental Encoder, ±10 VDC Position, Tachometer (±10V)	
Commutation Methods	-	Sinusoidal, Trapezoidal	
Modes of Operation	-	Profile Modes, Cyclic Synchronous Modes, Current, Velocity, Position, Interpolated Position Mode (PVT)	
Motors Supported ⁴	-	Three Phase (Brushless Servo), Single Phase (Brushed Servo, Voice Coil, Inductive Load), Stepper (2- or 3-Phase Closed Loop), AC Induction (Closed Loop Vector)	
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs	-	4/3	
Programmable Analog Inputs/Outputs	-	1/0	
Primary I/O Logic Level	-	5 VDC, not isolated	
Current Loop Sample Time	μs	50	
Velocity Loop Sample Time	μs	100	
Position Loop Sample Time	μs	100	
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)	

Description	Mechanical Specifications		Value
	Units		
Size (H x W x D)	mm (in)	133.4 x 127.0 x 15.0 (5.25 x 5.00 x 0.60)	
Weight	g (oz)	280.7 (9.9)	
Ambient Operating Temperature Range ⁵	°C (°F)	0 – 65 (32 – 149)	
Storage Temperature Range	°C (°F)	-40 – 85 (-40 – 185)	
Relative Humidity	-	0-95%, non-condensing	
P1 LOGIC POWER CONNECTOR	-	2-port 3.5 mm spaced screw terminal	
P2 USB COMMUNICATION CONNECTOR	-	USB Type C, horizontal entry	
P4 CANopen COMMUNICATION CONNECTOR	-	9-pin male D-sub	
P5 STO CONNECTOR	-	8-pin 2.00 mm spaced, enclosed, friction lock header	
P6 INPUTS CONNECTOR	-	8-port 3.5 mm spaced insert connector	
P7 OUTPUTS CONNECTOR	-	8-port 3.5 mm spaced insert connector	
P8 STEP/DIR CONNECTOR	-	8-port 3.5 mm spaced insert connector	
P9 FEEDBACK 2 CONNECTOR	-	15-pin vertical D-Sub	
P10 FEEDBACK 1 CONNECTOR	-	15-pin vertical D-Sub	
P11/12/13 MOTOR POWER TERMINALS	-	3x Hex Screw Lug	
P14/15 DC POWER TERMINALS	-	2x Hex Screw Lug	

Notes

1. Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
2. Continuous I_{Arms} value attainable when RMS Charge-Based Limiting is used.
3. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
4. Maximum motor speed for stepper motors is 600 RPM. Consult the hardware installation manual for 2-phase stepper wiring configuration.
5. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

P1 – Logic Power Connector

Pin	Name	Description / Notes	I/O
1	LOGIC PWR	Logic Supply Input (10 – 55VDC) (required)	I
2	LOGIC GND	Ground	GND

Connector Information	2-port Screw Terminal	
Mating Connector Details	N/A	
Mating Connector Included	N/A	

P2 – USB Communication Connector

Pin	Name	Description / Notes	I/O
1	VBUS	Supply Voltage	O
2	DATA-	Data -	I/O
3	DATA+	Data +	I/O
4	RESERVED	Reserved.	-
5	GND	Ground	GND

Connector Information	5-pin, Mini USB B Type port	
Mating Connector Details	TYCO: 1496476-3 (2-meter STD-A to MINI-B ASSY)	
Mating Connector Included	No	

P4 – CANopen / RS485 Communication Connectors

Pin	Name	Description / Notes	I/O
1	RS485 RX+	Receive Line (RS-485)	I
2	CAN_L	CAN_L Line (Dominant Low)	I
3	GND	Ground	GND
4	RS485 TX+	Transmit Line (RS-485)	O
5	CAN_SHLD	CAN shield, connected to Chassis	-
6	RS485 RX- / RS232 RX	Receive Line (RS-232 or RS-485)	I
7	CAN_H	CAN_H Line (Dominant High)	I
8	RS485 TX- / RS232 TX	Transmit Line (RS-232 or RS-485)	O
9	RESERVED	Reserved	-

Connector Information	9-pin male D-sub	
Mating Connector Details	AMP: Plug P/N 205203-3; Housing P/N 748677-1; Terminals P/N 745253-6 (loose) or 745253-2 (strip)	
Mating Connector Included	No	

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P5 – STO Connector			
Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved.	-
2	RESERVED	Reserved.	-
3	STO RETURN	Safe Torque Off Return	STORET
4	STO-1 INPUT	Safe Torque Off – Input 1	I
5	STO RETURN	Safe Torque Off Return	STORET
6	STO-2 INPUT	Safe Torque Off – Input 2	I
7	RESERVED	Reserved.	-
8	RESERVED	Reserved.	-

Connector Information	8-port, 2.00 mm spaced, enclosed, friction lock header	
Mating Connector Details	Molex: P/N 51110-0860 (housing); 50394-8051 (pins)	
Mating Connector Included	Yes	

P6 – Inputs Connector			
Pin	Name	Description / Notes	I/O
1	PDI-1	General Purpose Programmable Digital Input	I
2	PDI-2	General Purpose Programmable Digital Input	I
3	PDI-3	General Purpose Programmable Digital Input	I
4	PDI-4	General Purpose Programmable Digital Input	I
5	GND	Ground.	GND
6	GND	Ground.	GND
7	PAI-1+	General Purpose Differential Programmable Analog Input or Reference Signal Input. ±10VDC Range (12-bit Resolution)	I
8	PAI-1-		I

Connector Information	8-port 3.5 mm spaced insert connector	
Mating Connector Details	Phoenix Contact: P/N 1840421	
Mating Connector Included	Yes	

P7 – Outputs Connector			
Pin	Name	Description / Notes	I/O
1	PDO-1	General Purpose Programmable Digital Output (TTL/8mA)	O
2	PDO-2	General Purpose Programmable Digital Output (TTL/8mA)	O
3	PDO-3	General Purpose Programmable Digital Output (TTL/8mA)	O
4	+5V USER	+5V Supply Output. Short-circuit protected. (300ma total load capacity shared between P7-4, P8-7, P9-13, and P10-13)	O
5	GND	Ground.	GND
6	GND	Ground.	GND
7	RESERVED	Reserved	-
8	RESERVED	Reserved	-

Connector Information	8-port 3.5 mm spaced insert connector	
Mating Connector Details	Phoenix Contact: P/N 1840421	
Mating Connector Included	Yes	

P8 – STEP/DIR Connector			
Pin	Name	Description / Notes	I/O
1	STEP +	Differential Step Input	I
2	STEP -		I
3	DIR +	Differential Direction Input	I
4	DIR -		I
5	RESERVED	Reserved	-
6	RESERVED		-
7	+5V USER	+5V Supply Output. Short-circuit protected. (300ma total load capacity shared between P7-4, P8-7, P9-13, and P10-13)	O
8	GND	Ground.	GND

Connector Information	8-port 3.5 mm spaced insert connector	
Mating Connector Details	Phoenix Contact: P/N 1840421	
Mating Connector Included	Yes	

P9 – Feedback 2 Connector			
Pin	Incremental Encoder	Description / Notes	I/O
1	HALL A	Single-ended Commutation Sensor Inputs. Signals shared with Feedback 1 connector. Use only Hall connections on either Feedback 1 or Feedback 2.	I
2	HALL B		I
3	HALL C		I
4	ENC 2 A+	Differential Incremental Encoder A.	I
5	ENC 2 A-		I
6	ENC 2 B+	Differential Incremental Encoder B.	I
7	ENC 2 B-		I
8	ENC 2 INDEX+	Differential Incremental Encoder Index.	I
9	ENC 2 INDEX-		I
10	RESERVED	Reserved.	-
11	RESERVED	Reserved.	-
12	GND	Ground.	GND
13	+5V USER	+5V Supply Output. Short-circuit protected. (300ma total load capacity shared between P7-4, P8-7, P9-13, and P10-13)	O
14	THERMISTOR	Motor Thermal Protection. Select which Thermistor pin is active using DIP Switch SW6 (see Board Configuration section below). Only one Thermistor pin between Feedback 1 and Feedback 2 Connector can be active.	I
15	RESERVED	Reserved.	-

Connector Information	15-pin, high-density, female D-sub	
Mating Connector Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)	
Mating Connector Included	No	

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P10 – Feedback 1 Connector

Pin	Absolute Encoder	Incremental Encoder	Description / Notes	I/O
1	HALL A	HALL A	Single-ended Commutation Sensor Inputs. Signals shared with Feedback 2 connector. Use only Hall connections on either Feedback 1 or Feedback 2.	I
2	HALL B	HALL B		I
3	HALL C	HALL C		I
4	ENC 1 DATA+	ENC 1 A+	Differential Data Line for Absolute Encoders (BiSS: SLO+/-) or Differential Incremental Encoder A.	I
5	ENC 1 DATA-	ENC 1 A-		I
6	ENC 1 CLOCK+	ENC 1 B+	Differential Clock Line for Absolute Encoders (BiSS: MA+/-) or Differential Incremental Encoder B.	I
7	ENC 1 CLOCK-	ENC 1 B-		I
8	ENC 1 REF MARK+	ENC 1 I+	Differential Reference Mark for Absolute Encoders (Leave open for BiSS and EnDat 2.2) or Differential Incremental Encoder Index.	I
9	ENC 1 REF MARK-	ENC 1 I-		I
10	RESERVED	RESERVED	Reserved.	-
11	RESERVED	RESERVED	Reserved.	-
12	GND	GND	Ground.	GND
13	+5V USER	+5V USER	+5V Supply Output. Short-circuit protected. (300ma total load capacity shared between P7-4, P8-7, P9-13, and P10-13)	O
14	THERMISTOR	THERMISTOR	Motor Thermal Protection. Select which Thermistor pin is active using DIP Switch SW6 (see Board Configuration section below). Only one Thermistor pin between Feedback 1 and Feedback 2 Connector can be active.	I
15	RESERVED	RESERVED	Reserved.	-

Connector Information	15-pin, high-density, female D-sub	
Mating Connector Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)	
Mating Connector Included	No	

P11/12/13 - Motor Power Terminals

Pin	Name	Description / Notes	I/O
1	MOTOR A	Motor Phase A.	O
2	MOTOR B	Motor Phase B.	O
3	MOTOR C	Motor Phase C.	O

Connector Information	Bushings with M4 Screw	
Mating Connector Details	N/A	
Mating Connector Included	N/A	

P14/15 - DC Power Terminals

Pin	Name	Description / Notes	I/O
1	HV	DC Supply Input (10-55 VDC).	I
2	POWER GND	Ground.	GND

Connector Information	Bushings with M4 Screw	
Mating Connector Details	N/A	
Mating Connector Included	N/A	

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BOARD CONFIGURATION
Status LED Functions

LED	Description
STAT	Indicates drive power bridge status. GREEN when DC bus power is applied and the drive is enabled. RED when the drive is in a fault state.
LOGIC PWR	Indicates that +5V logic power is available to the drive. GREEN when +5V logic power is available.
EMA	Indicates whether the Emulated Encoder Output functionality is active. GREEN for Emulated Encoder Output active. OFF for Step & Direction Input or PWM & Direction Input.

Input/Output LED Functions

LED	Description
DI1 – DI4	Indicates digital input status. GREEN when the corresponding digital input is active.
DO1 – DO3	Indicates digital output status. BLUE when the corresponding digital output is active

Address Selector Switches

Switch Diagram	Description																								
	<p>Hexadecimal switch settings correspond to the CANopen Node ID. Allowable CANopen Node ID range using the rotary switches is 1 - 63. Node IDs above 63 can be set via ACE setup software or network commands and stored to NVM (up to a Node ID of 127). Setting the rotary switches to zero will use the address stored in NVM.</p> <table border="1"> <thead> <tr> <th>SW3</th> <th>SW4</th> <th>Node ID</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Address stored in NVM</td> </tr> <tr> <td>0</td> <td>1</td> <td>001</td> </tr> <tr> <td>0</td> <td>2</td> <td>002</td> </tr> <tr> <td>...</td> <td>...</td> <td>...</td> </tr> <tr> <td>3</td> <td>D</td> <td>61</td> </tr> <tr> <td>3</td> <td>E</td> <td>62</td> </tr> <tr> <td>3</td> <td>F</td> <td>63</td> </tr> </tbody> </table>	SW3	SW4	Node ID	0	0	Address stored in NVM	0	1	001	0	2	002	3	D	61	3	E	62	3	F	63
SW3	SW4	Node ID																							
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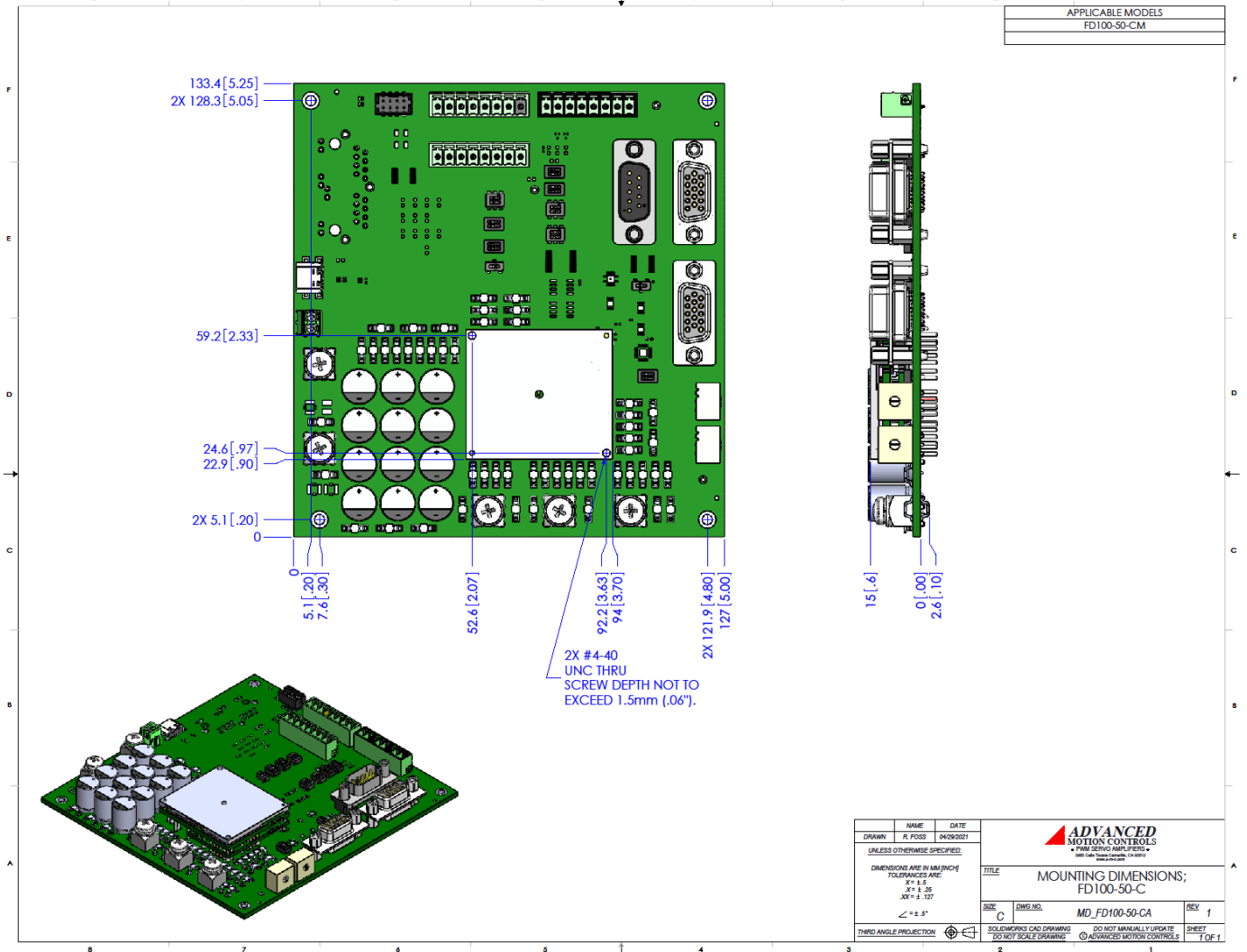
DIP Switches

Switch	Description	ON	OFF
SW6	Motor Thermistor Selection. Note that both switches on SW6 must be set to the same position for proper operation.	Uses the motor thermistor reading from P9 – Feedback 2 Connector	Uses the motor thermistor reading from P10 – Feedback 1 Connector
SW9	CAN Termination. The last device in a CAN network requires termination. Note that both switches on SW9 must be set to the same position for proper operation.	Terminated	Not terminated
SW10	CAN Communication Selection. Note that all 4 switches of SW10 and SW11 must be set to the same position for proper operation.	RS232/485	CAN
SW11			
SW12	Hall Sensor Selection	Uses the Hall Sensor signals from P9 – Feedback 2 Connector	Uses the Hall Sensor signals from P10 – Feedback 1 Connector

Safe Torque Off (STO) Inputs

The Safe Torque Off (STO) inputs are dedicated +5VDC sinking single-ended inputs. For applications not using STO functionality, disabling of the STO feature is required for proper drive operation. STO may be disabled by installing the included mating connector for the STO connector and following the STO Disable wiring instructions as given in the hardware installation manual. Consult the hardware installation manual for more information. Alternatively, a dedicated STO Disable Key connector is available for purchase for applications where STO is not in use. Contact the factory for ordering information.

MOUNTING DIMENSIONS



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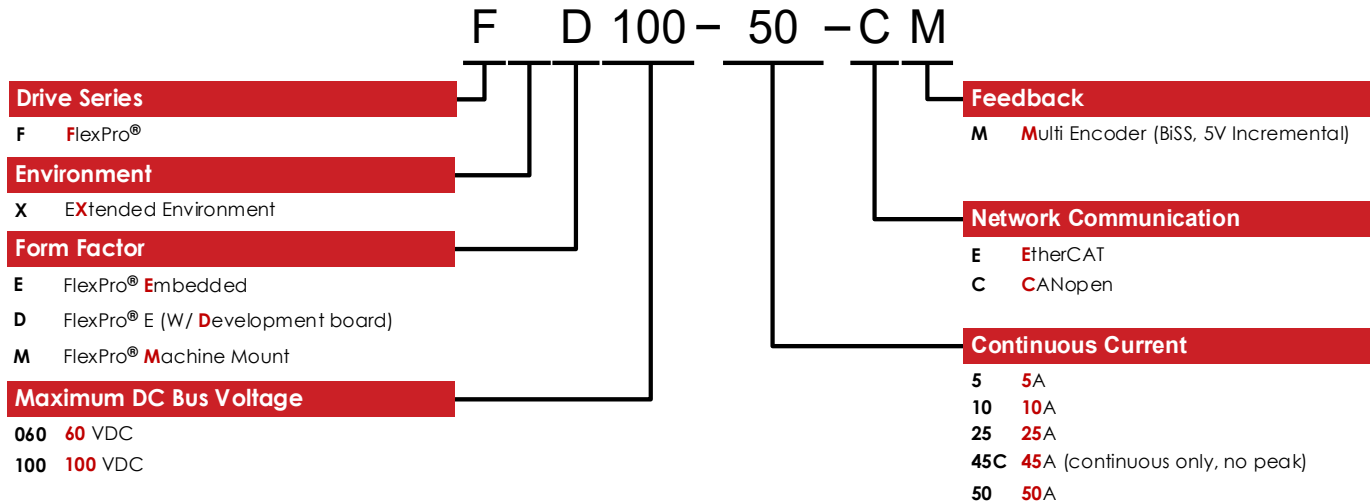
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PART NUMBERING AND CUSTOMIZATION INFORMATION



ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- | | |
|--|--|
| <ul style="list-style-type: none"> ▲ Optimized Footprint ▲ Private Label Software ▲ OEM Specified Connectors ▲ No Outer Case ▲ Increased Current Resolution ▲ Increased Temperature Range ▲ Custom Control Interface ▲ Integrated System I/O | <ul style="list-style-type: none"> ▲ Tailored Project File ▲ Silkscreen Branding ▲ Optimized Base Plate ▲ Increased Current Limits ▲ Increased Voltage Range ▲ Conformal Coating ▲ Multi-Axis Configurations ▲ Reduced Profile Size and Weight |
|--|--|

Feel free to contact us for further information and details!

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.

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