

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a CANopen interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare® 7, available for download at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Range

Peak Current	60 A (42.4 A _{RMS})
Continuous Current	30 A (30 A _{RMS})
AC Supply Voltage	200 - 240 VAC
DC Supply Voltage	255 - 373 VDC



Features

- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ▲ Fully Digital State-of-the-art Design
- ▲ Programmable Gain Settings
- ▲ Fully Configurable Current, Voltage, Velocity and Position Limits
- ▲ PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ Compact Size, High Power Density
- ▲ 16-bit Analog to Digital Hardware
- ▲ Built-in brake/shunt regulator
- ▲ On-the-Fly Mode Switching
- ▲ On-the-Fly Gain Set Switching

MODES OF OPERATION

- Profile Current
- Profile Velocity
- Profile Position
- Cyclic Synchronous Current Mode
- Cyclic Synchronous Velocity Mode
- Cyclic Synchronous Position Mode

COMMAND SOURCE

- ±10 V Analog
- PWM and Direction
- Encoder Following
- Over the Network
- Sequencing
- Indexing
- Jogging

FEEDBACK SUPPORTED

- ±10 VDC Position
- Halls
- Incremental Encoder
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

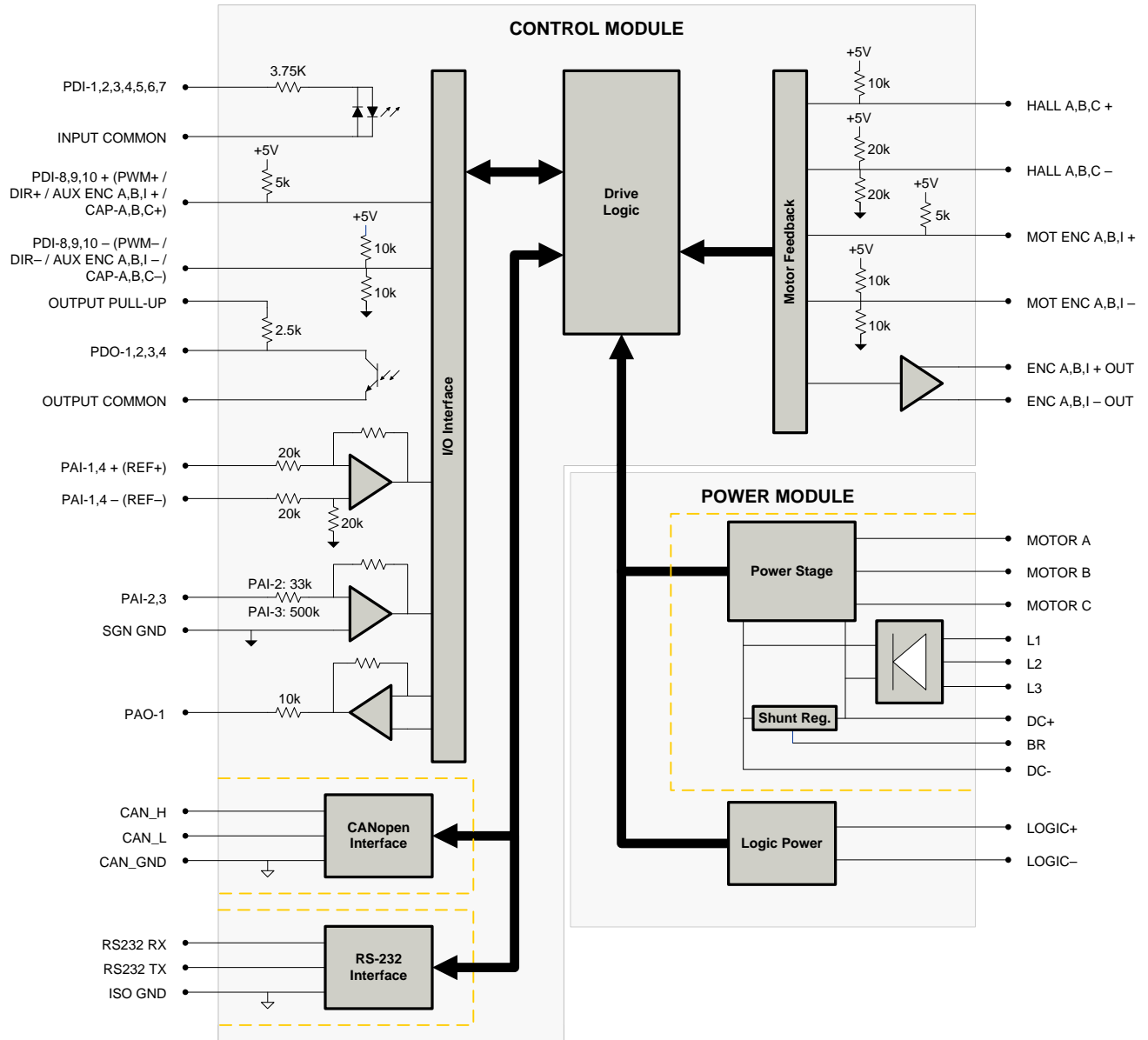
INPUTS/OUTPUTS

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 1 Programmable Analog Output (10-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

COMPLIANCES & AGENCY APPROVALS

- RoHS
- UL/cUL Pending
- CE Pending

BLOCK DIAGRAM



Information on Approvals and Compliances



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

SPECIFICATIONS

Power Specifications			
Description	Units		Value
Rated Voltage	VAC (VDC)	240 (339)	
AC Supply Voltage Range	VAC	200 - 240	
AC Supply Minimum	VAC	180	
AC Supply Maximum	VAC	264	
AC Input Phases ¹	-	3	
AC Supply Frequency	Hz	50 - 60	
DC Supply Voltage Range ²	VDC	255 – 373	
DC Bus Over Voltage Limit	VDC	420	
DC Bus Under Voltage Limit	VDC	205	
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)	
Maximum Peak Output Current ³	A (Arms)	60 (42.4)	
Maximum Continuous Output Current ⁴	A (Arms)	30 (30)	
Max. Continuous Output Power @ Rated Voltage ⁵	W	9662	
Max. Continuous Power Dissipation @ Rated Voltage	W	509	
Internal Bus Capacitance	µF	1120	
External Shunt Resistor Minimum Resistance ⁶	Ω	20	
Minimum Load Inductance (Line-To-Line) ⁷	µH	600	
Switching Frequency	kHz	14	
Maximum Output PWM Duty Cycle	%	100	
Low Voltage Supply Outputs	-	+5 VDC (250 mA)	
Control Specifications			
Description	Units		Value
Communication Interfaces	-	CANopen (RS-232 for configuration)	
Command Sources	-	±10 V Analog, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging	
Feedback Supported	-	±10 VDC Position, Aux. Incremental Encoder, Halls, Incremental Encoder, Tachometer (±10 VDC)	
Commutation Methods	-	Sinusoidal, Trapezoidal	
Modes of Operation	-	Profile Current, Profile Velocity, Profile Position, Cyclic Synchronous Current Mode, Cyclic Synchronous Velocity Mode, Cyclic Synchronous Position Mode	
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)	
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4	
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/1	
Primary I/O Logic Level	-	24 VDC	
Current Loop Sample Time	µs	71.4	
Velocity Loop Sample Time	µs	142.9	
Position Loop Sample Time	µs	142.9	
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)	
Internal Shunt Regulator	-	Yes	
Internal Shunt Resistor	-	No	
Mechanical Specifications			
Description	Units		Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL	
Size (H x W x D)	mm (in)	256.5 x 182.6 x 83.7 (10.1 x 7.2 x 3.3)	
Weight	g (oz)	2812.3 (99.2)	
Heatsink (Base) Temperature Range ⁸	°C (°F)	0 - 75 (32 - 167)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Form Factor	-	Panel Mount	
Cooling System	-	Natural Convection	
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header	
FAN Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header	
AUX COMM Connector	-	3-pin, 2.5 mm spaced, enclosed, friction lock header	
AUX ENCODER Connector	-	15-pin, high-density, male D-sub	
COMM Connector	-	Shielded, dual RJ-45 socket with LEDs	
FEEDBACK Connector	-	15-pin, high-density, female D-sub	
I/O Connector	-	26-pin, high-density, female D-sub	
MOTOR POWER Connector	-	4-port, 10.16 mm spaced, enclosed, friction lock header	
AC POWER Connector	-	4-port, 10.16 mm spaced, enclosed, friction lock header	
DC POWER Connector	-	4-port, 10.16 mm spaced, enclosed, friction lock header	

Notes

- Can operate on single-phase AC (208 VAC minimum) as long as output power does not exceed 3kW maximum.
- Large inrush current may occur upon initial DC supply connection to DC Bus.
- Ability of supplying drive rated peak current for 2 seconds with 10 second fallback to continuous value. Longer times are possible with lower current limits.
- Continuous I_{rms} value attainable when RMS Charge-Based Limiting is used.
- (DC Rated Voltage) * (Cont. RMS Current) * 0.95.
- ADVANCED Motion Controls recommends using an external fuse in series with the shunt resistor. A 5 amp motor delay fuse is typical.
- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS
AUX COMM - RS232 Communication Connector

Pin	Name	Description / Notes	I/O
1	RS232 RX	Receive Line (RS-232)	I
2	RS232 TX	Transmit Line (RS-232)	O
3	ISO GND	Isolated Signal Ground	IGND

AUX ENCODER - Auxiliary Feedback Connector

Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
8	PDI-10 + (AUX ENC I+ / CAP-A+)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
9	PDI-10 - (AUX ENC I- / CAP-A-)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-4 +	Differential Programmable Analog Input (12-bit Resolution)	I
15	PAI-4 -		I

COMM - CAN Communication Connector

Pin	Name	Description / Notes	I/O
1	CAN_H	CAN_H Line (Dominant High)	I
2	CAN_L	CAN_L Line (Dominant Low)	I
3	CAN_GND	CAN Ground	CGND
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	RESERVED	Reserved	-
7	CAN_GND	CAN Ground	CGND
8	RESERVED	Reserved	-

FEEDBACK - Feedback Connector

Pin	Name	Description / Notes	I/O
1	HALL A+	Commutation Sensor Inputs	I
2	HALL B+		I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive Input)	I
5	MOT ENC A-		I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive Input)	I
7	MOT ENC B-		I
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	I
9	MOT ENC I-		I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I

I/O - Signal Connector

Pin	Name	Description / Notes	I/O
1	PDO-1	Isolated Programmable Digital Output	O
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	O
4	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
5	PAI-1 - (REF-)		I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	PAO-1	Programmable Analog Output (10-bit Resolution)	O
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	O
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	O
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4	Isolated Programmable Digital Input	I
18	PDI-6	Isolated Programmable Digital Input	I
19	PDI-7	Isolated Programmable Digital Input	I
20	ENC A+ OUT	Buffered Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Buffered Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT	Buffered Encoder Index Output	O
25	ENC I- OUT		O
26	SGN GND	Signal Ground	SGND

Logic Power Connector

Pin	Name	Description / Notes	I/O
1	LOGIC GND	Logic Supply Ground	GND
2	LOGIC PWR	Logic Supply Input	I

Fan Power Connector

Pin	Name	Description / Notes	I/O
1	FAN GND	Fan Ground	GND
2	FAN PWR	Fan Power Input	I

AC Power Connector

Pin	Name	Description / Notes	I/O
1	L1	AC Supply Input (Three Phase)	I
2	L2		I
3	L3		I
4	CHASSIS	Chassis Ground	CGND

DC Power Connector

Pin	Name	Description / Notes	I/O
1	DC-	Power Ground	PGND
2	DC+	DC Power Input	I
3	DC+	External Shunt Resistor Connection. Connect resistor between DC+ and BR.	-
4	BR		-

Motor Power Connector

Pin	Name	Description / Notes	I/O
1	CHASSIS	Chassis Ground	CGND
2	MOTOR A	Motor Phase A	O
3	MOTOR B	Motor Phase A	O
4	MOTOR C	Motor Phase B	O

HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0

Additional Details

The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Bit Rate (kbits/sec)	Value For Bit Rate Setting
Load from non-volatile memory	0
500	1
250	2
125	3

Jumper Settings

Jumper	Description	Configuration		
		Not Installed	Pins 1-2	Pins 2-3
J1	CAN bus termination. Install this jumper (2.54mm) on the last drive in a CAN network. This jumper is located on a 4-pin header adjacent to the RS-232 connector. It consists of the two pins furthest from the connector.	Non-terminating Node	Terminating Node	N/A
J2	Reserved.	-	-	N/A

MECHANICAL INFORMATION

AUX COMM - RS232 Communication Connector

Connector Information		3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix: Plug P/N 1881338
	Included with Drive	Yes

AUX ENCODER - Auxiliary Feedback Connector

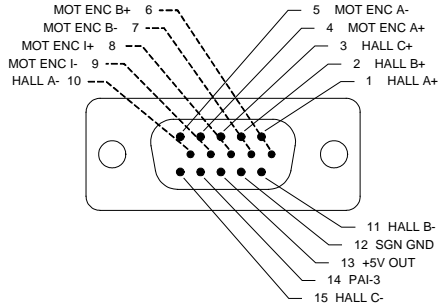
Connector Information		15-pin, high-density, male D-sub
Mating Connector	Details	TYCO: Plug P/N 1658681-1; Housing P/N 5748677-1; Terminals P/N 1658686-2 (loose) or 1658686-1 (strip)
	Included with Drive	No

COMM - CAN Communication Connector

Connector Information		Shielded, dual RJ-45 socket with LEDs
Mating Connector	Details	AMP: Plug P/N 5-569552-3
	Included with Drive	No

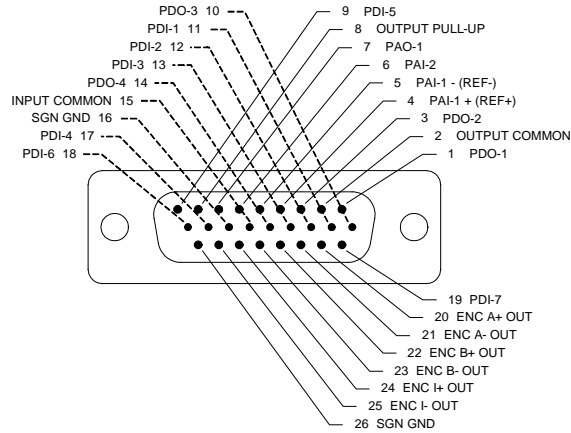
FEEDBACK - Feedback Connector

Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



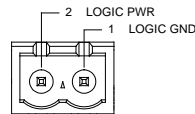
I/O - Signal Connector

Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



Logic Power Connector

Connector Information		2-port, 5.08 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1757019
	Included with Drive	Yes



Fan Power Connector

Connector Information		2-port, 5.08 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1757019
	Included with Drive	Yes

AC Power Connector

Connector Information		4-pin, 10.16 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1913523
	Included with Drive	Yes

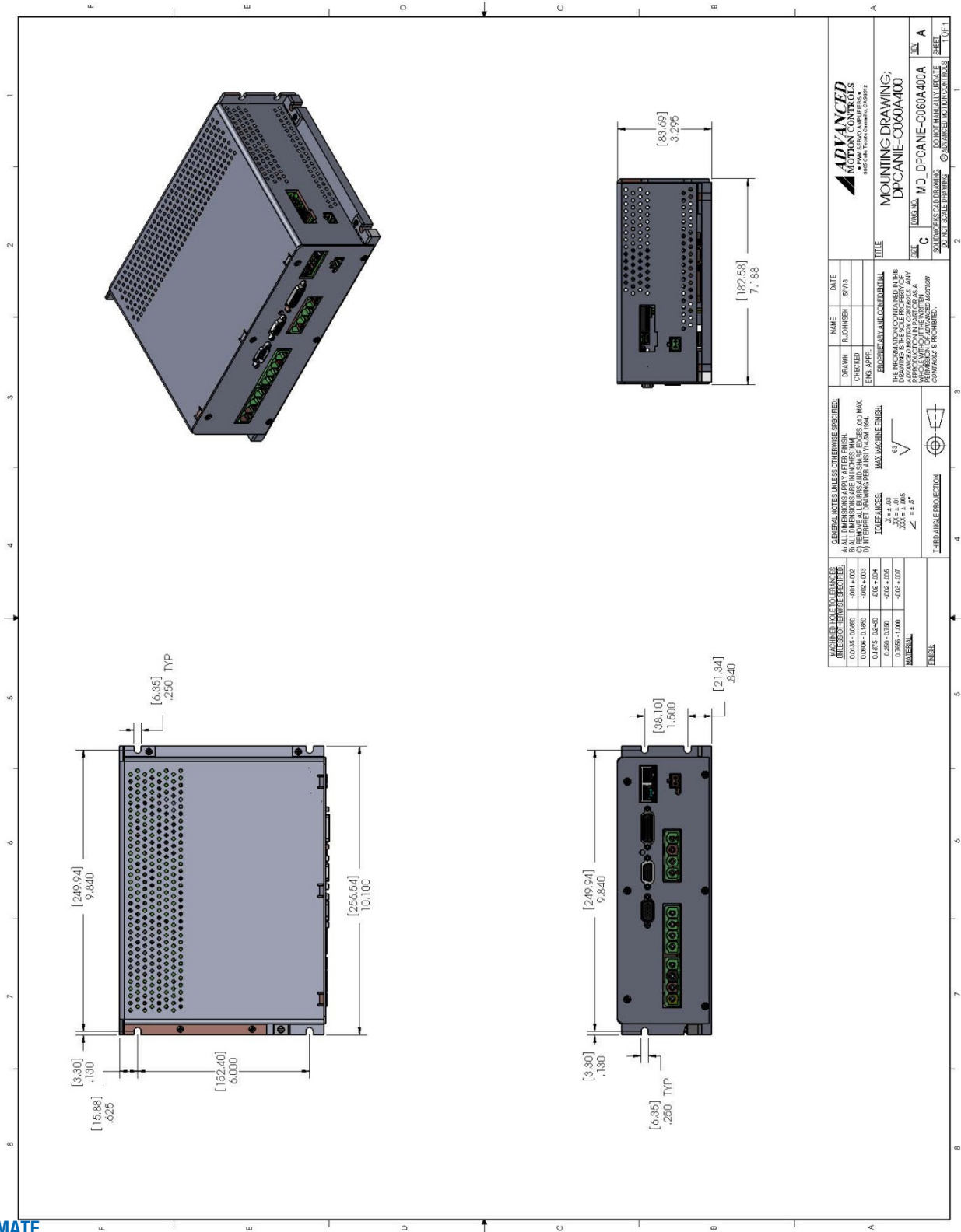
DC Power Connector

Connector Information		4-pin, 10.16 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1913523
	Included with Drive	Yes

Motor Power Connector

Connector Information		4-pin, 10.16 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1913523
	Included with Drive	Yes

MOUNTING DIMENSIONS



PART NUMBERING INFORMATION

Example: **D P C A N I E - C 0 6 0 A 4 0 0 -**

Drive Series

DP	DigiFlex Performance
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Communication

R	RS232/RS485
C	CANopen or RS232
E	EtherCAT
P	Ethernet Powerlink or TCP/IP

Command Inputs

AN	Analog (±10V) No Step & Direction
AL	Analog (±10V) Low Voltage Step & Direction (5V)
AH	Analog (±10V) High Voltage Step & Direction (24V)
NL	No Analog Low Voltage Step & Direction (5V)
NN	No Analog, No Step & Direction (Communication Interface Only)

Digital I/O

I	Isolated (24V)
T	TTL (5V) Non-Isolated

Motor Feedback

E	Incremental Encoder and/or Halls
R	Resolver
A	Absolute Sin/Cos (HiPercase & Endat)
S	Sin/Cos with Halls
U	Universal (Halls, Inc. Enc., Abs. Enc., 1Vp-p Sin/Cos Enc.)

Customer Special

Code used to identify customer specials

Max DC Bus Voltage (V_{DC})

080	80
200	200
400	400
800	800

Power and Logic Supply

A	AC Input +24V _{DC} User Logic Supply Required
S	AC Input Single Phase Only +24V _{DC} User Logic Supply Required
B	DC Input Both Logic Supply Options (Internal or User)
L	DC Input Logic Supply Required

Peak Current (A₀ to Peak)

015	15
016	16
020	20
025	25
030	30
040	40
060	60
C060	60
C100	100

DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- ▲ Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- ▲ Integrated System I/O
- ▲ Tailored Project File
- ▲ Silkscreen Branding
- ▲ Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- ▲ Conformal Coating
- ▲ Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



→
To Motor