

# TECNOTION<sup>®</sup>

THE LINEAR MOTOR COMPANY

*Frameless torque motor series*



# QUALITY AND SERVICE DELIVERED WORLDWIDE

## [ TECNOTION ]

Tecnotion is *the* global authority on direct drive motor technology. We are the world's only unbundled manufacturer of linear and torque motors. As a former part of Philips, we specialize solely in the development and production of linear and torque motors. Because of this, our expertise, customer service and product quality are unmatched.

We have a global presence, with production plants in the Netherlands and China and local representation around the world. This ensures short delivery times and high quality support, wherever you are located.

When you do business with Tecnotion, you have a team of highly skilled sales and application engineers at your disposal. They help you from your initial prototype all the way to the application of our products and beyond.

Whatever your needs, you can rely on Tecnotion as a solid, reliable partner.





## [ SALES SUPPORT ]

At Tecnotion we understand that each application of our motors is a unique case with specific requirements and demands.

Our sales and application engineers have extensive experience with a wide range of application types and collaborate on a high level with our customers to make sure you get the solution that best fits your requirements.

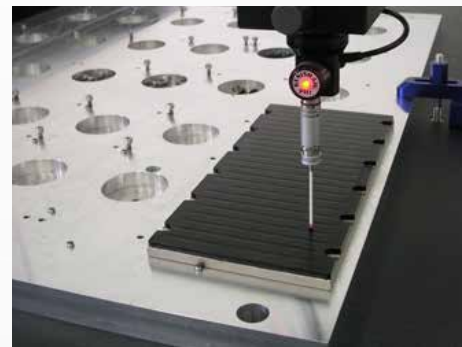
Additionally our specialized simulation tool is available to help you find your way through our wide range of motors and analyze/test out different motor types within your application specifications.

## [ INNOVATION ]

We have an in-house R&D department, which is continuously pushing the boundaries of technology and taking our products to the next level. This translates directly to our high level of understanding of manufacturing processes.

Apart from our “off-the-shelf” range of standard motors, we can also design and manufacture custom made motors for high profile projects or OEM applications that require a tailor-made solution.

All our custom motors are built to the same high standards that characterize our standard range of products.



## [ MANUFACTURING ]

Manufacturing of our standard range of motors takes place at our modern plant in China, where we are able to produce in high volume at very competitive rates.

At our competence centre and headquarters in the Netherlands we specialize in advanced technology. This is where we do our research and development and where custom motors are built with extreme accuracy in our special state of the art clean room environment.

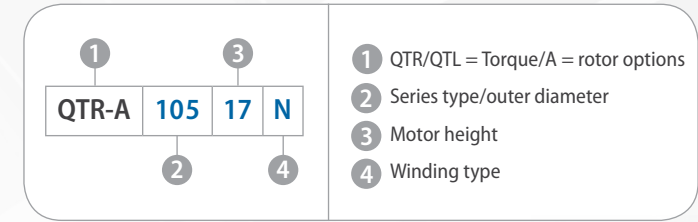
Tecnotion is committed to excellence. Both of our plants are ISO 9001 certified and comply to the highest quality standards possible.

## [ GLOBAL LOGISTICS ]

We always have our most popular products in stock in our warehouses in both the Netherlands and China.

Our logistics department can ship to you from both locations, making short delivery times possible across the globe, even when markets are ramping.





### QTR-A 65 and 78 series

*See page 13*

The QTR-A 65 and 78 are the smallest motors from our torque range. The largest QTR-A 78-60 motor offers a ultimate torque of 10.85 Nm. Compact sizing and low voltage support makes the QTR 65 motor ideal for robotics applications. Small build-space and a large 29mm inner diameter make

the QTR 78 motor a favorite in semiconductor machinery. To provide maximum flexibility and integration the motor is equipped with flying leads instead of a power cable.

These motor series comes in two diameters: 65 and 78 mm and four heights: 17, 25, 34 and 60 mm.



### QTR-A 105-133-160 series

*See page 17*

Our medium range motors are available with a range of options. Different winding types are available, optimizing back EMF. A digital Hall sensor can be used as a 'wake and shake' replacement, simplifying the startup of the QTR motor. The largest QTR-A 160-60 motor, excels with a 91.6 Nm ultimate torque.

Various applications such as in medical, testing equipment, and factory automation benefit from the large inner diameter and the high peak torque of the series.

These motor series comes in three diameters: 105, 133 and 160 mm and four heights: 17, 25, 34 and 60 mm.



### QTL-A 210-230-290-310 series

*See page 23*

The QTL motor series are our largest torque motors up to date, yet very compact for the generated torque. The QTL is frameless as all our QTR motors and therefore it can be integrated directly into the machine structure, while the spacious open inner diameter enables wire and cable feed-through. The series are suitable

for a variety of markets including rotary indexing tables, printing machinery and materials handling. Available with (QTL 230 and 310) or without cooling ring (QTL 210 and 290).

The QTL-A motor series comes in four diameters (210, 230, 290 and 310 mm) and three heights (65, 85 and 105 mm).

# Frameless torque motors










## Torque motor power range

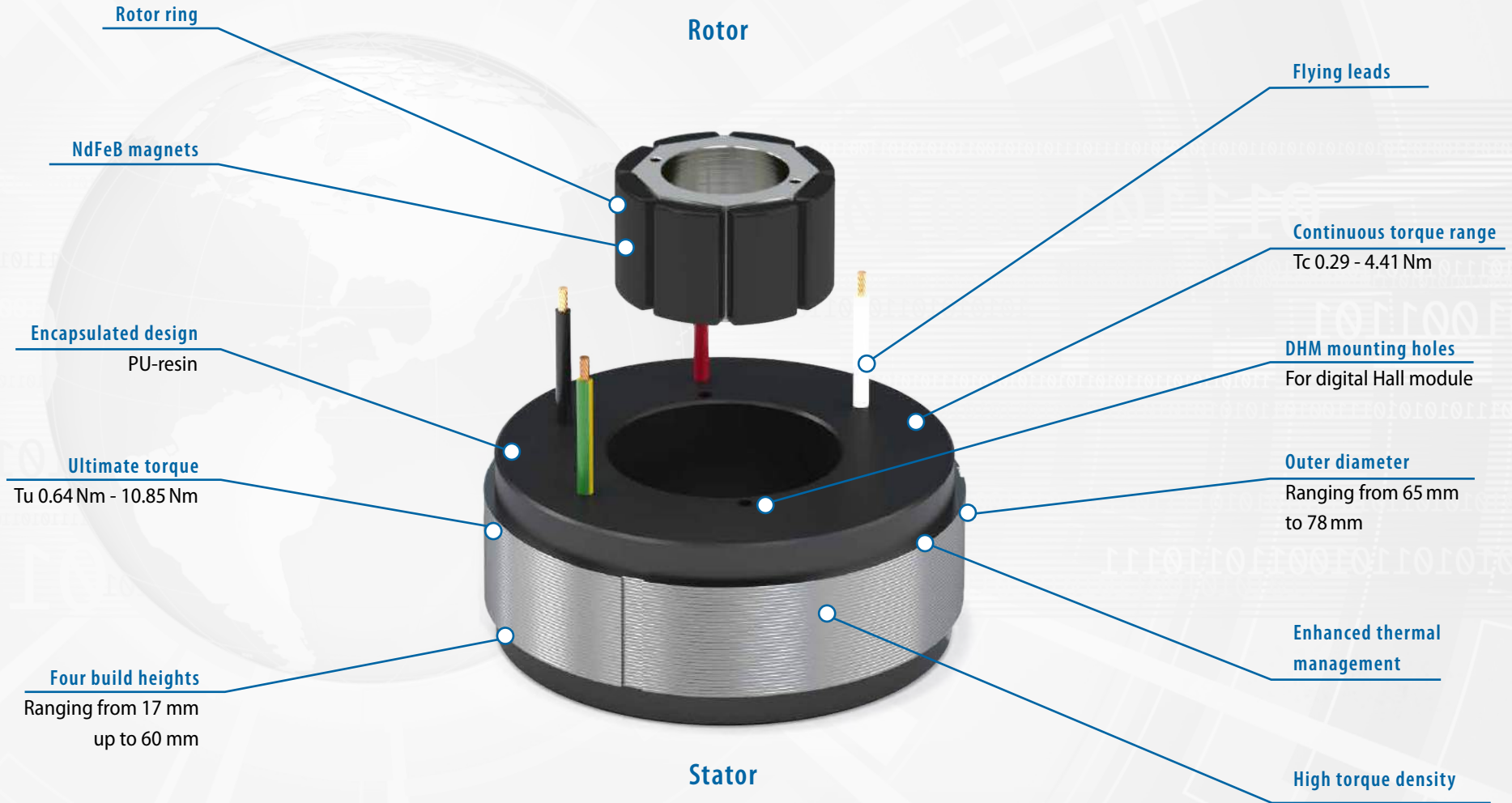


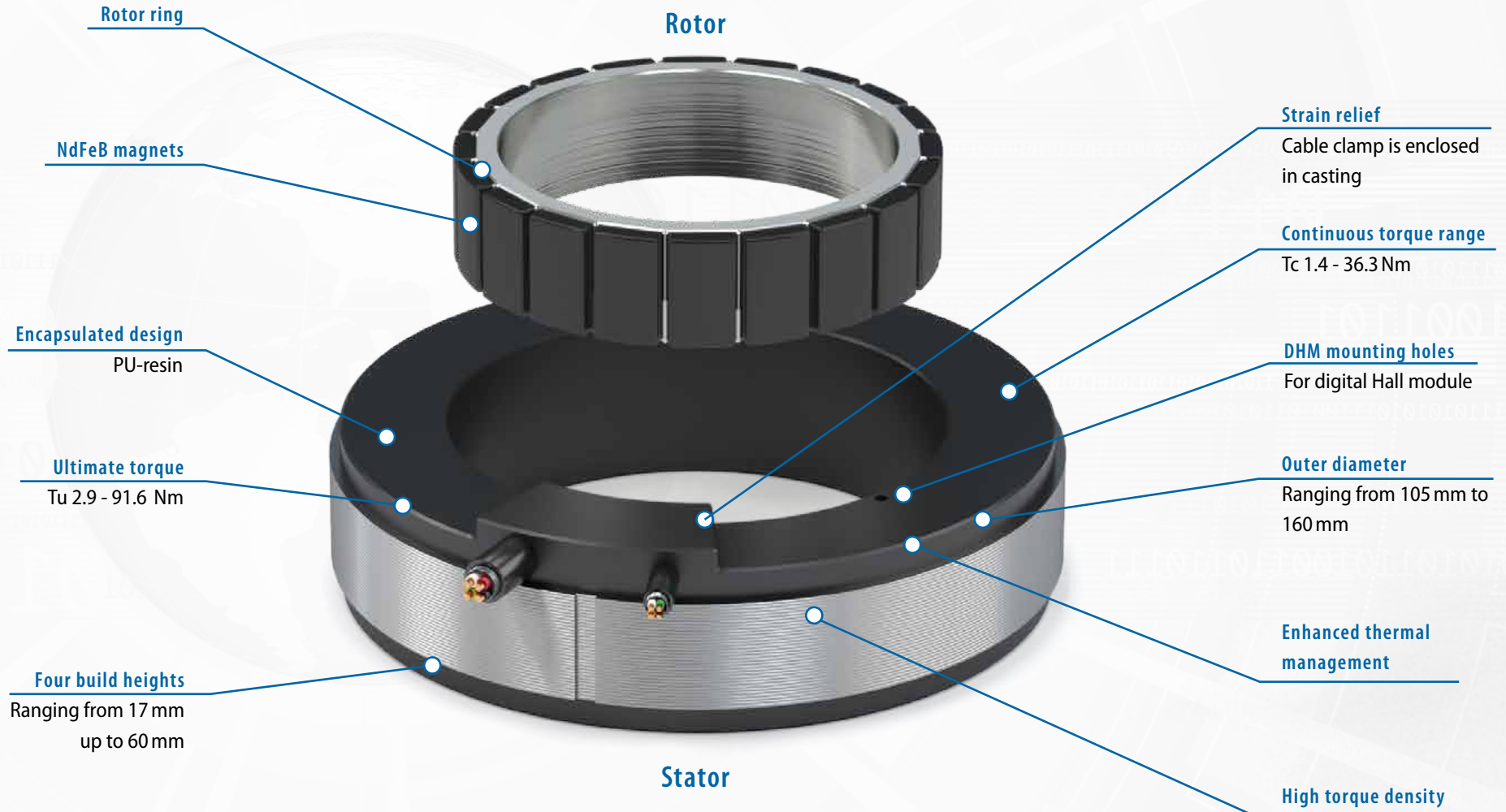
Ultimate torque

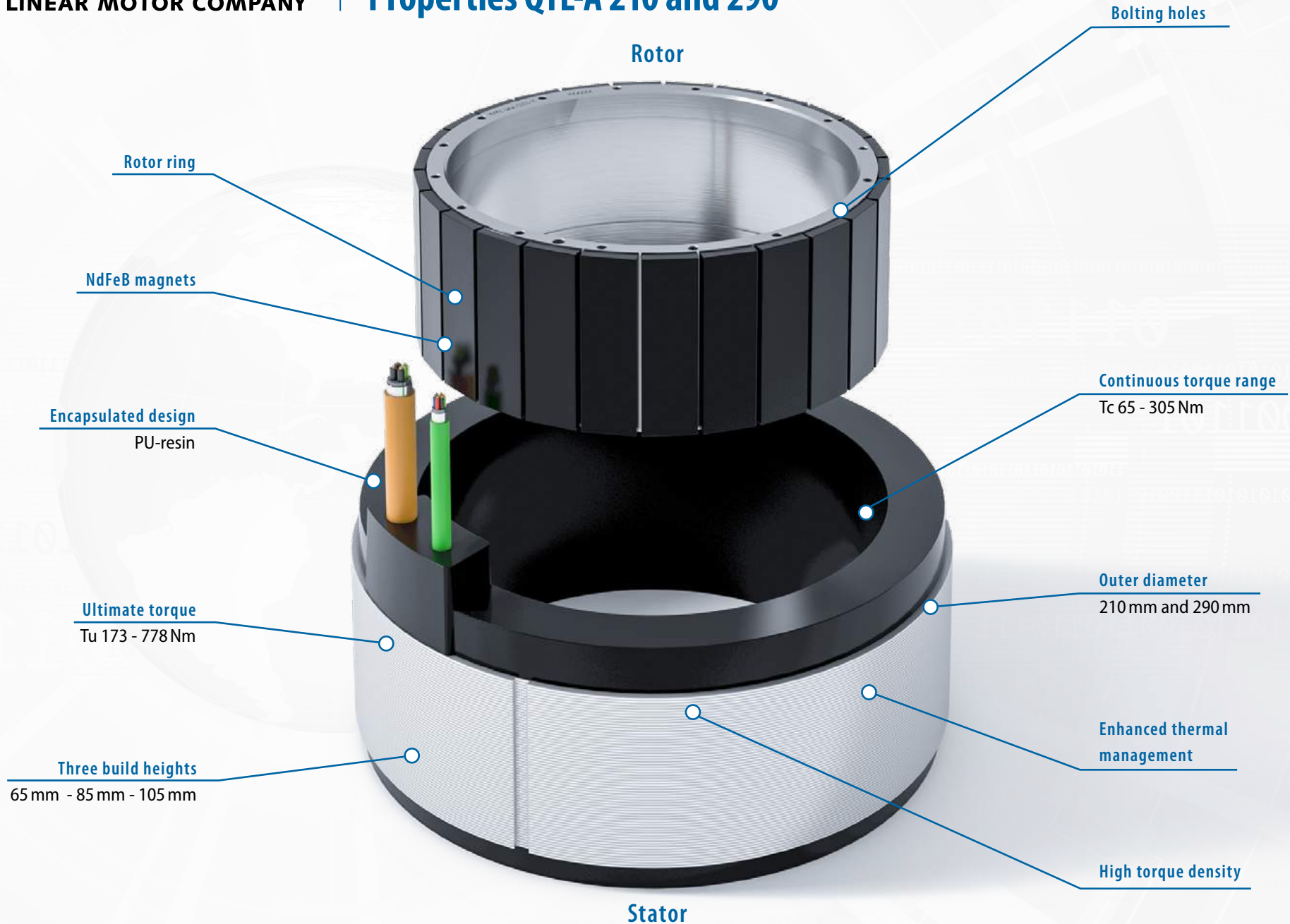


Continuous torque

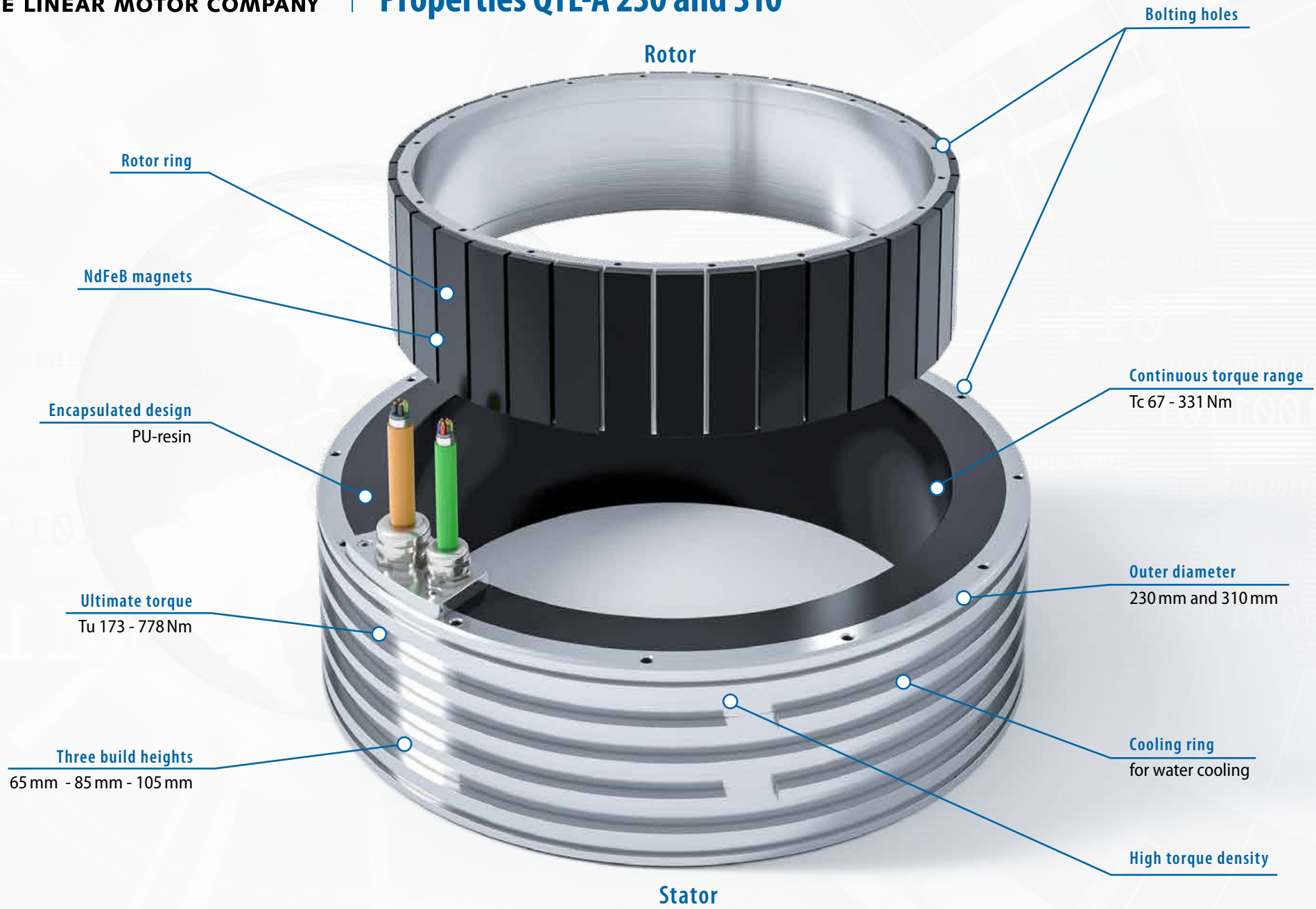
 <b>QTR-65 Series</b>	0.64 - 5.47 Nm				
	0.29 - 2.31 Nm				
 <b>QTR-78 Series</b>		1.22 - 10.85 Nm			
	0.57 - 4.41 Nm				
 <b>QTR-105 Series</b>		2.9 - 28.4 Nm			
		1.4 - 12 Nm			
 <b>QTR-133 Series</b>		5.6 - 55.5 Nm			
		2.6 - 21.9 Nm			
 <b>QTR-160 Series</b>		9.3 - 91.6 Nm			
		4.1 - 36.3 Nm			
 <b>QTL-210 Series</b>			173 - 346 Nm		
			65 - 142 Nm		
 <b>QTL-230 Series</b>			173 - 346 Nm		
			67 - 147 Nm		
 <b>QTL-290 Series</b>			389 - 778 Nm		
			140 - 305 Nm		
 <b>QTL-310 Series</b>			389 - 778 Nm		
			151 - 331 Nm		
	0.2 Nm	1 Nm	10 Nm	100 Nm	1000 Nm











## Features

### Tecnotion's QTR torque motor performance advantages

The direct drive technology of brushless torque motors is a perfect way to enhance productivity, accuracy, and dynamic performance of applications. The technology lowers costs, makes designs slimmer, and reduce wear and tear. Torque motors eliminate the need for mechanical transmissions like gearboxes, belts and speed reducers. Between rotor and stator there is no contact, this means no mechanical wear.

**Direct drive**  
Higher stiffness no backlash.

**Ultra thin design**  
The lower build height allows to build a flatter axis, resulting in less tipping and settling time. Extraordinary flexibility in designing the motor into small spaces.

**Tecnotion QTR has the highest torque density in the market**  
More torque in a smaller packing means lowering footprint.

**Low thermal resistance**  
Allowing good heat transfer, achieving an extremely high continuous torque when using a decent size heatsink or active cooling.

**Low cogging value, low total harmonic distortion THD**  
For smooth motion and position accuracy in your application.

**Encapsulated design**  
No open coil wires which can be damaged or that need to be covered up for safety reasons.



**Shielded cable with strain relief**

No shielding EMC issues with loose wires. No risk to damage the motor by accidentally pulling the cable.

**Low stator and rotor mass**

Lower masses increase the dynamics and response of the system by lowering the inertia. It hands the opportunity to improve entire stage designs! And as a result, lowering an applications cost of ownership.

**Large inner diameter**

Allows easy integration of a large number of cables and hoses or allows large shaft fittings.

**High voltage insulated, up to 300VDC/600VDC bus voltage**

Enabling the use of a wide range of servo drives, and power supplies.

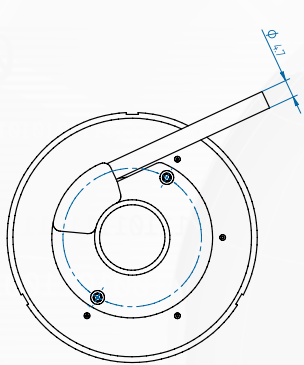
**Good product repeatability**

All motors have specifications with extremely little variation between them.

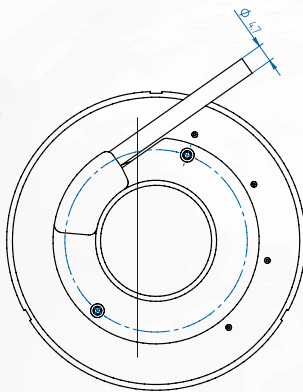
**100% QC**

All products are 100% mechanically and electrically tested.

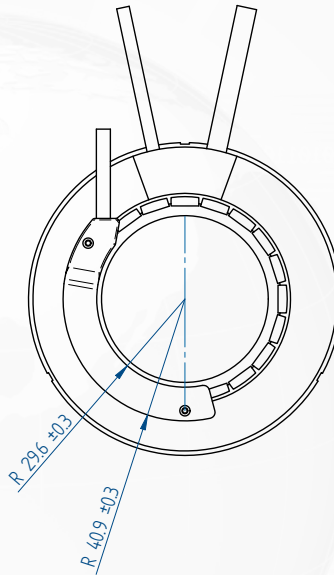
## Torque QTR-A digital Hall module



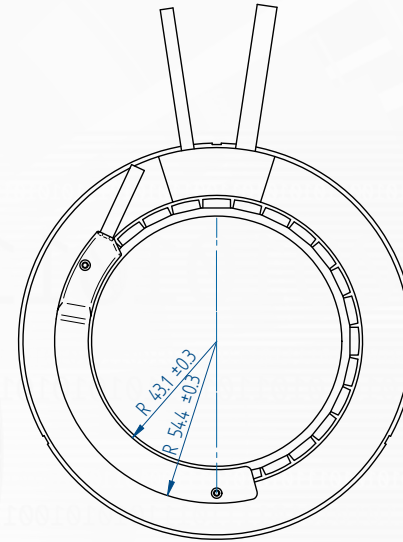
Digital Hall module mounted\* on  
QTR-A 65 series



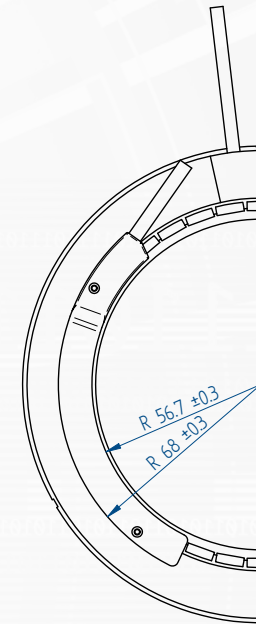
Digital Hall module mounted\* on  
QTR-A 78 series



Digital Hall module mounted\* on  
QTR-A 105 series



Digital Hall module mounted\* on  
QTR-A 133 series



Digital Hall module mounted\* on  
QTR-A 160 series



### Specifications

Input voltage:	5V...15Vdc
Output voltage:	3 phase TTL, max 2.5mA, 5Vdc AquadB TTL, max 2.5mA, 5Vdc

Tecnotion QTR motors can be equipped with a Tecnotion QTR digital Hall module. The module covers a small portion of the motor and measures just a little over 3 mm in thickness for the largest part.

When a QTR stator is not powered the Tecnotion QTR digital Hall module can be used to determine the electrical position of the rotor. It is a 'wake and shake' replacement, simplifying the startup of the QTR motor.

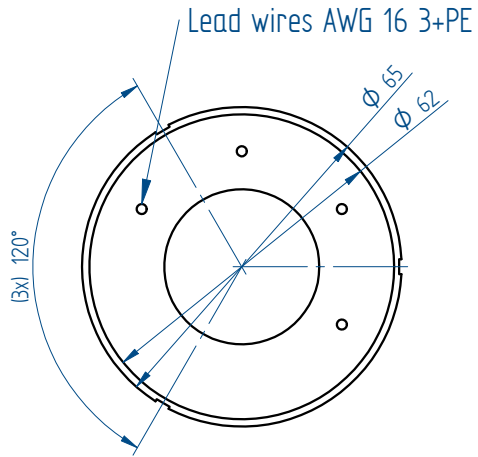
Digital Hall sensors are available for the QTR-A 65, 78, 105, 133 and 160 series.



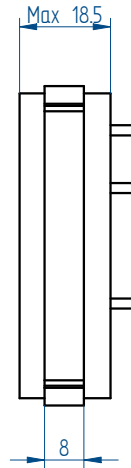
\* Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

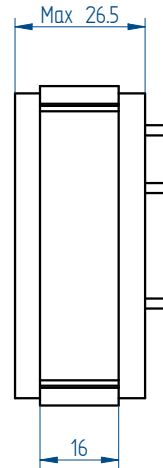
## STATOR



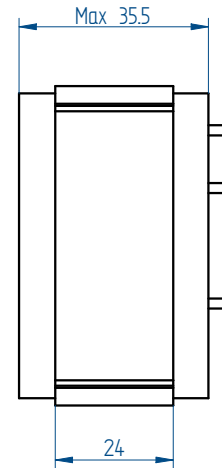
QTR-A 65-17



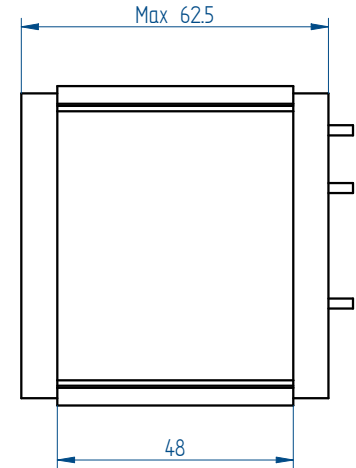
QTR-A 65-25



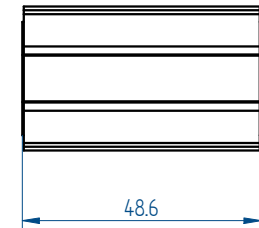
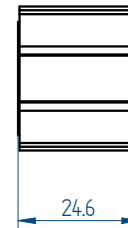
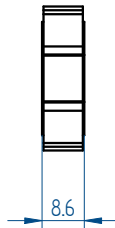
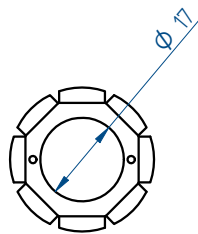
QTR-A 65-34



QTR-A 65-60



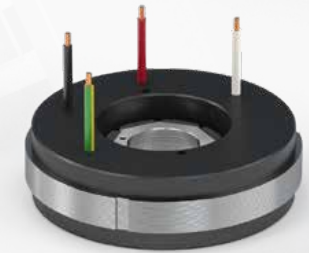
## ROTOR



\* All sizes are in mm

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	Parameter	Remarks	Symbol	Unit	QTR-A 65-17	QTR-A 65-25	QTR-A 65-34	QTR-A 65-60
Performance	Winding type				N	N	Y	Y
	Motortype max. voltage ph-ph	3-phase synchronous		$V_{acrms} (V_{dc})$	420 (600)			
	Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	0.64	1.31	2.25	5.47
	Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	0.42	0.85	1.43	3.82
	Continuous torque	coil @ 100°C	$T_c$	Nm	0.29	0.66	1.08	2.31
	Maximum speed <sup>(3)</sup> @ 48 Volt	@ Tc	$n_{max}$	rpm	5735	2673	3456	910
	Maximum speed @ max. voltage	@ Tc	$n_{max}$	rpm	28000	28000	28000	16960
	Motor torque constant	up to Ic	$K_t$	Nm/A <sub>rms</sub>	0.060	0.118	0.098	0.267
	Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	0.0021	0.0059	0.0111	0.0321
	Electrical	Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	13.84	13.84	27.98
Peak current		magnet @ 25°C	$I_p$	A <sub>rms</sub>	7.58	7.58	15.32	15.05
Maximum continuous current <sup>(1)</sup>		coils @ 100°C	$I_c$	A <sub>rms</sub>	4.86	5.61	11.07	8.65
Back EMF phase-phase <sub>peak</sub>			$K_e$	V/krpm	5.1	10.1	8.4	22.8
Back EMF phase-phase <sub>RMS</sub>			$K_e$	V/krpm	3.6	7.2	5.9	16.1
Coil resistance per phase		coils @ 25°C ex. cable	R	Ω	0.575	0.799	0.287	0.741
Coil induction per phase		$l < 0.6 l_p$	L	mH	0.86	1.62	0.69	2.10
Electrical time constant		coils @ 25°C	$\tau_e$	ms	1.5	2.0	2.4	2.8
Poles			$N_{mgn}$	nr	8	8	8	8
Thermal		Continuous power loss	coils @ 100°C	$P_c$	W	53	99	138
	Thermal resistance <sup>(2)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	1.50	0.81	0.58	0.37
	Thermal time constant	up to 63% max. coiltemp.	$\tau_{th}$	s	21	16	16	38
	Temperature cut-off / sensor				No temperature sensor			
Mechanical	Stator OD		OD <sub>s</sub>	mm	65			
	Rotor ID		ID <sub>R</sub>	mm	17			
	Motor height		H <sub>motor</sub>	mm	18	26	35	62
	Lamination stack height		H <sub>arm</sub>	mm	8	16	24	48
	Rotor inertia		J <sub>R</sub>	kg*m <sup>2</sup>	3.8E-06	7.5E-06	1.1E-05	2.3E-05
	Stator mass	excluding cables	M <sub>s</sub>	g	149	248	361	717
	Rotor mass		M <sub>R</sub>	g	27	54	80	160
	Total mass	excluding cables	M <sub>T</sub>	g	176	302	441	877
	Cable mass	all cables	m	g	36			
Cable type (power)	length 0.5 m	d	mm (AWG)	2.06 (16)				



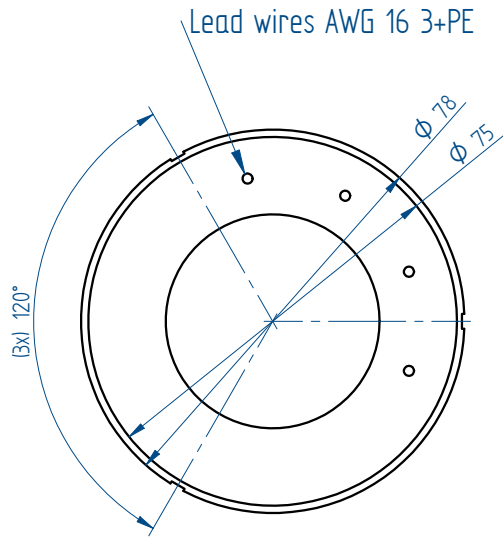
QTR-A 65 Stator and rotor shown with a height of 17 mm

1. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
2. Rth based on radial mounting of stator lamination stack.
3. MAXIMUM allowable speed for QTR-A 65 series motors is 28.000 rpm. If you plan a high speed application, please contact Tecnotion.

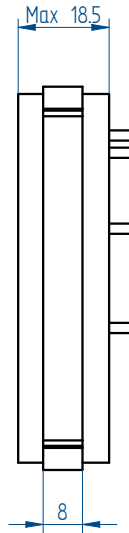
All specifications ±0%

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

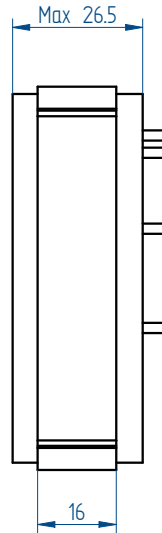
## STATOR



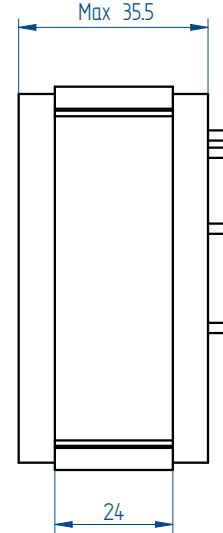
QTR-A 78-17



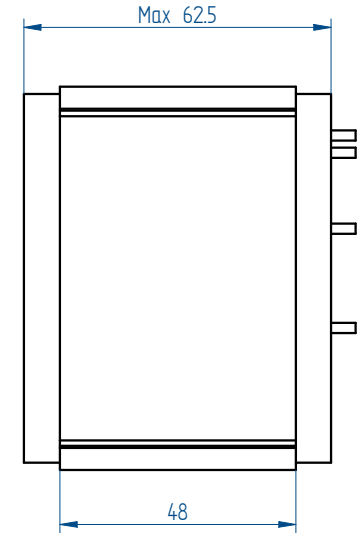
QTR-A 78-25



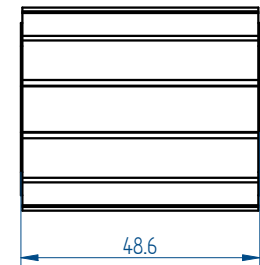
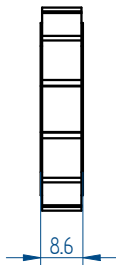
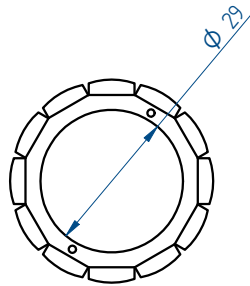
QTR-A 78-34



QTR-A 78-60



## ROTOR



\* All sizes are in mm

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	Parameter	Remarks	Symbol	Unit	QTR-A 78-17	QTR-A 78-25	QTR-A 78-34	QTR-A 78-60
Performance	Winding type				N	Y	Y	Y
	Motortype max. voltage ph-ph	3-phase synchronous		$V_{acrms} (V_{dc})$	420 (600)			
	Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	1.22	2.93	4.54	10.85
	Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	0.84	1.90	2.88	7.57
	Continuous torque	coil @ 100°C	$T_c$	Nm	0.57	1.38	2.19	4.41
	Maximum speed <sup>(3)</sup> @ 48 Volt	@ Tc @ 48 Vdc	$n_{max}$	rpm	2657	2360	1463	324
	Maximum speed @ max. voltage	@ Tc	$n_{max}$	rpm	23000	23000	23000	8147
	Motor torque constant	up to Ic	$K_t$	Nm/A <sub>rms</sub>	0.117	0.131	0.198	0.530
	Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	0.0053	0.0166	0.0304	0.0842
	Electrical	Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	13.84	27.98	27.98
Peak current		magnet @ 25°C	$I_p$	A <sub>rms</sub>	7.58	15.32	15.32	15.05
Maximum continuous current		coils @ 100°C	$I_c$	A <sub>rms</sub>	4.89	10.56	11.08	8.33
Back EMF phase-phase <sub>peak</sub>			$K_e$	V/krpm	10.0	11.2	16.9	45.3
Back EMF phase-phase <sub>RMS</sub>			$K_e$	V/krpm	7.1	7.9	12.0	32.0
Coil resistance per phase		coils @ 25°C ex. cable	R	Ω	0.857	0.342	0.430	1.111
Coil induction per phase		$l < 0.6$ lp	L	mH	1.35	0.76	1.04	3.4
Electrical time constant		coils @ 25°C	$\tau_e$	ms	1.6	2.2	2.4	3.1
Poles			$N_{mgn}$	nr	12	12	12	12
Thermal		Continuous power loss	coils @ 100°C	$P_c$	W	80	150	207
	Thermal resistance <sup>(2)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.99	0.53	0.39	0.26
	Thermal time constant	up to 63% max. coiltemp.	$\tau_{th}$	s	20	16	16	41
	Temperature cut-off / sensor				No temperature sensor			
Mechanical	Stator OD		OD <sub>S</sub>	mm	78			
	Rotor ID		ID <sub>R</sub>	mm	29			
	Motor height		H <sub>motor</sub>	mm	18	26	35	62
	Lamination stack height		H <sub>arm</sub>	mm	8	16	24	48
	Rotor inertia		J <sub>R</sub>	kg*m <sup>2</sup>	1.3E-05	2.5E-05	3.8E-05	7.6E-05
	Stator mass	excluding cables	M <sub>S</sub>	g	208	353	501	1003
	Rotor mass		M <sub>R</sub>	g	42	84	126	243
	Total mass	excluding cables	M <sub>T</sub>	g	250	437	627	1246
	Cable mass	all cables	m	g	36			
Cable type (power)	length 0.5 m	d	mm (AWG)	2.06 (16)				



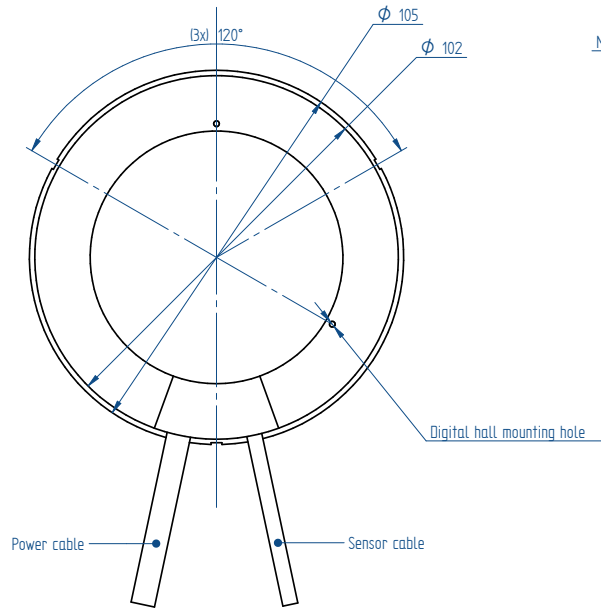
QTR-A 78 Stator and rotor shown with a height of 17 mm

1. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
2. R<sub>th</sub> based on radial mounting of stator lamination stack.
3. MAXIMUM allowable speed for QTR-A 78 series motors is 23.000 rpm. If you plan a high speed application, please contact Tecnotion.

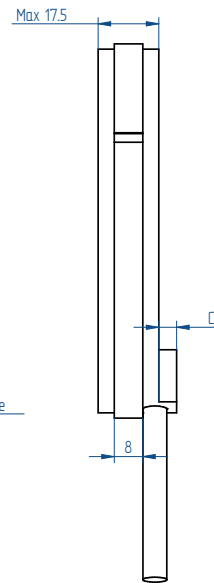
All specifications ±0%

Mounting instructions and tolerances can be found in the Torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

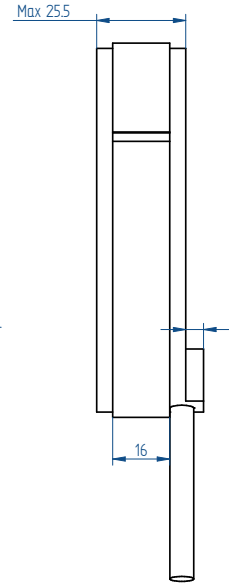
## STATOR



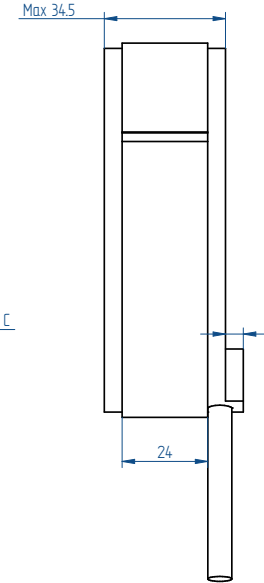
QTR-A 105-17



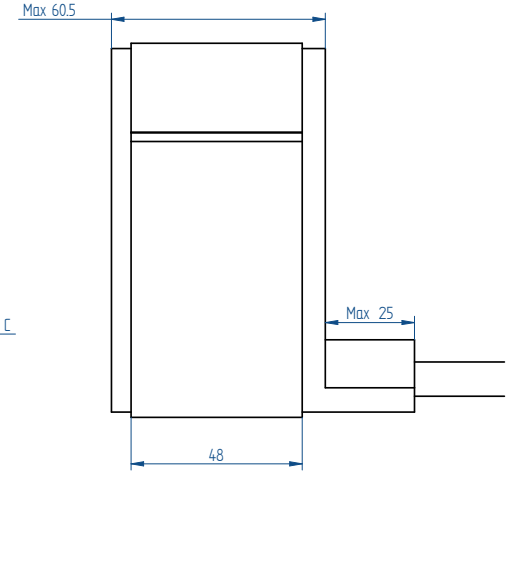
QTR-A 105-25



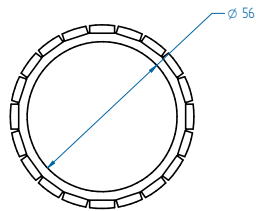
QTR-A 105-34



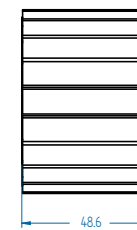
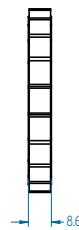
QTR-A 105-60



## ROTOR



\* All sizes are in mm



winding	C (mm)
N	3.5
Y+Z	5.5

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Parameter	Remarks	Symbol	Unit	QTR-A-105-17			QTR-A-105-25			QTR-A-105-34			QTR-A-105-60
				N	Y	Z	N	Y	Z	N	Y	Z	N
Winding type				N	Y	Z	N	Y	Z	N	Y	Z	N
Motor type max. voltage ph-ph	3-phase synchronous		$V_{acrms} (V_{dL})$	230 (300)									420 (600)
Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	2.9	3.3	3.3	6.1	7.5	6.9	10.6	11.3	10.4	28.4
Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	1.9	2.2	2.2	3.9	4.4	4.4	6.7	6.6	6.6	18.1
Continuous torque	coil @ 100°C	$T_c$	Nm	1.4	1.4	1.4	3.2	3.3	3.3	5.4	5.2	5.2	12.0
Maximum speed <sup>(3)</sup> @ 48 Volt	@ $T_c$	$n_{max}$	rpm	784	1761	3300	240	783	1623	0	444	1028	0
Maximum speed @ max. voltage	@ $T_c$	$n_{max}$	rpm	6890	12286	16500	3625	6534	11399	1928	4439	7833	1455
Motor torque constant	up to $I_c$	$K_t$	Nm/A <sub>rms</sub>	0.30	0.17	0.10	0.60	0.33	0.19	1.07	0.50	0.29	2.86
Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	0.021	0.022	0.022	0.061	0.065	0.065	0.127	0.115	0.120	0.40
Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	13.8	28.2	48.8	13.8	28.2	48.8	13.3	28.2	48.8	13.5
Peak current	magnet @ 25°C	$I_p$	A <sub>rms</sub>	7.6	15.4	26.7	7.6	15.4	26.7	7.3	15.4	26.7	7.37
Maximum continuous current <sup>(1)</sup>	coils @ 100°C	$I_c$	A <sub>rms</sub>	4.6	8.5	14.7	5.3	9.8	17.0	5.1	10.3	17.9	4.2
Back EMF phase-phase <sub>peak</sub>		$K_e$	V/krpm	25	14	8	51	28	16	92	43	25	244
Back EMF phase-phase <sub>RMS</sub>		$K_e$	V/krpm	18	10	6	36	20	12	65	30	17	173
Coil resistance per phase	coils @ 25°C ex. cable	R	Ω	1.38	0.43	0.14	1.93	0.57	0.19	3.02	0.74	0.24	6.84
Coil induction per phase	$l < 0.6 l_p$	L	mH	2.58	0.83	0.28	4.05	1.29	0.43	7.93	1.75	0.59	25.3
Electrical time constant	coils @ 25°C	$\tau_e$	ms	1.9	2.0	1.9	2.1	2.3	2.2	2.6	2.4	2.4	3.7
Poles		$N_{mgn}$	nr	20	20	20	20	20	20	20	20	20	20
Continuous power loss	coils @ 100°C	$P_c$	W	115	115	115	214	214	214	300	300	300	469
Thermal resistance <sup>(2)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.65	0.65	0.65	0.35	0.35	0.35	0.25	0.25	0.25	0.16
Thermal time constant	up to 63% max. coiltemp.	$\tau_{th}$	s	21	25	25	16	18	18	17	17	17	25
Temperature cut-off / sensor				PTC 1kΩ / KTY83-122									
Stator OD		$OD_s$	mm	105									
Rotor ID		$ID_R$	mm	56									
Motor height		$H_{motor}$	mm	17			25			34			60
Lamination stack height		$H_{arm}$	mm	8			16			24			48
Rotor inertia		$J_R$	kg*m <sup>2</sup>	8.0E-05			1.5E-04			2.2E-04			4.3E-04
Stator mass	excluding cables	$M_s$	g	299			472			746			1476
Rotor mass		$M_R$	g	79			146			218			433
Total mass	excluding cables	$M_T$	g	378			618			964			1909
Cable mass	all cables	m	g	63	90	90	63	90	90	63	90	90	95
Cable type (power)	length 0.5 m	d	mm (AWG)	6.5 (20)	6.7 (14)	6.7 (14)	6.5 (20)	6.7 (14)	6.7 (14)	6.5 (20)	6.7 (14)	6.7 (14)	9.6 (18)
Cable type (sensor)	length 0.5 m	d	mm (AWG)	4.3 (26)									



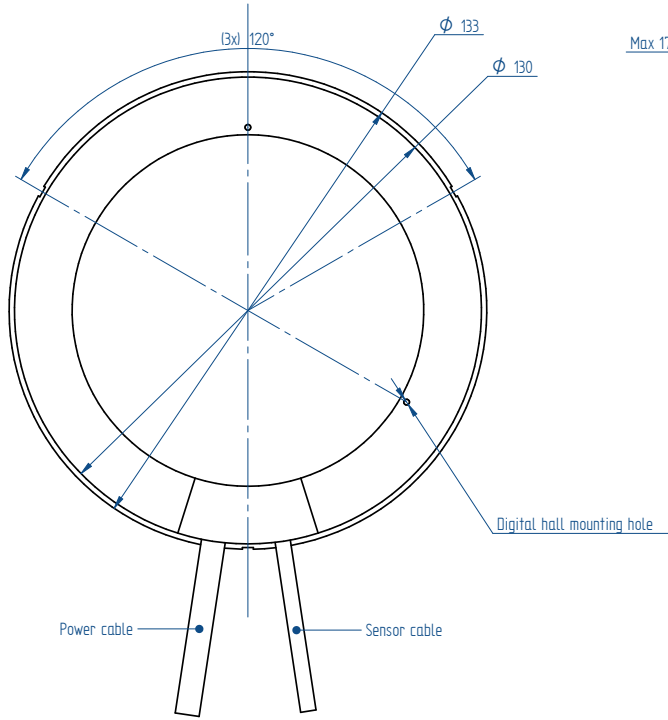
QTR-A-105 Stator and rotor shown with a height of 17 mm

1. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
2.  $R_{th}$  based on radial mounting of stator lamination stack.
3. MAXIMUM allowable speed for QTR-A 105 series motors is 16.500 rpm. If you plan a high speed application, please contact Tecnotion.

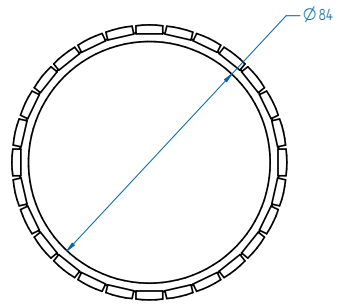
All specifications ±10%

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

## STATOR

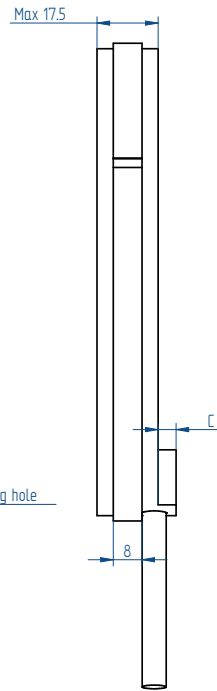


## ROTOR

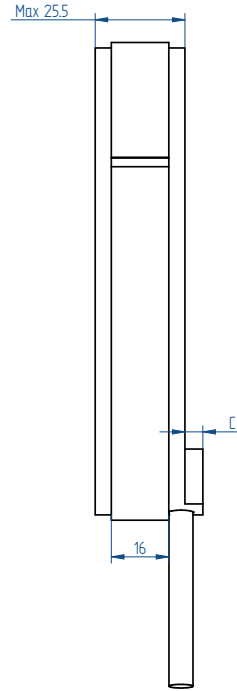


\* All sizes are in mm

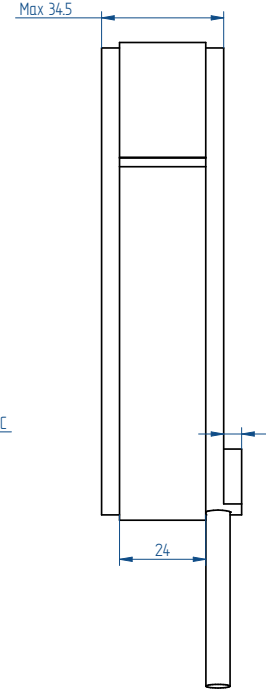
QTR-A 133-17



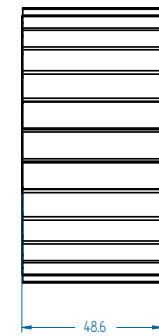
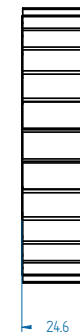
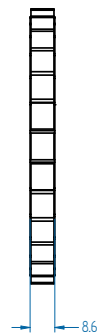
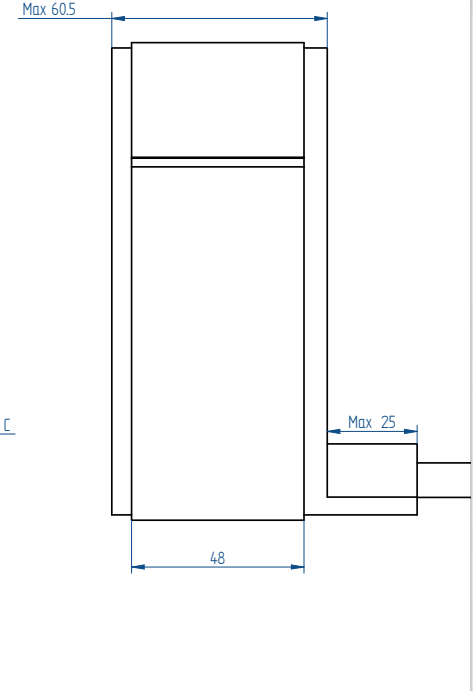
QTR-A 133-25



QTR-A 133-34



QTR-A 133-60



winding	C (mm)
N	3.5
Y+Z	5.5

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Parameter	Remarks	Symbol	Unit	QTR-A-133-17			QTR-A-133-25			QTR-A-133-34		QTR-A-133-60	
Winding type				N	Y	Z	N	Y	Z	N	Z	N	
Motor type max. voltage ph-ph	3-phase synchronous		$V_{acrms} (V_{dc})$	230 (300)									420 (600)
Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	5.6	6.4	6.4	11.9	13.5	13.5	20.6	20.3	55.5	
Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	3.8	4.3	4.3	7.5	8.6	8.6	13.1	12.9	35.3	
Continuous torque	coil @ 100°C	$T_c$	Nm	2.6	2.6	2.6	5.9	6.0	6.0	10.0	9.5	21.9	
Maximum speed <sup>(3)</sup> @ 48 Volt	@ $T_c$	$n_{max}$	rpm	317	839	1641	33	345	788	0	478	0	
Maximum speed @ max. voltage	@ $T_c$	$n_{max}$	rpm	3514	6340	10807	1825	3389	5930	946	4040	724	
Motor torque constant	up to $I_c$	$K_t$	Nm/A <sub>rms</sub>	0.58	0.33	0.19	1.16	0.65	0.38	2.09	0.56	5.57	
Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	0.058	0.061	0.061	0.167	0.177	0.180	0.344	0.310	1.08	
Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	13.8	28.2	48.8	13.8	28.2	48.8	13.3	48.8	13.5	
Peak current	magnet @ 25°C	$I_p$	A <sub>rms</sub>	7.56	15.40	26.70	7.56	15.40	26.70	7.31	26.70	7.37	
Maximum continuous current <sup>(1)</sup>	coils @ 100°C	$I_c$	A <sub>rms</sub>	4.43	8.10	14.00	5.05	9.30	16.10	4.77	16.90	3.93	
Back EMF phase-phase <sub>peak</sub>		$K_e$	V/krpm	50	28	16	99	56	32	179	48	476	
Back EMF phase-phase <sub>rms</sub>		$K_e$	V/krpm	35	20	11	70	39	23	126	34	337	
Coil resistance per phase	coils @ 25°C ex. cable	R	Ω	1.93	0.58	0.20	2.70	0.80	0.27	4.23	0.34	9.58	
Coil inductance per phase	$l < 0.6 l_p$	L	mH	3.74	1.20	0.40	5.87	1.87	0.62	11.50	0.85	36.6	
Electrical time constant	coils @ 25°C	$\tau_e$	ms	1.9	2.1	2.0	2.2	2.4	2.3	2.7	2.5	3.8	
Poles		$N_{mgn}$	nr	28	28	28	28	28	28	28	28	28	
Continuous power loss	coils @ 100°C	$P_c$	W	147	147	147	268	268	268	375	375	577	
Thermal resistance <sup>(2)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.51	0.51	0.51	0.28	0.28	0.28	0.20	0.20	0.13	
Thermal time constant	up to 63% max. coiltemp.	$\tau_{th}$	s	23	27	27	18	21	21	19	19	29	
Temperature cut-off / sensor				PTC 1kΩ / KTY83-122									
Stator OD		OD <sub>s</sub>	mm	133									
Rotor ID		ID <sub>r</sub>	mm	84									
Motor height		H <sub>motor</sub>	mm	17			25			34		60	
Lamination stack height		H <sub>arm</sub>	mm	8			16			24		48	
Rotor inertia		J <sub>r</sub>	kg*m <sup>2</sup>	2.1E-04			4.2E-04			6.2E-04		1.2E-03	
Stator mass	excluding cables	M <sub>s</sub>	g	414			717			1037		2090	
Rotor mass		M <sub>r</sub>	g	106			208			309		613	
Total mass	excluding cables	M <sub>t</sub>	g	520			925			1346		2703	
Cable mass	all cables	m	g	63	90	90	63	90	90	63	90	95	
Cable type (power)	length 0.5 m	d	mm (AWG)	6.5 (20)	6.7 (14)	6.7 (14)	6.5 (20)	6.7 (14)	6.7 (14)	6.5 (20)	6.7 (14)	9.6 (18)	
Cable type (sensor)	length 0.5 m	d	mm (AWG)	4.3 (26)									

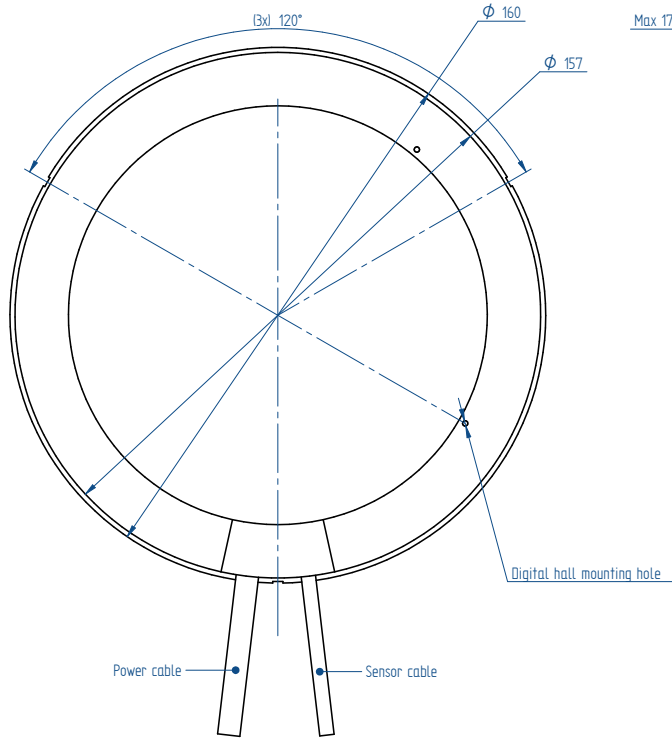


QTR-A-133 Stator and rotor shown with a height of 17 mm

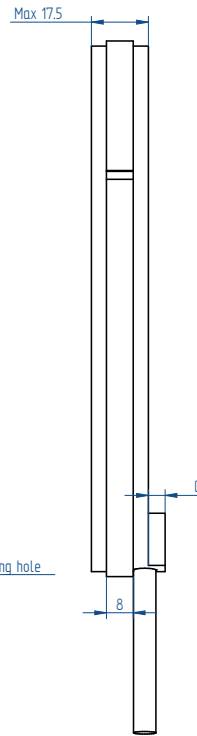
- All specifications ±10%
- These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
  - R<sub>th</sub> based on radial mounting of stator lamination stack.
  - MAXIMUM allowable speed for QTR-A 133 series motors is 14,000 rpm. If you plan a high speed application, please contact Tecnotion.

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

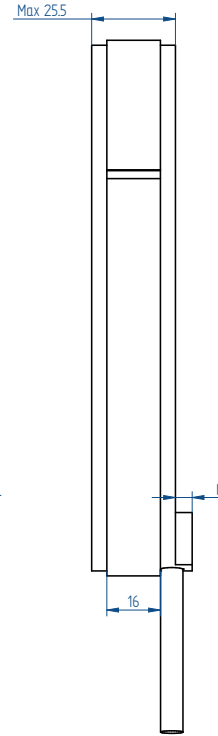
## STATOR



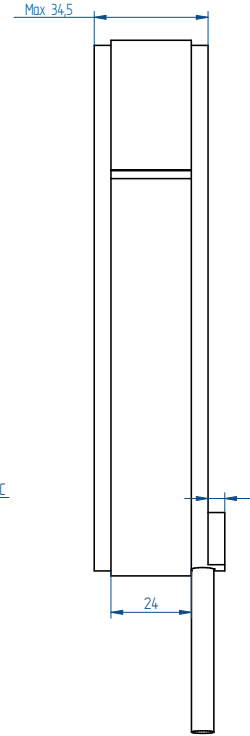
QTR-A 160-17



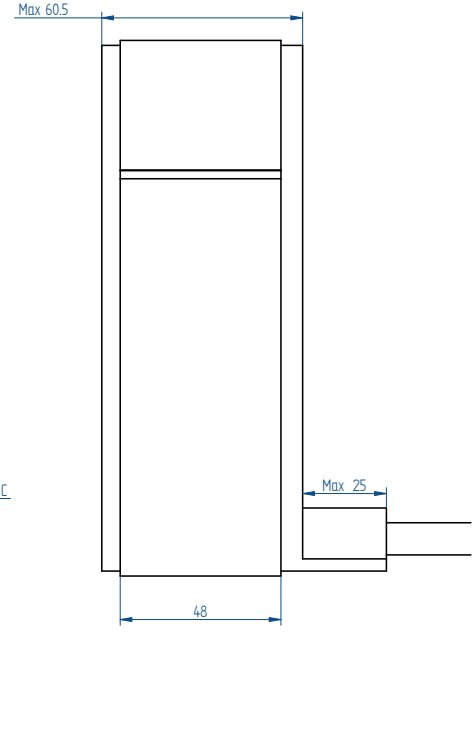
QTR-A 160-25



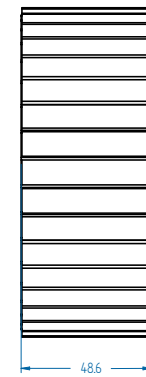
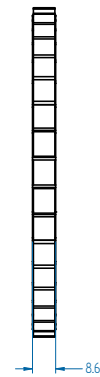
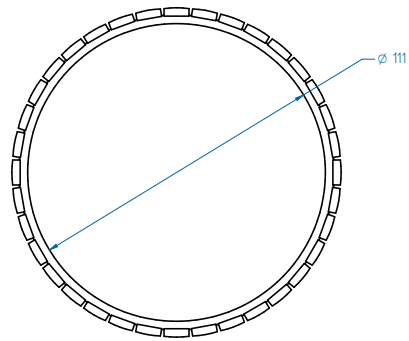
QTR-A 160-34



QTR-A 160-60



## ROTOR



\* All sizes are in mm

winding	C (mm)
N	3.5
Y+Z	5.5

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	Parameter	Remarks	Symbol	Unit	QTR-A-160-17			QTR-A-160-25			QTR-A-160-34		QTR-A-160-60
					N	Y	Z	N	Y	Z	N	Z	N
Performance	Winding type				N	Y	Z	N	Y	Z	N	Z	N
	Motortype max. voltage ph-ph	3-phase synchronous		$V_{acrms} (V_{dc})$	230 (300)								420 (600)
	Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	9.3	10.6	10.6	19.6	22.4	22.4	34.1	33.6	91.6
	Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	6.2	7.1	7.1	12.5	14.2	14.2	21.7	21.4	58.3
	Continuous torque	coil @ 100°C	$T_c$	Nm	4.1	4.2	4.2	9.4	9.7	9.7	15.7	15.0	36.3
	Maximum speed <sup>(3)</sup> @ 48 Volt	@ $T_c$	$n_{max}$	rpm	142	467	965	0	165	441	0	259	0
	Maximum speed @ max. voltage	@ $T_c$	$n_{max}$	rpm	2145	3871	6663	1084	2039	3604	555	2464	411
	Motor torque constant	up to $I_c$	$K_t$	Nm/A <sub>rms</sub>	0.96	0.54	0.31	1.92	1.07	0.62	3.45	0.93	9.20
Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	0.12	0.13	0.13	0.35	0.38	0.38	0.73	0.67	2.29	
Electrical	Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	13.8	28.2	48.8	13.8	28.2	48.8	13.3	48.8	13.5
	Peak current	magnet @ 25°C	$I_p$	A <sub>rms</sub>	7.6	15.4	26.7	7.6	15.4	26.7	7.3	26.7	7.4
	Maximum continuous current <sup>(1)</sup>	coils @ 100°C	$I_c$	A <sub>rms</sub>	4.3	7.8	13.4	4.9	9.0	15.7	4.6	16.2	3.9
	Back EMF phase-phase <sub>peak</sub>		$K_e$	V/krpm	82	46	26	164	92	53	295	79	787
	Back EMF phase-phase <sub>rms</sub>		$K_e$	V/krpm	58	32	19	116	65	37	209	56	556
	Coil resistance per phase	coils @ 25°C ex. cable	R	Ω	2.47	0.75	0.25	3.47	1.03	0.35	5.45	0.44	12.30
	Coil induction per phase	$l < 0.6 l_p$	L	mH	4.89	1.57	0.52	7.68	2.45	0.82	15.0	1.11	47.9
	Electrical time constant	coils @ 25°C	$\tau_e$	ms	2.0	2.1	2.1	2.2	2.4	2.4	2.8	2.5	3.9
Poles		$N_{mgn}$	nr	36	36	36	36	36	36	36	36	36	
Thermal	Continuous power loss	coils @ 100°C	$P_c$	W	174	174	174	326	326	326	441	441	750
	Thermal resistance <sup>(2)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.43	0.43	0.43	0.23	0.23	0.23	0.17	0.17	0.10
	Thermal time constant	up to 63% max. coiltemp	$\tau_{th}$	s	25	29	29	19	22	22	21	21	29
	Temperature cut-off / sensor				PTC 1kΩ / KTY83-122								
Mechanical	Stator OD		$OD_s$	mm	160								
	Rotor ID		$ID_r$	mm	111								
	Motor height		$H_{motor}$	mm	17			25			34		60
	Lamination stack height		$H_{arm}$	mm	8			16			24		48
	Rotor inertia		$J_r$	kg*m <sup>2</sup>	4.7E-04			9.2E-04			1.4E-03		2.6E-03
	Stator mass	excluding cables	$M_s$	g	527			875			1212		2555
	Rotor mass		$M_r$	g	138			269			401		754
	Total mass	excluding cables	$M_T$	g	665			1144			1613		3309
	Cable mass	all cables	m	g	63	90	90	63	90	90	63	90	95
	Cable type (power)	length 0.5 m	d	mm (AWG)	6.5 (20)	6.7 (14)	6.7 (14)	6.5 (20)	6.7 (14)	6.7 (14)	6.5 (20)	6.7 (14)	9.6 (18)
Cable type (sensor)	length 0.5 m	d	mm (AWG)	4.3 (26)									

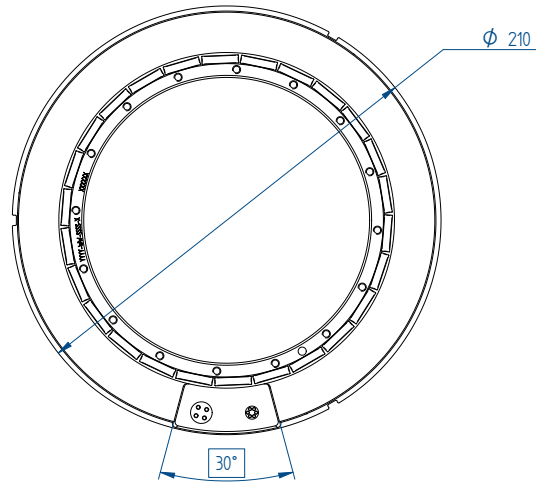


QTR-A-160 Stator and rotor shown with a height of 17 mm

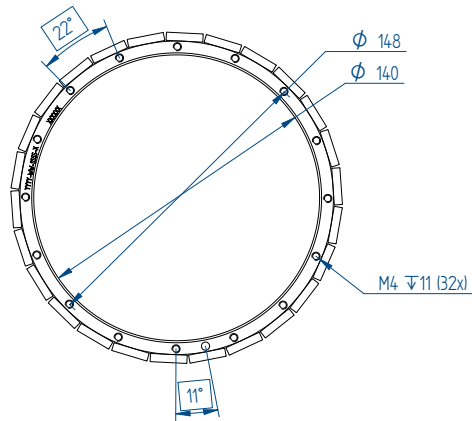
- All specifications ±10%
1. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
  2. R<sub>th</sub> based on radial mounting of stator lamination stack.
  3. MAXIMUM allowable speed for QTR-A 160 series motors is 12,000 rpm. If you plan a high speed application, please contact Tecnotion.

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

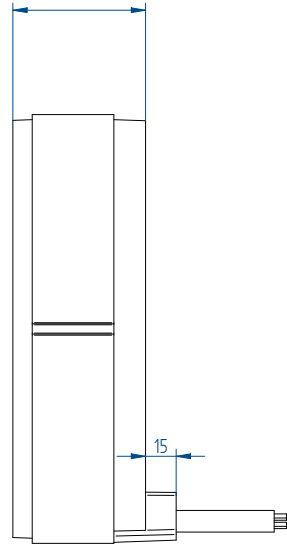
## STATOR



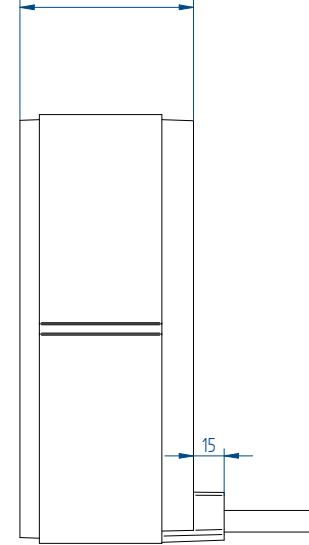
## ROTOR



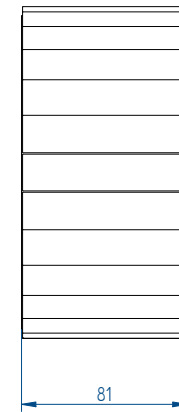
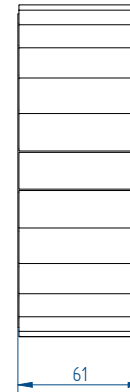
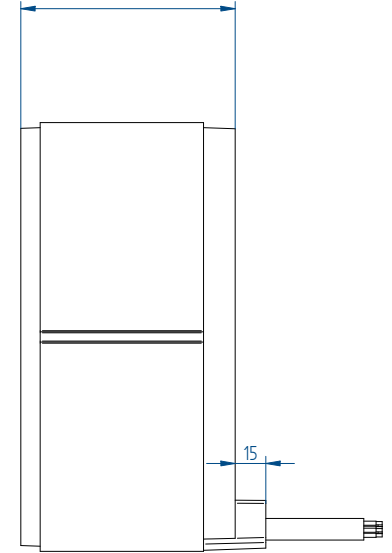
QTL-A 210-65



QTL-A 210-85



QTL-A 210-105



\* All sizes are in mm

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QTL 210 series, with a height of 65 mm

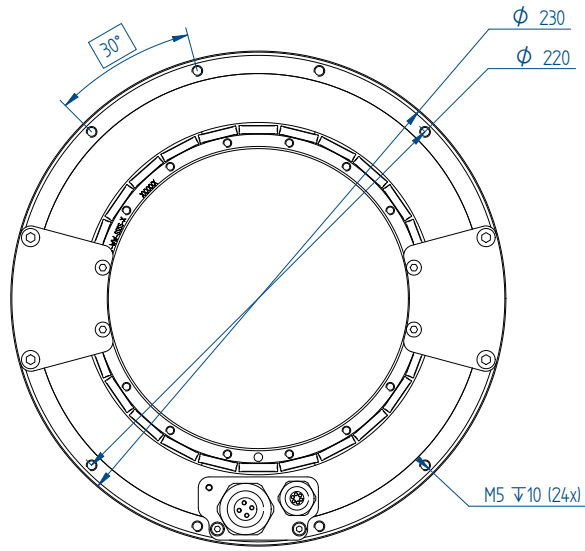
	Parameter	Remarks	Symbol	Unit	QTL-A 210-65	QTL-A 210-85	QTL-A 210-105
Performance	Winding type				N	N	N
	Motortype max. voltage ph-ph	3-phase synchronous		$V_{ac,rms} (V_{dc})$		480 (680)	
	Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	173	259	346
	Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	140	211	281
	Continuous torque	coil @ 100°C	$T_c$	Nm	65	103	142
	Stall torque	coil @ 100°C	$T_s$	Nm	46	73	100
	Maximum speed <sup>(1)</sup>	@Tc @ 680 Vdc	$n_{max}$	rpm	716	457	326
	Motor torque constant	up to Ic	$K_t$	Nm/A <sub>rms</sub>	8.7	13.1	17.5
	Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	8.0	13.5	19.2
	Electrical	Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	22.0	22.0
Peak current		magnet @ 25 °C	$I_p$	A <sub>rms</sub>	16.9	16.9	16.9
Maximum continuous current <sup>(2)</sup>		coils @ 100°C	$I_c$	A <sub>rms</sub>	7.45	7.88	8.11
Stall Current <sup>(2)</sup>		coils @ 100°C	$I_s$	A <sub>rms</sub>	5.27	5.57	5.74
Back EMF phase-phase <sub>peak</sub>			$K_e$	V/krpm	747	1121	1494
Back EMF phase-phase <sub>RMS</sub>			$K_e$	V/krpm	528	793	1057
Coil resistance per phase		coils @ 25°C ex. cable	R	Ω	3.18	4.25	5.31
Coil induction per phase		$l < 0.6$ lp	L	mH	16.0	22.3	28.7
Electrical time constant			$\tau_e$	ms	5.0	5.3	5.4
Poles			$N_{mgn}$	nr	26	26	26
Thermal	Continuous power loss	coils @ 100°C	$P_c$	W	690	1028	1363
	Thermal resistance <sup>(3)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.116	0.078	0.059
	Thermal time constant		$\tau_{th}$	s	53	47	45
	Temperature cut-off / sensor				PTC 1kΩ (3x) / PT1000 (3x)		
Mechanical	Stator OD		OD <sub>s</sub>	mm	210		
	Rotor ID		ID <sub>R</sub>	mm	140		
	Motor height		H <sub>motor</sub>	mm	65	85	105
	Lamination stack height		H <sub>arm</sub>	mm	40	60	80
	Rotor inertia		J <sub>R</sub>	kg*m <sup>2</sup>	0.009	0.014	0.019
	Stator mass	excluding cables	M <sub>s</sub>	kg	4.2	5.9	7.5
	Rotor mass		M <sub>R</sub>	kg	1.6	2.4	3.2
	Total mass	excluding cables	M <sub>T</sub>	kg	5.8	8.3	10.7
	Cable mass	all cables	m	g	500		
	Cable type (power)	length 2 m	d	mm (AWG)	10.6 (13)		
Cable type (sensor)	length 2 m	d	mm (AWG)	6.4 (25)			

All specifications ±0.0%

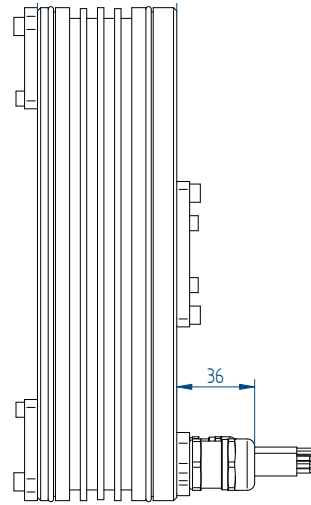
1. Actual values depend on bus voltage. Please check the T/n diagram in our manual or online simulation tool.
2. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
3. R<sub>th</sub> based on radial mounting of stator lamination stack.

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

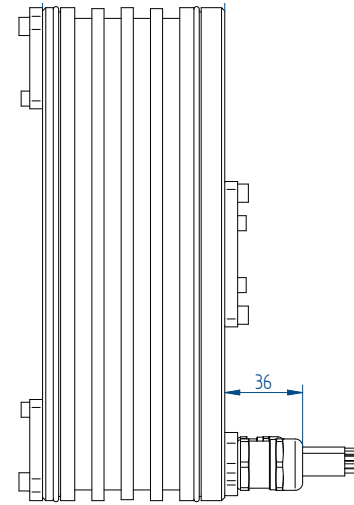
## STATOR



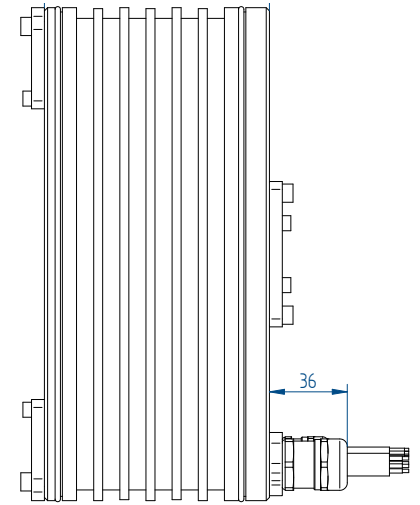
QTL-A 230-65



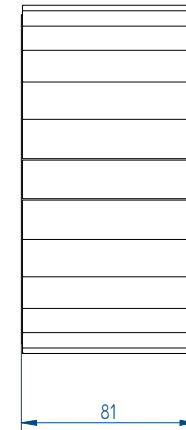
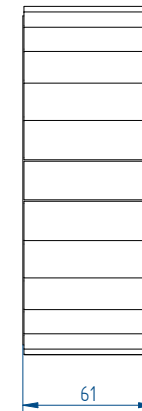
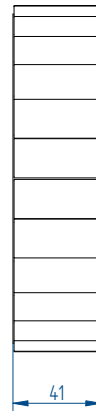
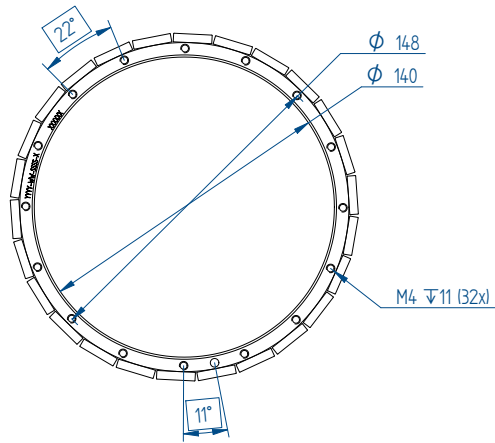
QTL-A 230-85



QTL-A 230-105



## ROTOR



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	Parameter	Remarks	Symbol	Unit	QTL-A 230-65	QTL-A 230-85	QTL-A 230-105
Performance	Winding type				N	N	N
	Motor type max. voltage ph-ph	3-phase synchronous		$V_{ac\ rms} (V_{dc})$	480 (680)		
	Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	173	259	346
	Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	140	211	281
	Continuous torque	coil @ 100°C	$T_c$	Nm	67	107	147
	Stall torque	coil @ 100°C	$T_s$	Nm	48	76	104
	Maximum speed <sup>(1)</sup>	@ $T_c$ @ 680 Vdc	$n_{max}$	rpm	709	451	321
	Motor torque constant	up to $I_c$	$K_t$	Nm/A <sub>rms</sub>	8.7	13.1	17.5
	Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	8.0	13.5	19.2
	Electrical	Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	22.0	22.0
Peak current		magnet @ 25 °C	$I_p$	A <sub>rms</sub>	16.9	16.9	16.9
Maximum continuous current <sup>(2)</sup>		coils @ 100°C	$I_c$	A <sub>rms</sub>	7.69	8.16	8.42
Stall current <sup>(2)</sup>		coils @ 100°C	$I_s$	A <sub>rms</sub>	5.44	5.77	5.95
Back EMF phase-phase <sub>peak</sub>			$K_e$	V/krpm	747	1121	1494
Back EMF phase-phase <sub>RMS</sub>			$K_e$	V/krpm	528	793	1057
Coil resistance per phase		coils @ 25°C ex. cable	R	Ω	3.18	4.25	5.31
Coil induction per phase		$l < 0.6 I_p$	L	mH	16.0	22.3	28.7
Electrical time constant			$\tau_e$	ms	5.0	5.3	5.4
Poles			$N_{mgn}$	nr	26	26	26
Thermal	Continuous power loss	coils @ 100°C	$P_c$	W	735	1102	1469
	Thermal resistance <sup>(3)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.109	0.073	0.054
	Thermal time constant		$\tau_{th}$	s	49	44	41
	Water cooling flow	for $\Delta T=3K$	$\Phi_w$	l/min	3.5	5.3	7.0
	Water Cooling pressure drop	order of magnitude	$\Delta P_w$	bar	0.7	1.0	1.5
	Temperature cut-off / sensor				PTC 1kΩ (3x) / PT1000 (3x)		
Mechanical	Stator OD		$OD_s$	mm	230		
	Rotor ID		$ID_R$	mm	140		
	Motor height		$H_{motor}$	mm	65	85	105
	Lamination stack height		$H_{arm}$	mm	40	60	80
	Rotor inertia		$J_R$	kg*m <sup>2</sup>	0.009	0.014	0.019
	Stator mass	excluding cables	$M_s$	kg	5.2	7.2	9.0
	Rotor mass		$M_R$	kg	1.6	2.4	3.2
	Total mass	excluding cables	$M_T$	kg	6.8	9.6	12.2
	Cable mass	all cables	m	g	500		
	Cable type (power)	length 2 m	d	mm (AWG)	10.6 (13)		
Cable type (sensor)	length 2 m	d	mm (AWG)	6.4 (25)			



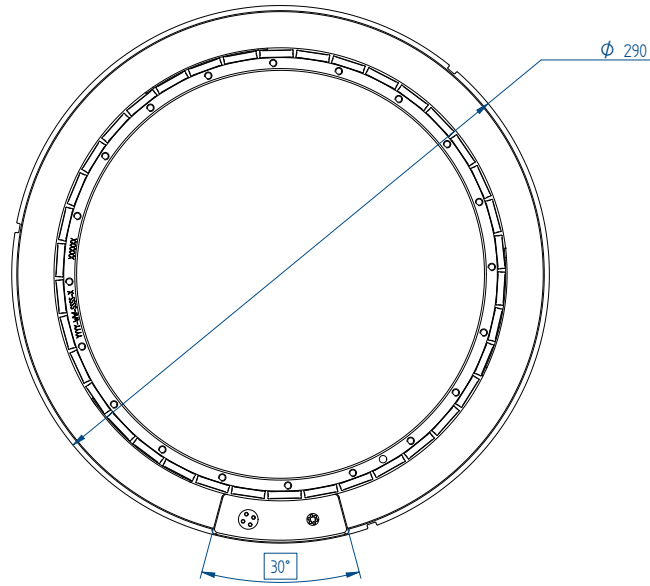
QTL 230 series, with a height of 85 mm

All specifications ±0%

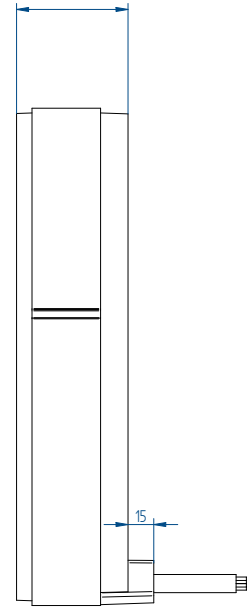
1. Actual values depend on bus voltage. Please check the T/n diagram in our manual or online simulation tool.
2. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
3. R<sub>th</sub> based on given water flow and pressure.

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

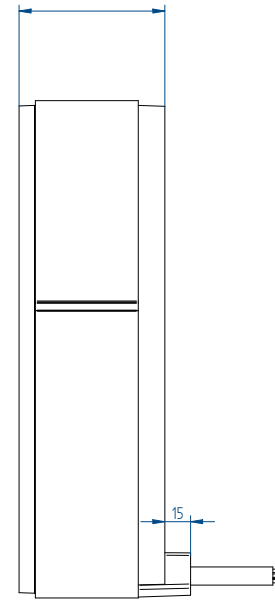
## STATOR



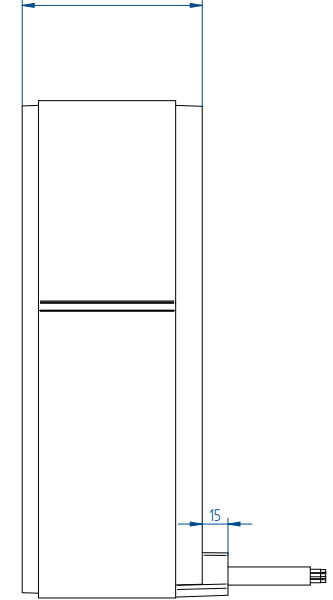
QTL-A 290-65



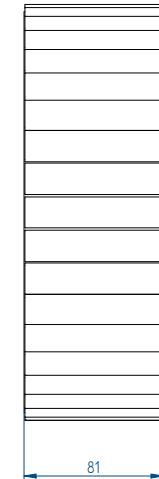
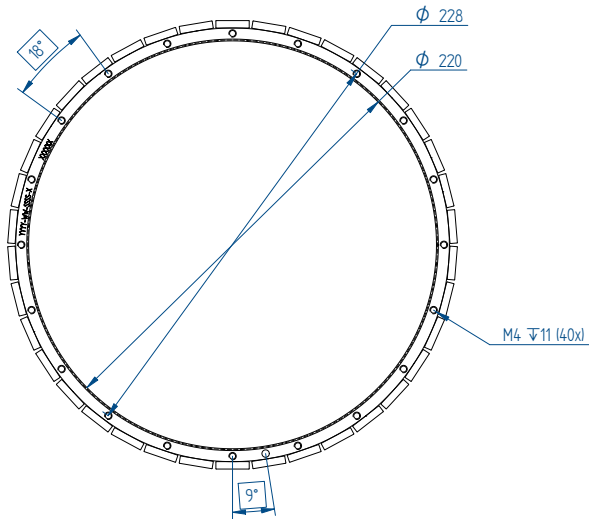
QTL-A 290-85



QTL-A 290-105



## ROTOR



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QTL 290 series, with a height of 65 mm

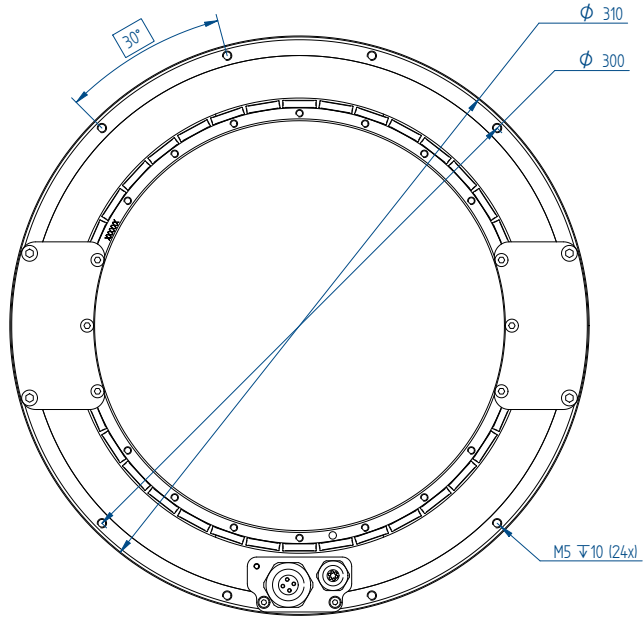
	Parameter	Remarks	Symbol	Unit	QTL-A 290-65	QTL-A 290-85	QTL-A 290-105
Performance	Winding type				N	N	N
	Motortype max. voltage ph-ph	3-phase synchronous		$V_{ac\ rms} (V_{dc})$		480 (680)	
	Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	389	583	778
	Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	316	474	632
	Continuous torque	coil @ 100°C	$T_c$	Nm	140	222	305
	Stall torque	coil @ 100°C	$T_s$	Nm	99	157	215
	Maximum speed <sup>(1)</sup>	@ Tc @ 680 Vdc	$n_{max}$	rpm	306	189	130
	Motor torque constant	up to Ic	$K_t$	Nm/A <sub>rms</sub>	19.7	29.5	39.3
	Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	27.0	45.5	64.7
	Electrical	Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	22.0	22.0
Peak current		magnet @ 25°C	$I_p$	A <sub>rms</sub>	16.9	16.9	16.9
Maximum continuous current <sup>(2)</sup>		coils @ 100°C	$I_c$	A <sub>rms</sub>	7.14	7.54	7.75
Stall current <sup>(2)</sup>		coils @ 100°C	$I_s$	A <sub>rms</sub>	5.05	5.33	5.48
Back EMF phase-phase <sub>peak</sub>			$K_e$	V/krpm	1681	2521	3362
Back EMF phase-phase <sub>RMS</sub>			$K_e$	V/krpm	1189	1783	2377
Coil resistance per phase		coils @ 25°C ex. cable	R	Ω	4.77	6.37	7.96
Coil induction per phase		l < 0.6 lp	L	mH	23.9	34.7	45.5
Electrical time constant			$\tau_e$	ms	5.0	5.5	5.7
Poles			$N_{mgn}$	nr	38	38	38
Thermal	Continuous power loss	coils @ 100°C	$P_c$	W	948	1410	1864
	Thermal resistance <sup>(3)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.084	0.057	0.043
	Thermal time constant		$\tau_{th}$	s	57	52	49
	Temperature cut-off / sensor				PTC 1kΩ (3x) / PT1000 (3x)		
Mechanical	Stator OD		OD <sub>s</sub>	mm	290		
	Rotor ID		ID <sub>R</sub>	mm	220		
	Motor height		H <sub>motor</sub>	mm	65	85	105
	Lamination stack height		H <sub>arm</sub>	mm	40	60	80
	Rotor inertia		J <sub>R</sub>	kg*m <sup>2</sup>	0.031	0.046	0.061
	Stator mass	excluding cables	M <sub>s</sub>	kg	6.0	8.3	10.8
	Rotor mass		M <sub>R</sub>	kg	2.3	3.5	4.7
	Total mass	excluding cables	M <sub>T</sub>	kg	8.3	11.8	15.5
	Cable mass	all cables	m	g	500		
	Cable type (power)	length 2 m	d	mm (AWG)	10.6 (13)		
Cable type (sensor)	length 2 m	d	mm (AWG)	6.4 (25)			

All specifications ±0%

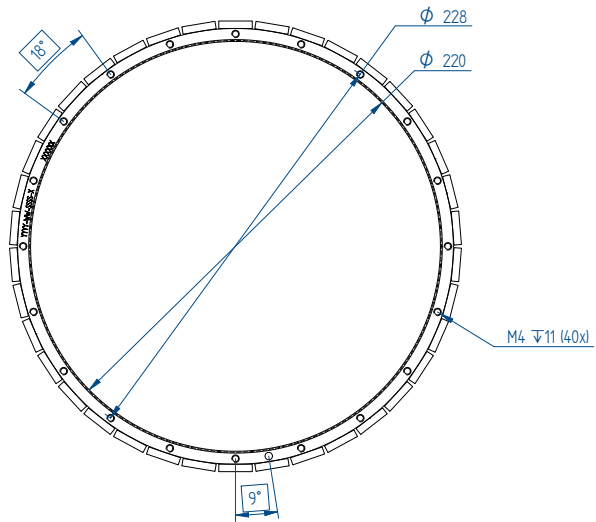
1. Actual values depend on bus voltage. Please check the T/n diagram in our manual or online simulation tool.
2. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
3. R<sub>th</sub> based on radial mounting of stator lamination stack.

Mounting instructions and tolerances can be found in the torque installation manual. Manuals and 3D CAD files can be downloaded from our website.

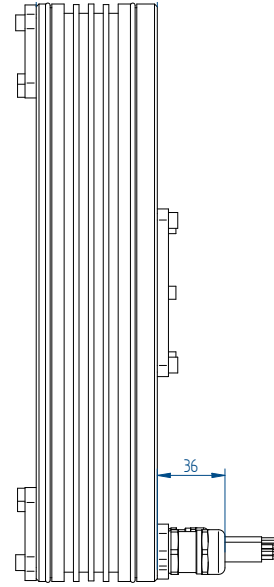
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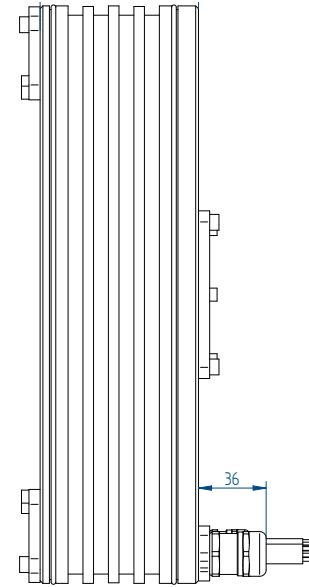
## ROTOR



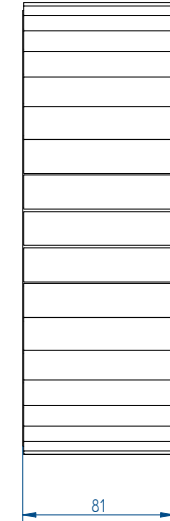
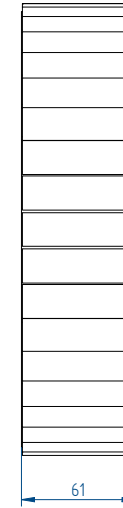
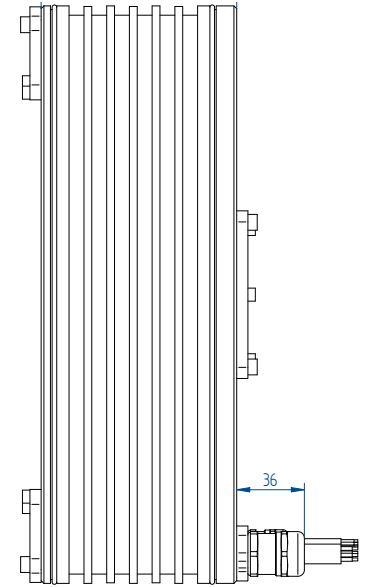
QTL-A 310-65



QTL-A 310-85



QTL-A 310-105



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	Parameter	Remarks	Symbol	Unit	QTL-A 310-65	QTL-A 310-85	QTL-A 310-105
Performance	Winding type				N	N	N
	Motor type max. voltage ph-ph	3-phase synchronous		$V_{ac\ rms} (V_{dc})$	480 (680)		
	Ultimate torque @ 20°C/s increase	magnet @ 25°C	$T_u$	Nm	389	583	778
	Peak torque @ 6°C/s increase	magnet @ 25°C	$T_p$	Nm	316	474	632
	Continuous torque	coil @ 100°C	$T_c$	Nm	151	241	331
	Stall torque	coil @ 100°C	$T_s$	Nm	107	170	234
	Maximum speed <sup>(1)</sup>	@ $T_c$ @ 680 Vdc	$n_{max}$	rpm	298	182	124
	Motor torque constant	up to $I_c$	$K_t$	Nm/A <sub>rms</sub>	19.7	29.5	39.3
	Motor constant	coils @ 25°C	$K_m$	(Nm) <sup>2</sup> /W	27.0	45.5	64.7
	Electrical	Ultimate current	magnet @ 25°C	$I_u$	A <sub>rms</sub>	22.0	22.0
Peak current		magnet @ 25°C	$I_p$	A <sub>rms</sub>	16.9	16.9	16.9
Maximum continuous current <sup>(2)</sup>		coils @ 100°C	$I_c$	A <sub>rms</sub>	7.70	8.16	8.42
Stall current <sup>(2)</sup>		coils @ 100°C	$I_s$	A <sub>rms</sub>	5.44	5.77	5.96
Back EMF phase-phase <sub>peak</sub>			$K_e$	V/krpm	1681	2521	3362
Back EMF phase-phase <sub>RMS</sub>			$K_e$	V/krpm	1189	1783	2377
Coil resistance per phase		coils @ 25°C ex. cable	R	Ω	4.77	6.37	7.96
Coil induction per phase		$l < 0.6 l_p$	L	mH	23.9	34.7	45.5
Electrical time constant			$\tau_e$	ms	5.0	5.5	5.7
Poles			$N_{mgn}$	nr	38	38	38
Thermal	Continuous power loss	coils @ 100°C	$P_c$	W	1102	1653	2204
	Thermal resistance <sup>(3)</sup>	coils to mount. sfc.	$R_{th}$	°C/W	0.073	0.048	0.036
	Thermal time constant		$\tau_{th}$	s	49	44	41
	Water cooling flow	for $\Delta T=3K$	$\Phi_w$	l/min	5.3	7.9	10.5
	Water cooling pressure drop	order of magnitude	$\Delta P_w$	bar	1.0	1.4	2.0
	Temperature cut-off / sensor				PTC 1kΩ (3x) / PT1000 (3x)		
Mechanical	Stator OD		$OD_s$	mm	310		
	Rotor ID		$ID_R$	mm	220		
	Motor height		$H_{motor}$	mm	65	85	105
	Lamination stack height		$H_{arm}$	mm	40	60	80
	Rotor inertia		$J_R$	kg*m <sup>2</sup>	0.031	0.046	0.061
	Stator mass	excluding cables	$M_s$	kg	7.4	10.1	12.9
	Rotor mass		$M_R$	kg	2.3	3.5	4.7
	Total mass	excluding cables	$M_T$	kg	9.7	13.6	17.6
	Cable mass	all cables	m	g	500		
	Cable type (power)	length 2 m	d	mm (AWG)	10.6 (13)		
Cable type (sensor)	length 2 m	d	mm (AWG)	6.4 (25)			



QTL 310 series, with a height of 85 mm

All specifications ±0%

1. Actual values depend on bus voltage. Please check the T/n diagram in our manual or online simulation tool.
2. These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool or manual.
3. R<sub>th</sub> based on given water flow and pressure.

## Additional products

To download our CAD files, installation manuals, product specifications and more, visit our website at:

[www.tecnotion.com](http://www.tecnotion.com)



### Product series

*Iron core & ironless motor series*

Tecnotion's linear motor series rely on 30 years of linear motor development experience. All motors excel in their force density ratings. They offer continuous force in a range of 10 Newton to 3000 Newton in a surprisingly small package.

Tecnotion can provide linear solutions for most applications which require a strong iron core linear motor or a highly dynamic ironless type linear motor.

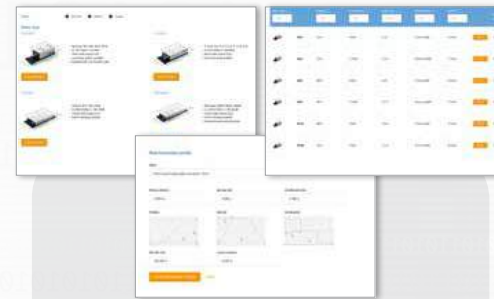


### Vacuum series

*Outgassing down to  $10^{-8}$  mbar*

Many years of experience is used in designing and building vacuum coils and magnets. Tecnotion can supply any vacuum linear motor that can match even the strictest vacuum requirements, for instance in the semiconductor industry.

Our vacuum rated ironless linear motors are a specifically designed coil units and magnet yokes for use in high vacuum, down to  $10^{-8}$  mBar.



### Simulation tool

*Analyze your application*

Save precious time by using our FREE online motor simulation tool. Our specialized software helps you find the best motor for the application and generate reports within seconds, without having to make time consuming calculations by hand.

The tool will provide you with diagrams for position, velocity, acceleration, jerk, torque, power, voltage, current, temperature, torque vs. velocity and more. Find the simulation tool at [www.tecnotion.com/simtool](http://www.tecnotion.com/simtool).



### Custom motors

*Motor solutions*

Besides the standard catalogue items we offer custom linear motor solutions. Some examples: custom windings, cable confection and vacuum motors for transport and positioning in vacuum.

Besides this Tecnotion offers moving magnet motors and linear solutions, completely designed toward your needs. For more information please contact Tecnotion.

## Article numbers

Series	Article	Article code
QTR	TORQUE KIT QTR-A-65-17 N	10 8062
QTR	TORQUE KIT QTR-A-65-25 N	10 8393
QTR	TORQUE KIT QTR-A-65-34 Y	10 8394
QTR	TORQUE KIT QTR-A-65-60 Y	10 8395
QTR	TORQUE KIT QTR-A-78-17 N	10 8397
QTR	TORQUE KIT QTR-A-78-25 Y	10 8399
QTR	TORQUE KIT QTR-A-78-34 Y	10 8400
QTR	TORQUE KIT QTR-A-78-60 Y	10 8401
QTR	TORQUE KIT QTR-A-105-17-N	4022 368 6120
QTR	TORQUE KIT QTR-A-105-17-Y	10 8848
QTR	TORQUE KIT QTR-A-105-17-Z	10 8158
QTR	TORQUE KIT QTR-A-105-25-N	4022 368 6121
QTR	TORQUE KIT QTR-A-105-25-Y	10 9393
QTR	TORQUE KIT QTR-A-105-25-Z	10 9398
QTR	TORQUE KIT QTR-A-105-34-N	4022 368 6122
QTR	TORQUE KIT QTR-A-105-34-Y	10 9394
QTR	TORQUE KIT QTR-A-105-34-Z	10 9399
QTR	TORQUE KIT QTR-A-105-60-N	4022 368 6123
QTR	TORQUE KIT QTR-A-133-17-N	4022 368 6140
QTR	TORQUE KIT QTR-A-133-17-Y	10 9395
QTR	TORQUE KIT QTR-A-133-17-Z	10 9400
QTR	TORQUE KIT QTR-A-133-25-N	4022 368 6141
QTR	TORQUE KIT QTR-A-133-25-Y	109396
QTR	TORQUE KIT QTR-A-133-25-Z	10 8159
QTR	TORQUE KIT QTR-A-133-34-N	4022 368 6142
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QTL	TORQUE KIT QTL-A-230-85-N	11 1145
QTL	TORQUE KIT QTL-A-230-105-N	11 1153
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QTL	TORQUE KIT QTL-A-290-105-N	11 1182
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