

ISA, PC/104, RS232, PCI Single-axis

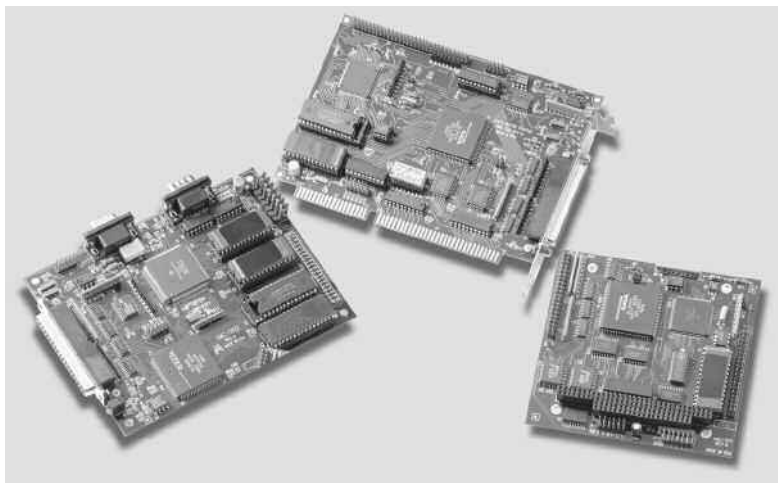
DMC-1410, DMC-1411, DMC-1412, DMC-1417

Product Description

The DMC-1410, DMC-1411, DMC-1412, DMC-1417 are economical, single axis motion control cards with ISA, PC/104, RS/232 and PCI communications, respectively. They have many of the same high-performance features of Galil's multi-axis controllers, but are designed for just one axis. This offers the user both space and cost-savings.

With a 32-bit microcomputer, the single axis controllers provide such advanced features as PID compensation with velocity and acceleration feedforward, program memory with multitasking for simultaneously

Left to right:
DMC-1412, DMC-1410,
DMC-1411



running two application programs, and uncommitted I/O for synchronizing motion with external events. It handles various modes of motion including point-to-point positioning, jogging, contouring, electronic gearing and ECAM. Additionally, the controllers accept inputs from two encoders, which is useful for electronic gearing applications. The user can configure the controller for either stepper or servo motor control.

Like all Galil controllers, the DMC-1410, -1411, -1412 and -1417 use a simple, English-like command language which makes them very easy to program. Galil's WSDK servo design software further simplifies system set-up with "one-button" servo tuning and real-time display of position and velocity information. Communication drivers are available for DOS, Linux and all current Windows operating systems.

Features

- 1-axis motion controller
- DMC-1410: ISA card
DMC-1411: PC/104 card
DMC-1412: Card with two daisy-chainable RS232 ports up to 38.4 kbaud
DMC-1412-BOX: Box-level controller
DMC-1417: PCI card
- User-configurable for stepper or servo motor control. Sinusoidal commutation for brushless servo motors.*
- Accepts up to 8 MHz encoder frequencies for servos. Outputs up to 2 MHz for steppers
- Advanced PID compensation with velocity and acceleration feedforward, offsets and integration limit
- Modes of motion include jogging, point-to-point positioning, contouring, electronic gearing and ECAM. Accepts input from auxiliary encoder for electronic gearing
- Over 125 English-like commands including conditional statements and event triggers such as AT TIME and AT POSITION
- Memory for application programs, variables and arrays. Multitasking for concurrent execution of two application programs
- Home input and forward and reverse limits
- 7 Uncommitted digital inputs, 3 digital outputs
- High-speed position latch
- DMC-1410, -1412 and -1417 use 37-pin D connector. DMC-1411 uses a 40-pin IDC connector. ICM-1460 interconnect module breaks-out 37-pin cable into screw terminals.
- Communication drivers for all current versions of Windows, DOS and Linux
- CE certified—DMC-1410, 1412
- Custom hardware and firmware options available

*DMC-1411 does not support sinusoidal commutation

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Specifications

System Processor

- Motorola 32-bit microcomputer

Communications Interface

- DMC-1410: ISA with bi-directional, high speed FIFO buffer
- DMC-1411: PC/104 with bi-directional, high speed FIFO buffer
- DMC-1412: (2) daisy-chainable RS232 ports up to 38.4 kbaud
- DMC-1417: PCI with bi-directional, high speed FIFO buffer

Modes of Motion:

- Point-to-point positioning
- Jogging
- Electronic Gearing
- Electronic Cam
- Contouring

Memory

- Program memory size — 250 lines × 40 characters
- 126 variables
- 1000 array elements in up to 6 arrays

Filter

- PID (proportional-integral-derivative) with velocity and acceleration feedforward
- Dual-loop control for backlash compensation
- Velocity smoothing to minimize jerk
- Integration limit
- Torque limit
- Offset adjustment

Kinematic Ranges

- Position: 32 bit (± 2.15 billion counts per move; automatic rollover; no limit in jog)
- Velocity: Up to 8 million counts/sec for servo motors
- Acceleration: Up to 67 million counts/sec²

Uncommitted Digital I/O

- 7 TTL inputs
- 3 TTL outputs

High Speed Position Latch

- Latches within 0.1 microseconds

Dedicated I/O

- Main encoder inputs—Channel A, A-, B, B-, I, I- (± 12 V or TTL)
- Dual encoder—Channel A, A-, B, B-
- Forward and reverse limit inputs
- Home input
- High-speed position latch input
- Analog motor command output with 16-bit DAC resolution
- Pulse and direction output for step motors
- Amplifier enable output
- Error output

Minimum Servo Loop Update Time

- 375 microseconds

Maximum Encoder Feedback Rate

- 8 MHz

Maximum Stepper Rate

- 2 MHz (Full, half or microstep)

Power Requirements

- DMC-1410, DMC-1411, DMC-1412-card, DMC-1417:
 - +5V 400 mA
 - 12V 40 mA
 - +12V 40 mA
- DMC-1412 Box: plugs into 90–260 VAC

Environmental

- Operating temperature: 0–70° C for card; 0–60° C for box
- Humidity: 20–95% RH, non-condensing

Mechanical

- DMC-1410: 7" ISA
- DMC-1411: 4.4" × 4.15"
- DMC-1412-card: 6.0" × 4.375"
- DMC-1412-box: 5.1" × 3.0" × 6.8"
- DMC-1417: 7.3" PCI

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Connectors

DMC-1410, DMC-1412, DMC-1417 J3

Main 37-pin D-type

1 Reset*	20 Error Output*
2 Amp enable	21 ACMD
3 Output 3	22 Output 2
4 Output 1	23 Reserved
5 PWM or step out	24 Sign or direction
6 Input 7	25 Input 6
7 Input 5	26 Input 4
8 Input 3	27 Input 2
9 Input 1 (and latch)	28 Forward limit
10 +5V	29 Reverse limit
11 Ground	30 Home
12 +12V	31 -12V
13 Ground	32 A+
14 A-	33 B+
15 B-	34 I+
16 I-	35 Auxiliary A+
17 Auxiliary A-	36 Auxiliary B+
18 Auxiliary B-	37 Abort*
19 ACMD Phase B	

DMC-1411 J3

Main 40-pin IDC

1 Reset*	2 Error Output*
3 Amp enable	4 Amp command for servo
5 Output 3	6 Output 2
7 Output 1	8 Reserved
9 PWM or step out	10 Sign or direction
11 Input 7	12 Input 6
13 Input 5	14 Input 4
15 Input 3	16 Input 2
17 Input 1 (and latch)	18 Forward limit
19 +5V	20 Reverse limit
21 Ground	22 Home
23 +12V	24 -12V
25 Ground	26 A+
27 A-	28 B+
29 B-	30 I+
31 I-	32 Auxiliary A+
33 Auxiliary A-	34 Auxiliary B+
35 Auxiliary B-	36 Abort*
37 Reserved	38 NC
39 NC	40 NC

*Active low

DMC-1412 J5

Power 7-pin Molex

1 -12V
2 Ground
3 Ground
4 +5V
5 +5V
6 +12V
7 Earth

DMC-1412

RS232 Main port 9-pin male

1 CTS—output	6 CTS—output
2 Transmit data—output	7 RTS—input
3 Receive data—input	8 CTS—output
4 RTS—input	9 NC
5 Ground	

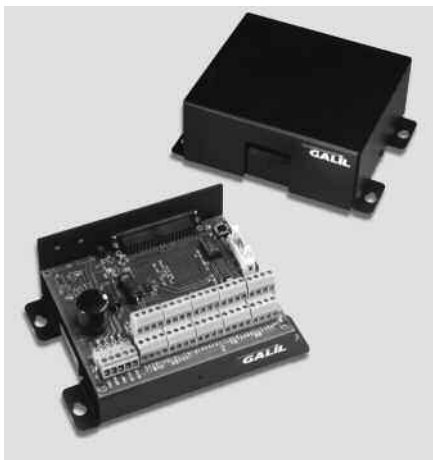
RS232 Auxiliary port 9-pin female

1 CTS—input	6 CTS—input
2 Transmit data—input	7 RTS—output
3 Receive data—output	8 CTS—input
4 RTS—output	9 NC
5 Ground	

Hardware Accessories

ICM-1460

The ICM-1460 Interconnect Module provides screw terminals for the 37-pin D-type cable from the DMC-1410 or DMC-1412, for quick connection of system hardware. A 40-pin to 37-pin cable allows the ICM-1460 to be used with the DMC-1411. The ICM-1460 is contained



ICM-1460 Interconnect Module
(shown with and without cover)

in a metal enclosure with dimensions of 6.9" × 4.9" × 2.6" and 0.2" diameter key-holes for mounting. The ICM is normally shipped configured for high amp enable, +5 V (-HAEN). For low amp enable, order ICM-1460-LAEN.

ICM-1460-OPTO

For applications requiring optoisolated inputs and outputs, the ICM-1460 option "OPTO" provides 5–24 V and 25 mA optoisolation on all general inputs and outputs, home inputs, and limits.

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Ordering Information

PART NUMBER	DESCRIPTION	QUANTITY 1	QUANTITY 100
DMC-1410	1-axis ISA	\$ 595	\$ 395
DMC-1411	1-axis PC/104	\$ 595	\$ 395
DMC-1412-card	1-axis stand-alone with RS232— card	\$ 595	\$ 395
DMC-1412-box	1-axis stand-alone with RS232 in enclosure with power supply	\$ 795	\$ 545
DMC-1417	1-axis PCI	\$ 595	\$ 395
CABLE 37-pin D	37-pin cable for DMC-1410, DMC-1412, DMC-1417	\$ 25	
CABLE 40-pin IDC	40-pin to 37-pin cable for DMC-1411	\$ 25	
ICM-1460	Interconnect Module for DMC-1400 series. Specify -HAEN for high amp enable or -LAEN for low amp enable	\$ 145	\$ 95
ICM-1460-OPTO	ICM with optoisolated inputs and outputs	\$ 195	\$ 145
Galil Utilities	Communication drivers, SmartTERM, DMCWIN software	\$ 20 for CD; free download	
DMCWIN32	Windows API Tool Kit (VB, C, C++, etc.)	Included with Utilities	
WSDK	Set-up, tuning and analysis software	\$ 195	
ActiveX Tool kit	Custom ActiveX controls for Microsoft platforms	\$ 595	

Galil offers additional quantity discounts for purchases between 1 and 100. Consult Galil for a quotation.

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